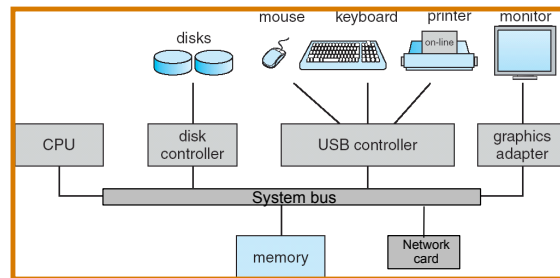


Last Class: OS and Computer Architecture



- CPU, memory, I/O devices, network card, system bus



Last Class: OS and Computer Architecture

OS Service	Hardware Support
Protection	Kernel/user mode, protected instructions, base/limit registers
Interrupts	Interrupt vectors
System calls	Trap instructions and trap vectors
I/O	Interrupts and memory mapping
Scheduling, error recovery, accounting	Timer
Synchronization	Atomic instructions
Virtual memory	Translation look-aside buffers



Today: OS Structures & Services

- More on System Calls
- Introduce the organization and components in an OS.
- **Four example OS organizations**
 - Monolithic kernel
 - Layered architecture
 - Microkernel
 - Modular



Class Exercise

- iOS 7 and iPhone 5S
 - “iPhone 5S first 64-bit smartphone, iOS 7 first 64-bit OS”
- iPhone 5S has M7 co-processor in addition to main A7 processor
 - Offloads work (primarily sensor data processing) from main CPU to co-processor
- Critique these design decisions. Benefits?



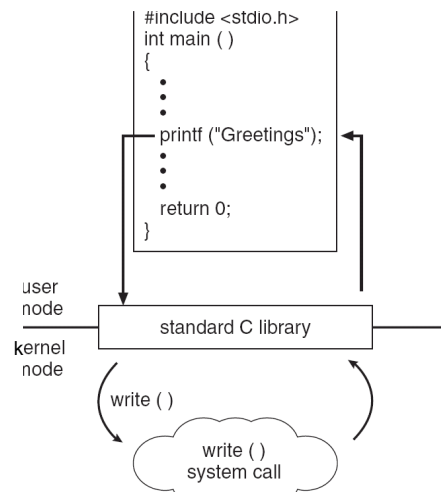
System Calls

- Programming interface to the services provided by the OS
- Typically written in a high-level language (C or C++)
- Mostly accessed by programs via a high-level **Application Program Interface (API)** rather than direct system call use
- Three most common APIs are Win32 API for Windows, POSIX API for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X), and Java API for the Java virtual machine (JVM)
- Why use APIs rather than system calls?



Standard C Library Example

- C program invoking printf() library call, which calls write() system call



Example of Standard API

- Consider the ReadFile() function in the
- Win32 API—a function for reading from a file

```
return value
  ↓
BOOL  ReadFile c (HANDLE    file,
                 LPVOID    buffer,
                 DWORD     bytes To Read,
                 LPDWORD   bytes Read,
                 LPOVERLAPPED ovl);
  ↑
function name      parameters
```

- A description of the parameters passed to ReadFile()
 - HANDLE file—the file to be read
 - LPVOID buffer—a buffer where the data will be read into and written from
 - DWORD bytesToRead—the number of bytes to be read into the buffer
 - LPDWORD bytesRead—the number of bytes read during the last read
 - LPOVERLAPPED ovl—indicates if overlapped I/O is being used

