

Two-body central force problem

$$L = \frac{1}{2} m_1 \dot{\vec{r}}_1^2 + \frac{1}{2} m_2 \dot{\vec{r}}_2^2 - U(|\vec{r}_1 - \vec{r}_2|)$$

Reduction to one-body problem.

Change coordinates

$$\left\{ \begin{array}{l} \text{center of mass} \\ \text{relative displacement} \end{array} \right. \quad \begin{array}{l} \vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2} \\ \vec{r} = \vec{r}_1 - \vec{r}_2 \end{array}$$

$$\left. \begin{array}{l} \vec{r}_1 = \vec{R} + \vec{r}_1' \\ \vec{r}_2 = \vec{R} + \vec{r}_2' \end{array} \right\} \quad m_1 \vec{r}_1' + m_2 \vec{r}_2' = 0$$

$$L = \frac{1}{2} (m_1 + m_2) \dot{\vec{R}}^2 + \frac{1}{2} m_1 \dot{\vec{r}}_1'^2 + \frac{1}{2} m_2 \dot{\vec{r}}_2'^2 - U(r) \\ r = |\vec{r}|$$

$$\vec{r}_2' = - \frac{m_1}{m_2} \vec{r}_1'$$

$$\vec{r} = \vec{r}_1' - \vec{r}_2' = \left(1 + \frac{m_1}{m_2}\right) \vec{r}_1' = \frac{m_1 + m_2}{m_2} \vec{r}_1'$$

$$\vec{r}_1' = \frac{m_2}{m_1 + m_2} \vec{r}$$

$$\vec{r}_2' = - \frac{m_1}{m_1 + m_2} \vec{r}$$

$$L = \frac{1}{2} (m_1 + m_2) \dot{\vec{R}}^2 + \underbrace{\frac{1}{2} m_1 \frac{m_2^2}{(m_1 + m_2)^2} \dot{\vec{r}}^2 + \frac{1}{2} m_2 \frac{m_1^2}{(m_1 + m_2)^2} \dot{\vec{r}}^2}_{\frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} \dot{\vec{r}}^2} - U(r)$$

μ , reduced mass

$$\frac{1}{\mu} = \frac{1}{m_1} + \frac{1}{m_2}$$

~~not a problem~~

$$\mu \leq m_1, m_2$$

[notice that]

$$m_1 \rightarrow \infty \Rightarrow \mu \rightarrow m_2$$

$$\frac{\partial L}{\partial \vec{R}} = 0 \Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\vec{R}}} \right) = \frac{d}{dt} \left((m_1 + m_2) \dot{\vec{R}} \right) = \frac{d\vec{P}}{dt} = 0$$

$$\vec{P} = \text{const}, \quad \vec{R} = \vec{R}_0 + \vec{V}_{\text{cm}} t$$

$$L = \frac{1}{2} \mu \dot{\vec{r}}^2 - U(r) \quad \leftarrow \text{one body problem in external potential}$$

Solve for $\vec{r}$, then

$$\begin{cases} \vec{r}_1 = \vec{R} + \frac{m_2}{m_1 + m_2} \vec{r} \\ \vec{r}_2 = \vec{R} - \frac{m_1}{m_1 + m_2} \vec{r} \end{cases}$$

$$L = \frac{1}{2} m \dot{\vec{r}}^2 - U(r)$$

[$\mu \rightarrow m$ note]

Spherical symmetry $\Rightarrow \vec{L}$ conserved

or

~~BRATATAT~~

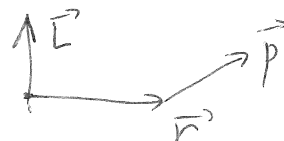
$$\vec{F} = -\vec{\nabla} U = -\left(\frac{\partial U}{\partial r}\right) \hat{r}$$

