

Today: Synchronization

- Synchronization
 - Mutual exclusion
 - Critical sections
- Example: Too Much Milk
- Locks

• Synchronization primitives are required to ensure that only one thread executes in a critical section at a time.



Recap: Synchronization

•What kind of knowledge and mechanisms do we need to get independent processes to communicate and get a consistent view of the world (computer state)?

roommate
ome
fridge, no milk
or grocery store
k
ome, put up milk
!

•Example: Too Much Milk

Recap: Synchronization Terminology

- **Synchronization:** use of atomic operations to ensure cooperation between threads
- **Mutual Exclusion:** ensure that only one thread does a particular activity at a time and *excludes* other threads from doing it at that time
- Critical Section: piece of code that only one thread can execute at a time
- Lock: mechanism to prevent another process from doing something
 - Lock before entering a critical section, or before accessing shared data.
 - Unlock when leaving a critical section or when access to shared data is complete
 - Wait if locked

=> All synchronization involves waiting.



Too M	uch Milk: Solutio	on 1
 What are the correctne Only one person buy Someone buys milk Restrict ourselves to at Leave a note (a versi Remove note (a versi Do not buy any milk 	ss properties for this problem? s milk at a time. (safety) if you need it. (liveness) comic loads and stores as building blo on of lock) ion of unlock) if there is note (wait)	cks.
Thread A	Thread B	
if (noMilk & NoNote) {	if (noMilk & NoNote) {	
buy milk;	buy milk;	
remove note;	remove note;	
}	}	
Does this w	ork?	
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Too Much Milk: Solution 3				
Thread A	Thread B			
<pre>leave note A X: while (Note B) { do nothing; } if (noMilk){ buy milk; } remove note A;</pre>	<pre>leave note B Y: if (noNote A) { if (noMilk){ buy milk; } } remove note B;</pre>			
Does this work?				
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Is Solution 3 a good solution? It is too complicated - it was hard to convince ourselves this solution works. It is asymmetrical - thread A and B are different. Thus, adding more threads would require different code for each new thread and modifications to existing threads. A is *busy waiting* - A is consuming CPU resources despite the fact that it is not doing any useful work. => This solution relies on loads and stores being atomic.

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Hardware Support for Synchronization

Implementing high level primitives requires low-level hardware support
What we have and what we want

	Concurrent programs		
Low-level atomic operations (hardware)	load/store	interrupt disable	test&set
High-level atomic operations (software)	lock monitors	semaphore send & receive	
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Implementing Locks By Disabling Interrupts

- There are two ways the CPU scheduler gets control:
 - Internal Events: the thread does something to relinquish control (e.g., I/O).
 - **External Events:** interrupts (e.g., time slice) cause the scheduler to take control away from the running thread.
- On uniprocessors, we can prevent the scheduler from getting control as follows:
 - **Internal Events:** prevent these by not requesting any I/O operations during a critical section.
 - **External Events:** prevent these by disabling interrupts (i.e., tell the hardware to delay handling any external events until after the thread is finished with the critical section)
- Why not have the OS support Lock::Acquire() and Lock::Release as system calls?



Atomic read-modify-write Instructions

- Atomic read-modify-write instructions *atomically* read a value from memory into a register and write a new value.
 - Straightforward to implement simply by adding a new instruction on a uniprocessor.
 - On a multiprocessor, the processor issuing the instruction must also be able to *invalidate* any copies of the value the other processes may have in their cache, i.e., the multiprocessor must support some type of *cache coherence*.

Examples:

- Test&Set: (most architectures) read a value, write '1' back, return old value
- **Exchange:** (x86) swaps value between register and memory.
- Compare&Swap: (68000) read value, if value matches register value r1, exchange register r2 and value.

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Implementing Locks with Test&Set Test&Set: reads a value, writes '1' to memory, and returns the old value. class Lock { Acquire() { // if busy do nothing public: while (test&set(value) == 1); void Acquire(); void Release(); } private: Release() { int value; value = 0;} } Lock() { value = 0;} If lock is free (value = 0), test&set reads 0, sets value to 1, and returns 0. The Lock is now busy: the test in the while fails, and Acquire is complete. • If lock is busy (value = 1), test&set reads 1, sets value to 1, and returns 1. The while continues to loop until a Release executes. Computer Science CS377: Operating Systems Lecture 7, page 17







- Communication among threads is typically done through shared variables.
- Critical sections identify pieces of code that cannot be executed in parallel by multiple threads, typically code that accesses and/or modifies the values of shared variables.
- Synchronization primitives are required to ensure that only one thread executes in a critical section at a time.
 - Achieving synchronization directly with loads and stores is tricky and errorprone
 - Solution: use high-level primitives such as locks, semaphores, monitors

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