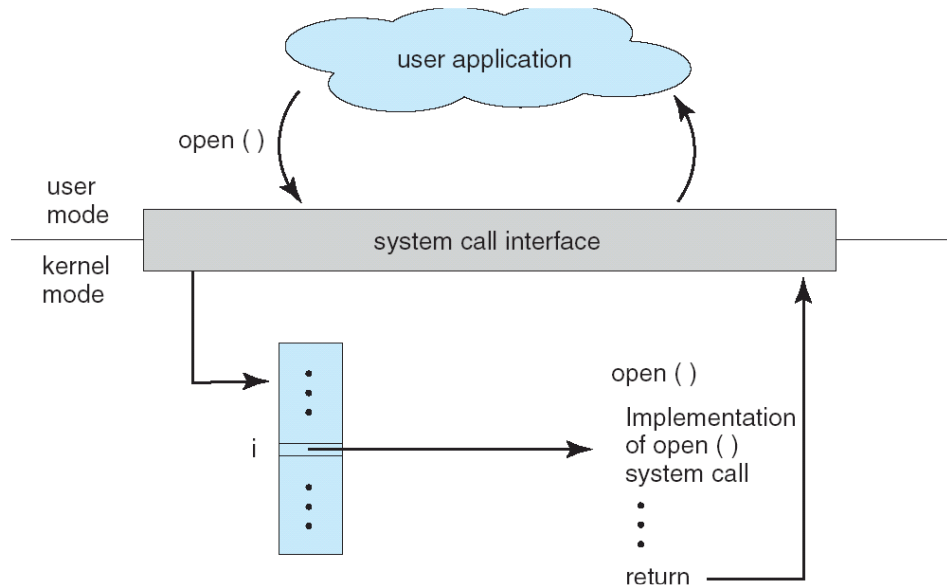


System Call Implementation

- Typically, a number associated with each system call
 - System-call interface maintains a table indexed according to these numbers
- The system call interface invokes intended system call in OS kernel and returns status of the system call and any return values
- The caller need know nothing about how the system call is implemented
 - Just needs to obey API and understand what OS will do as a result call
 - Most details of OS interface hidden from programmer by API
 - Managed by run-time support library (set of functions built into libraries included with compiler)



API – System Call – OS Relationship



System Call Parameter Passing

- Often, more information is required than simply identity of desired system call
 - Exact type and amount of information vary according to OS and call
- Three general methods used to pass parameters to the OS
 - Simplest: pass the parameters in *registers*
 - In some cases, may be more parameters than registers
 - Parameters stored in a *block*, or table, in memory, and address of block passed as a parameter in a register
 - This approach taken by Linux and Solaris
 - Parameters placed, or *pushed*, onto the *stack* by the program and *popped* off the stack by the operating system
 - Block and stack methods do not limit the number or length of parameters being passed

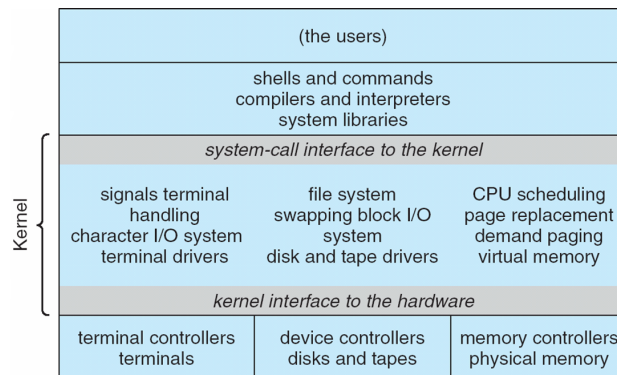


Examples of Windows and Unix System Calls

	Windows	Unix
Process Control	CreateProcess() ExitProcess() WaitForSingleObject()	fork() exit() wait()
File Manipulation	CreateFile() ReadFile() WriteFile() CloseHandle()	open() read() write() close()
Device Manipulation	SetConsoleMode() ReadConsole() WriteConsole()	ioctl() read() write()
Information Maintenance	GetCurrentProcessID() SetTimer() Sleep()	getpid() alarm() sleep()
Communication	CreatePipe() CreateFileMapping() MapViewOfFile()	pipe() shmget() mmap()
Protection	SetFileSecurity() InitializeSecurityDescriptor() SetSecurityDescriptorGroup()	chmod() umask() chown()