$$\vec{N} = \vec{r} \times \vec{F} = 0$$

$\Rightarrow \vec{L}$ conserved

Reduction to two dimensions

$$\vec{L} = \vec{r} \times \vec{p}$$



$$\vec{r}, \vec{p} \perp \vec{L}$$

$\vec{r}, \vec{p}$ remain in plane $\perp$ to $\vec{L}$

Choose $\hat{z}$ axis along $\vec{L} \Rightarrow \vec{r}, \vec{p}$ in xy plane

~~Polar coordinates r, θ~~

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - U(r)$$

$$\frac{\partial L}{\partial \theta} = 0 \Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = \frac{d}{dt} (mr^2 \dot{\theta}) = 0$$

$$mr^2 \dot{\theta} = l \text{ orbital angular momentum}$$

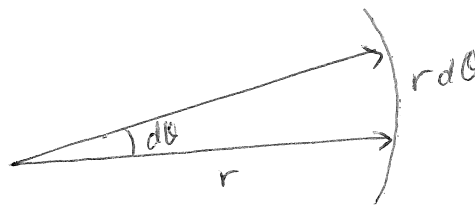
$$\dot{\theta} = \frac{l}{mr^2}$$

$$L = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} m r^2 \dot{\theta}^2 - U(r)$$

$$\frac{\partial L}{\partial \theta} = 0 \Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = \frac{d}{dt} (m r^2 \dot{\theta}) = 0$$

$m r^2 \dot{\theta} = \text{const} = l$, orbital angular momentum

~~angular momentum~~



$$dA = \frac{1}{2} r (r d\theta)$$

areal velocity $\frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta} = \frac{l}{2m} = \text{const}$

Kepler's Second Law = equal areas swept out in equal time

||| Conservation of angular momentum

$$\frac{\partial L}{\partial \dot{r}} = m\dot{r}$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) = \frac{\partial L}{\partial r}$$

$$m\ddot{r} = m r \dot{\theta}^2 - \frac{dU}{dr}$$

$$\dot{\theta} = \frac{L}{mr^2}$$

$$F = - \frac{dU}{dr}$$

$$m\ddot{r} = \frac{L^2}{mr^3} + F$$

~~the centrifugal force~~

F_c

"centrifugal force"

$$F_c = - \frac{dU_c}{dr}$$

$$U_c = \frac{L^2}{2mr^2}$$

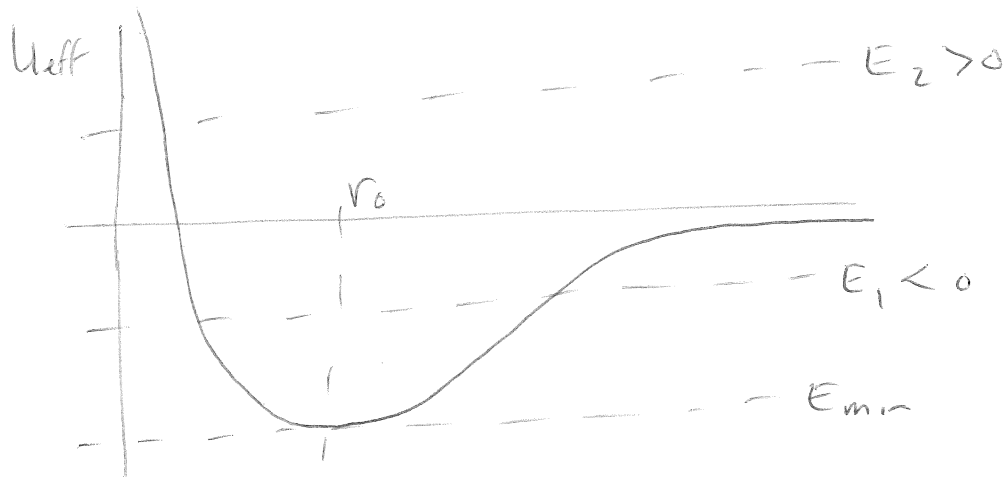
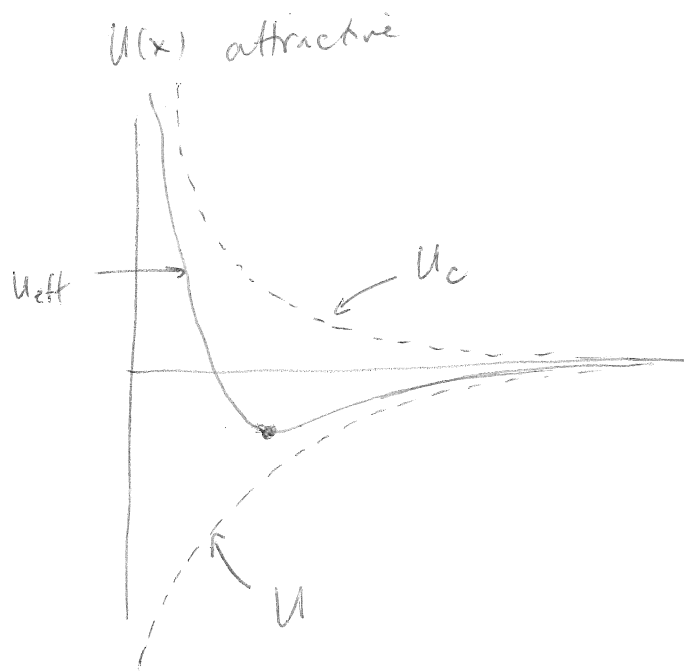
$$m\ddot{r} = - \frac{d}{dr} (U_c + U)$$

$$\underbrace{m\dot{r}\ddot{r}} = - \frac{d}{dr} (U_c + U) \frac{dr}{dt} = - \frac{d}{dt} (U_c + U)$$

$$\frac{d}{dt} \left(\frac{1}{2} m \dot{r}^2 \right)$$

$$\frac{d}{dt} \left(\frac{1}{2} m \dot{r}^2 + U + U_c \right) = 0$$

$$\frac{1}{2} m \dot{r}^2 + \underbrace{U(r) + U_c(r)}_{U_{eff}(r)} = E$$



① $E = E_{min}$

$$\frac{dU_{eff}}{dr} = 0 = \frac{d}{dr} \left(U + \frac{L^2}{2mr^2} \right)$$

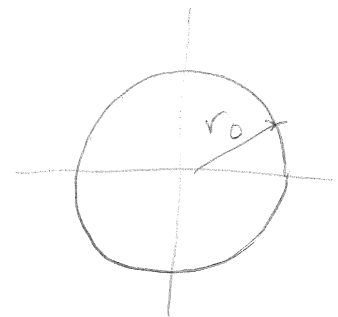
$$F_{eff} = 0 = F + \frac{L^2}{mr^3}$$

$$r = r_0 = \text{const}$$

$$\dot{\theta} = \frac{L}{mr_0^2}$$

$$\theta = \frac{L}{mr_0^2} t + \theta_0$$

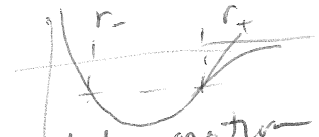
circular motion



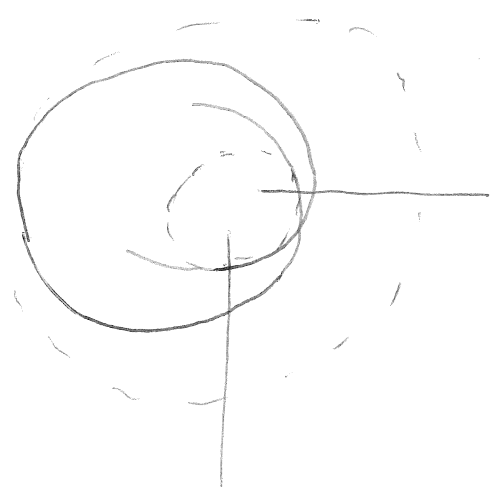
② $E = E_1 < 0$

$r_- < r < r_+$ bounded motion
 $r_{\pm}$ - apsidal distances

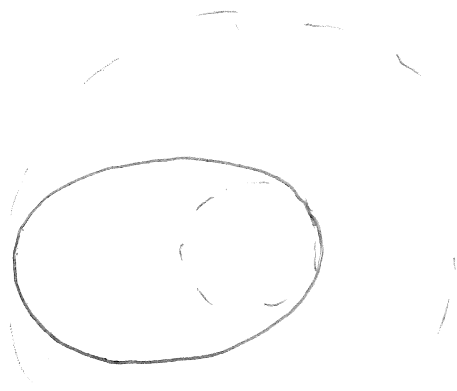
[turning points]