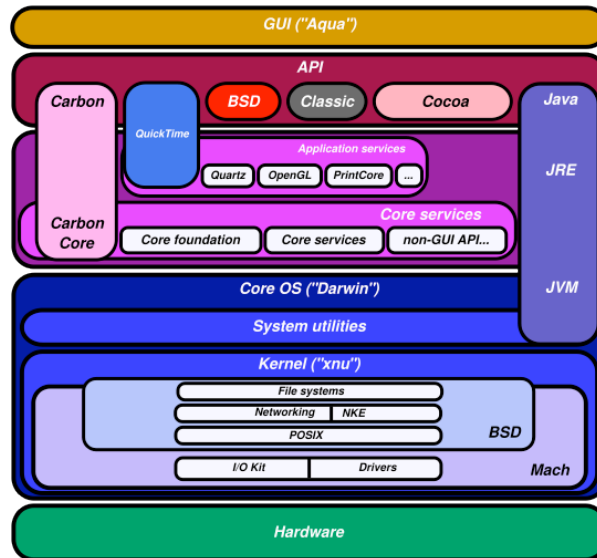
One Basic OS Structure



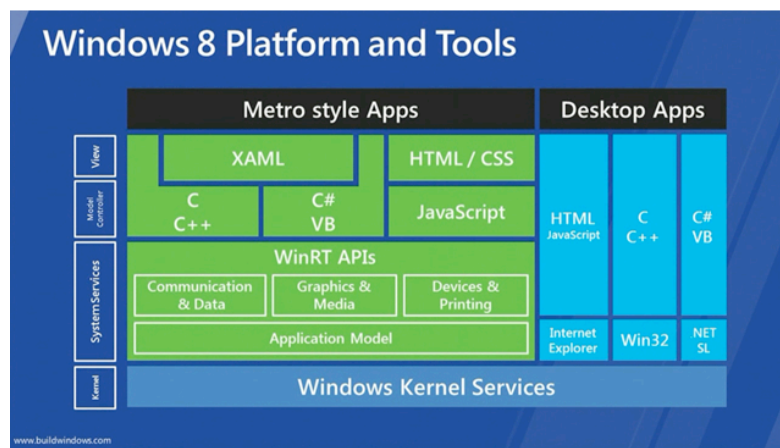
- The *kernel* is the protected part of the OS that runs in kernel mode, protecting the critical OS data structures and device registers from user programs.
- Debate about what functionality goes into the kernel (above figure: UNIX) - “monolithic kernels”



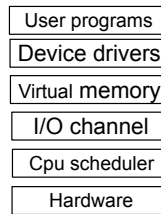
Mac OS X Architecture



Windows 8 Architecture



Layered OS design

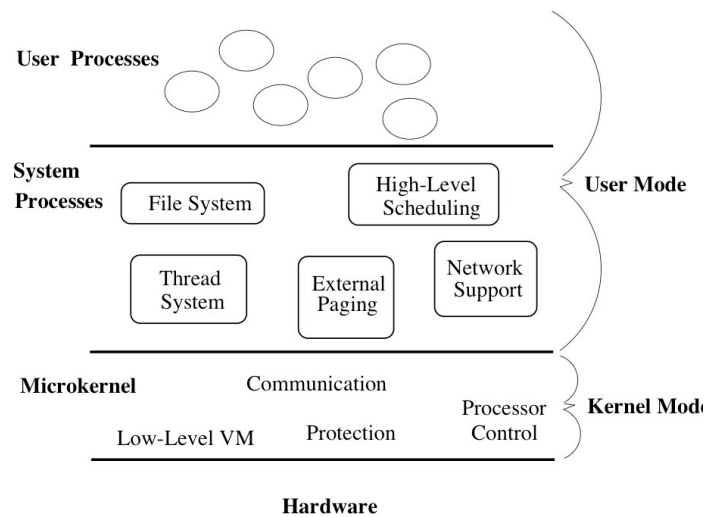


Layer N: uses layer N-1 and provides new functionality to N+1

- Advantages: modularity, simplicity, portability, ease of design/debugging
- Disadvantage - communication overhead between layers, extra copying, book-keeping, layer design