$T_{\text{radial}} < T_{\text{angular}}$



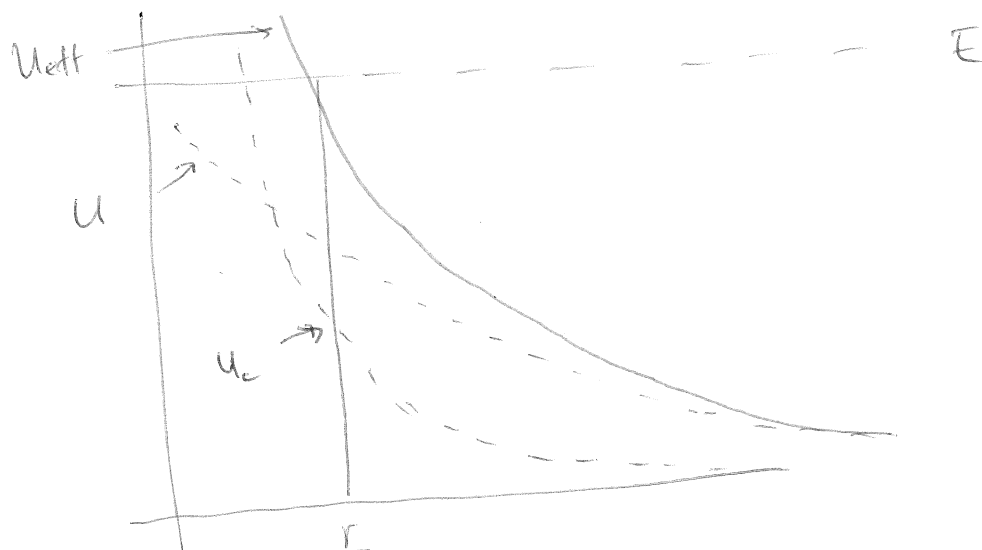
$T_{\text{radial}} > T_{\text{angular}}$
 ~~$T_{\text{radial}} = T_{\text{angular}}$~~



$T_{\text{radial}} = T_{\text{angular}}$

If T_{radial} and T_{angular} are commensurate, orbit closes.
 Bertrand's theorem: the only central forces that result in $\leftarrow$ [w/o proof]
 closed orbits are $f = -\frac{k}{r^2}$ and $f = -kr$ ($V = -\frac{k}{r}$ and $V = \frac{kr^2}{2}$)
 Proof: Goldstein

$U(x)$ repulsive



$E > 0$
 $r > r_0$ motion always unbounded



$U(x) = 0$



[looks like repulsion from radial part of wave]
 [complicated way to view straight line motion]



→ [Quantitative analysis] ↓

L9

~~Radial solution~~

$r(t), \theta(t)$: formal solution

$$\frac{1}{2} m \dot{r}^2 + \frac{l^2}{2mr^2} + U(r) = E$$

$$\frac{dr}{dt} = \sqrt{\frac{2}{m} \left(E - U(r) - \frac{l^2}{2mr^2} \right)}$$

$$dt = \frac{dr}{\sqrt{\frac{2}{m} \left(E - U(r) - \frac{l^2}{2mr^2} \right)}}$$

$$t(r) = \int_{r_0}^r \frac{dr}{\sqrt{\frac{2}{m} \left(E - U(r) - \frac{l^2}{2mr^2} \right)}}$$

[analytic or numerical solution]

~~Angular solution~~

$$\tau_{\text{radial}} = 2 \int_{r_-}^{r_+} \frac{dr}{\sqrt{\frac{2}{m} \left(E - U(r) - \frac{l^2}{2mr^2} \right)}}$$

Invert to get $r(t)$

[nontrivial]

$$\frac{d\theta}{dt} = \frac{l}{mr^2(t)}$$

$$\theta(t) - \theta_0 = \int_0^t \frac{l}{m r^2(t)} dt$$

[everything reduced to]
quadrature

Inverse square:

$$V = -\frac{k}{r}$$

$$k = GMm \text{ gravity}$$

$$= e^2 \text{ hydrogen atom}$$

$$\theta - \theta' = - \int \frac{du}{\sqrt{\frac{2mE}{l^2} + \frac{2mk}{l^2} u - u^2}}$$

$$\text{arc cos} \left[\frac{\frac{l^2 u}{mk} - 1}{\sqrt{1 + \frac{2El^2}{mk^2}}} \right]$$

$$\frac{1}{r} = u = \frac{mk}{l^2} \left[1 + \sqrt{1 + \frac{2El^2}{mk^2}} \cos(\theta - \theta') \right]$$

Two parameters (E, l)

$$\frac{1}{r} = C [1 + e \cos(\theta - \theta')]$$

↑
eccentricity

Conic section

[take $e > 0$, if $e < 0$,
shift θ' by π] $e = 0$ circle

$$E = -\frac{mk^2}{2l^2}$$

 $0 < e < 1$ ellipse

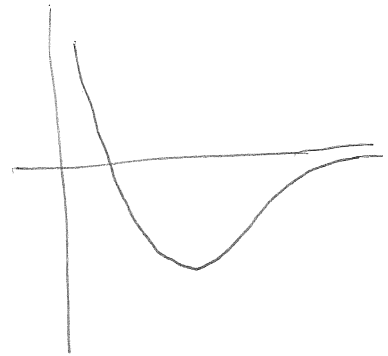
$$E < 0$$

 $e = 1$ parabola

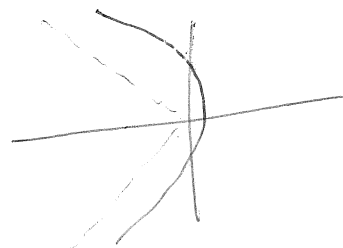
$$E = 0$$

 $e > 1$ hyperbola

$$E > 0$$

Kepler's 1st law

$$r \rightarrow 0 \Rightarrow \cos \theta = -\frac{1}{e}$$



Differential equation for the orbit $r(\theta)$

$$\frac{d\theta}{dt} = \frac{l}{mr^2}$$

$$m \frac{d^2 r}{dt^2} - \frac{l^2}{mr^3} = F(r)$$

$$\frac{d}{dt} = \frac{d\theta}{dt} \frac{d}{d\theta} = \frac{l}{mr^2} \frac{d}{d\theta}$$

$$\begin{cases} r = \frac{1}{u} \\ \frac{dr}{dt} = -\frac{1}{u^2} \frac{du}{dt} = -\frac{1}{u^2} \frac{l}{mr^2} \frac{du}{d\theta} = -\frac{l}{m} \frac{du}{d\theta} \\ \frac{d^2 r}{dt^2} = -\frac{l}{m} \frac{d}{dt} \left(\frac{du}{d\theta} \right) = -\frac{l}{m} \frac{l}{mr^2} \frac{d}{d\theta} \left(\frac{du}{d\theta} \right) = -\frac{l^2}{m^2} u^2 \frac{d^2 u}{d\theta^2} \end{cases}$$

$$-\frac{l^2}{m} u^2 \frac{d^2 u}{d\theta^2} - \frac{l^2}{m} u^3 = F\left(\frac{1}{u}\right)$$

$$\boxed{\frac{d^2 u}{d\theta^2} + u = -\frac{m}{l^2 u^2} F\left(\frac{1}{u}\right)}$$

Given $r(\theta)$, this gives $F(r)$.