Microkernel



- Small kernel that provides communication (message passing) and other basic functionality
- other OS functionality implemented as user-space processes

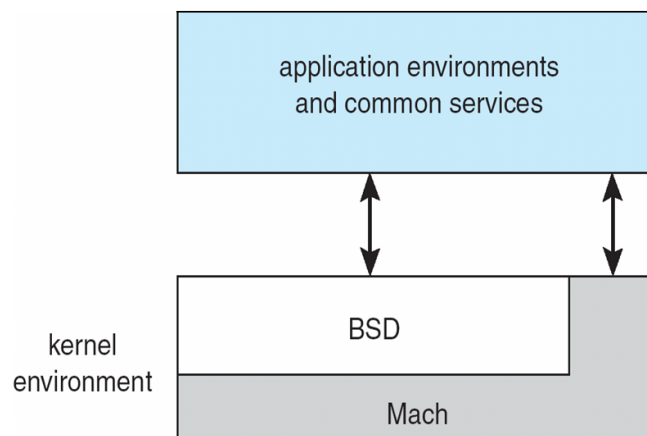


Microkernel Features

- **Goal:** to minimize what goes in the kernel (mechanism, no policy), implementing as much of the OS in User-Level processes as possible.
- **Advantages**
 - better reliability, easier extension and customization
 - mediocre performance (unfortunately)
- First Microkernel was Hydra (CMU '70). Current systems include Chorus (France) and Mach (CMU).



Mac OS X - hybrid approach



- Layered system: Mach microkernel (mem, RPC, IPC) + BSD (threads, CLI, networking, filesystem) + user-level services (GUI)

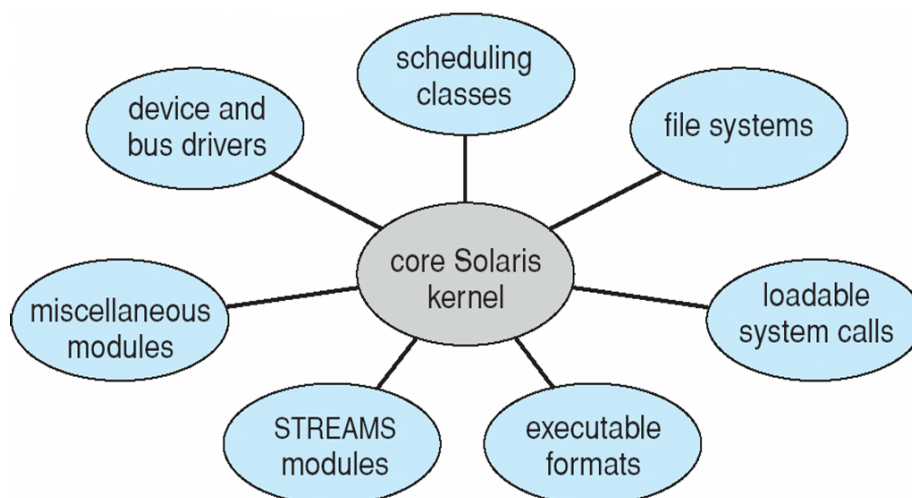


Modules

- Most modern operating systems implement kernel modules
 - Uses object-oriented approach
 - Each core component is separate
 - Each talks to the others over known interfaces
 - Each is loadable as needed within the kernel
- Overall, similar to layers but more flexible



Solaris Modular Approach



Summary

- **Big Design Issue:** How do we make the OS efficient, reliable, and extensible?
- **General OS Philosophy:** The design and implementation of an OS involves a constant tradeoff between *simplicity* and *performance*. As a general rule, strive for simplicity except when you have a strong reason to believe that you need to make a particular component complicated to achieve acceptable performance (strong reason = simulation or evaluation study)