$$F = -\frac{k}{r^2} = -ku^2$$

$$\frac{d^2 u}{d\theta^2} + u = \frac{mk}{l^2}$$

~~Homogeneous~~ Homogeneous: $u = C \cos(\theta - \theta')$

Specific: $u = \frac{mk}{l^2}$

General: $u = \frac{mk}{l^2} [1 + e \cos(\theta - \theta')] = \frac{1}{r}$

Ellipse: $0 < e < 1$

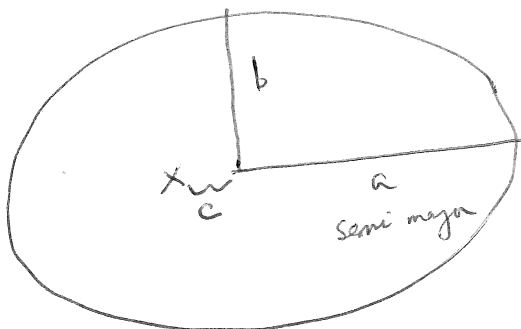
$$\frac{1}{r} = B(1 + e \cos \theta)$$

2 parameters: B, e

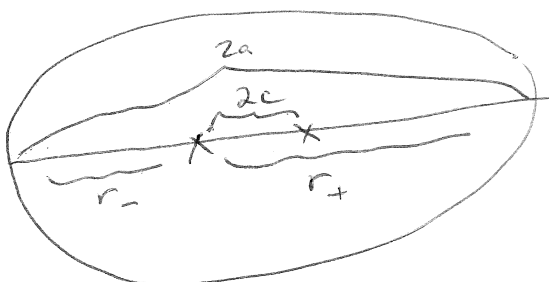
$\theta = 0$ $\frac{1}{r_-} = B(1 + e)$

$\theta = \pi$ $\frac{1}{r_+} = B(1 - e)$

$$\frac{r_+}{r_-} = \frac{1+e}{1-e} \Rightarrow e = \frac{r_+ - r_-}{r_+ + r_-}$$



$$e \equiv \frac{c}{a} \quad a^2 = b^2 + c^2$$



$$e = \frac{2c}{2a} = \frac{r_+ - r_-}{r_+ + r_-}$$

Other possible topics

1. Runge Lenz vector

2. Precession of orbit due to GR perturbation
($\frac{1}{r^4}$)

3. Scattering : cross section
differential cross section

Rutherford

4. Analysis of scattering in diff. frames, σ in lab.

$$B = \frac{1}{r_+ (1+e)} = \frac{r_+ + r_-}{2r_+ r_-}$$

$$\frac{1}{r} = \frac{r_+ + r_-}{2r_+ r_-} \left[1 + \frac{r_+ - r_-}{r_+ + r_-} \cos \theta \right]$$

2 parameters: r_+, r_-

How are r_+, r_- related to E, l ?

$$E = \frac{1}{2} m \dot{r}^2 + \frac{l^2}{2mr^2} - \frac{k}{r}$$

$\dot{r} = 0$ at turning points

$$E = \frac{l^2}{2mr^2} - \frac{k}{r}$$

$$r^2 + \frac{k}{E} r - \frac{l^2}{2mE} = 0$$

$$(r - r_+)(r - r_-) = 0$$

$$r^2 - (r_+ + r_-)r + r_+ r_- = 0$$

$$r_{\pm} = -\frac{k}{2E} \pm \frac{1}{2} \sqrt{\frac{k^2}{E^2} + \frac{2l^2}{mE}}$$

$$B = \frac{r_+ + r_-}{2r_+ r_-} = \frac{\left(-\frac{k}{E}\right)}{\left(-\frac{l^2}{mE}\right)} = \frac{mk}{l^2}$$

$$e = \frac{r_+ - r_-}{r_+ + r_-} = \frac{\sqrt{\frac{k^2}{E^2} + \frac{2l^2}{mE}}}{-\frac{k}{E}} = \sqrt{1 + \frac{2El^2}{mk^2}}$$

Semi major axis: $a = \frac{r_+ + r_-}{2} = -\frac{k}{2E}$, $E = -\frac{k}{2a}$ [virial]

$$b = \sqrt{a^2 - c^2} = \sqrt{a^2 - a^2 e^2} = a \sqrt{1 - e^2} = \frac{-k}{2E} \sqrt{\frac{-2El^2}{mk^2}}$$

$$\text{Area of ellipse} = \pi ab = \frac{\pi k^2}{4E^2} \sqrt{\frac{-2El^2}{mk^2}}$$

Period of motion

$$\frac{dA}{dt} = 2 \frac{L}{m}$$

$$A = \frac{L}{2m} T$$

$$T = \frac{2m A}{L} = \pi k \sqrt{\frac{m}{2}} \sqrt{\frac{1}{-E^3}}$$

$$T^2 = \frac{\pi^2 k^2 m}{-2 E^3} = \frac{4\pi^2 m}{k} a^3$$

$$T^2 = \frac{4\pi^2 m}{k} a^3$$

Kepler's 3rd law

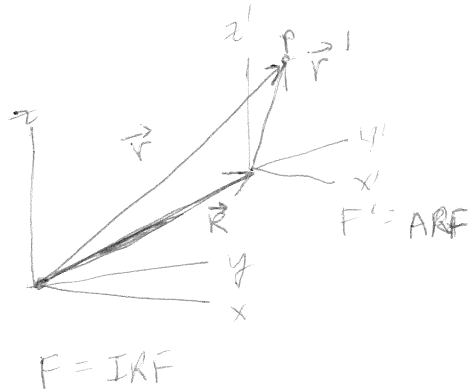
Velocities

$$E = \frac{1}{2} m v^2 = \frac{k}{r} = - \frac{k}{(r_+ + r_-)}$$

At perihelion, aphelion

$$\frac{1}{2} m v_{\pm}^2 = \frac{k}{r_{\pm}} - \frac{k}{(r_+ + r_-)}$$

Non inertial (accelerating) reference frames



$$\vec{F}' = \vec{F} - \vec{R}$$

$$\vec{v}' = \vec{v} - \vec{v}_R$$

$$\vec{a}' = \vec{a} - \vec{a}_R$$

$$F: \quad m\vec{a} = \vec{F}$$

~~inertial frame~~

$$m(\vec{a}' + \vec{a}_R) = \vec{F}$$

$$\begin{aligned} m\vec{a}' &= \vec{F} - m\vec{a}_R \\ &= \vec{F} + \vec{F}_{\text{pseudo}} \end{aligned}$$

$$\vec{F}_{\text{pseudo}} = -m\vec{a}_R$$

elevator



$$N - mg = ma_R$$

$$N = m(g + a_R)$$

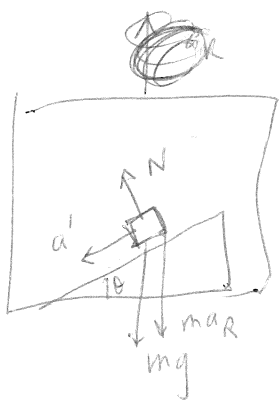
ARF



~~inertial frame~~

$$N - mg - ma_R = 0$$

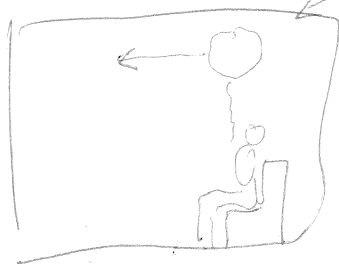
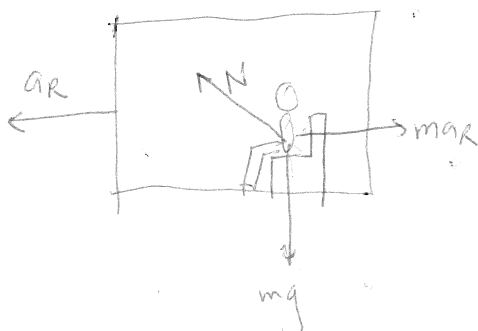
$$N = m(g + a_R)$$



ARF

$$N = m(g + a_R) \cos \theta$$

$$m(g + a_R) \sin \theta = ma'$$



[think what the helium balloon goes?]