

A Lorentz boost in the x-direction

$$ct' = \gamma(ct - \beta x)$$

$$\beta = \frac{v}{c}$$

$$x' = \gamma(x - \beta \cdot ct)$$

$$\gamma = \frac{1}{\sqrt{1-\beta^2}}$$

$$y' = y$$

$$z' = z$$

can be expressed in matrix form

$$\begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

This suggests we define a four-vector

$$X^\mu = \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

$$\text{where } \begin{cases} x^0 = ct \\ x^1 = x \\ x^2 = y \\ x^3 = z \end{cases}$$

[Greek index
 $\mu = 0, 1, 2, 3$]

which transforms under a general Lorentz transformation as

$$\begin{pmatrix} x^{0'} \\ x^{1'} \\ x^{2'} \\ x^{3'} \end{pmatrix} = \begin{pmatrix} \Lambda^0_0 & \Lambda^0_1 & \Lambda^0_2 & \Lambda^0_3 \\ \Lambda^1_0 & \Lambda^1_1 & \Lambda^1_2 & \Lambda^1_3 \\ \Lambda^2_0 & \Lambda^2_1 & \Lambda^2_2 & \Lambda^2_3 \\ \Lambda^3_0 & \Lambda^3_1 & \Lambda^3_2 & \Lambda^3_3 \end{pmatrix} \begin{pmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

Λ = Lorentz transformation matrix

This can be written more compactly in index notation

$$x^{\mu'} = \sum_{\nu=0}^3 \Lambda^{\mu'}_{\nu} x^{\nu} \quad \text{where } \Lambda^{\mu'}_{\nu} = \text{matrix element of } \Lambda$$

(row) $\nwarrow$
 $\swarrow$ (column)

($\mu=0, 1, 2, 3$)

Def: A fourvector is any object $A^{\mu} = \begin{pmatrix} A^0 \\ A^1 \\ A^2 \\ A^3 \end{pmatrix}$

that transforms as $A^{\mu'} = \sum_{\nu=0}^3 \Lambda^{\mu'}_{\nu} A^{\nu}$

under a Lorentz transformation.

examples

$$x^{\mu} = \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

$\leftarrow$ all components have same units

wave four-vector

$$k^{\mu} = \begin{pmatrix} k^0 \\ k^1 \\ k^2 \\ k^3 \end{pmatrix} = \begin{pmatrix} \frac{\omega}{c} \\ k_x \\ k_y \\ k_z \end{pmatrix}$$

$\leftarrow$ all components have same units

A Lorentz transformation matrix Λ must obey

$$\Lambda^T \eta \Lambda = \eta$$

where

$$\eta = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \text{Minkowski metric}$$

Lorentz transformations include boosts and rotations

e.g.

Boost in x-direction

$$\Lambda = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Rotation in xy-plane

$$\Lambda = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta & \sin\theta & 0 \\ 0 & -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & R \end{pmatrix}$$

[ex. show these obey $\Lambda^T \eta \Lambda = \eta$]

"The views of space and time which I wish to lay before you have sprung from the soil of experimental physics, and therein lies their strength. They are radical. Henceforth space by itself, and time by itself, are doomed to fade away into mere shadows, and only a kind of union of the two will preserve an independent reality.

H. Minkowski, "Space and Time," 1908

Def: Lorentz scalar = a quantity invariant under Lorentz transformations

e.g. scalar product of two 4-vectors

$$\sum_{\mu=0}^3 \sum_{\nu=0}^3 A^{\mu} \eta_{\mu\nu} B^{\nu}$$

$$= A^0 \underbrace{\eta_{00}}_{-1} B^0 + A^0 \underbrace{\eta_{01}}_0 B^1 + \dots + A^1 \underbrace{\eta_{11}}_1 B^1 + \dots$$

$$= -A^0 B^0 + \underbrace{A^1 B^1 + A^2 B^2 + A^3 B^3}_{\vec{A} \cdot \vec{B}}$$

Example

$$\sum \sum k^{\mu} \eta_{\mu\nu} k^{\nu} = -\left(\frac{\omega}{c}\right)\left(\frac{\omega}{c}\right) + \vec{k} \cdot \vec{k} = -\frac{1}{c^2}(\underbrace{\omega^2 - c^2 k^2}_{=0})$$

$$\sum \sum k^{\mu} \eta_{\mu\nu} x^{\nu} = -\left(\frac{\omega}{c}\right)(ct) + \vec{k} \cdot \vec{x} = \underbrace{k \cdot x}_{\text{phase of travelling wave}} + \omega t$$

invariant = nodes are nodes
in any frame

Prove that scalar product is invariant (similar to earlier proof)

$$\sum \sum A^{\mu'} \eta_{\mu\nu} B^{\nu'} = \underbrace{(A^0 A^1 A^2 A^3)}_{(A^0 A^1 A^2 A^3) \Lambda^T} \eta \underbrace{\begin{pmatrix} B^0 \\ B^1 \\ B^2 \\ B^3 \end{pmatrix}}_{\Lambda \begin{pmatrix} B^0 \\ B^1 \\ B^2 \\ B^3 \end{pmatrix}}$$

$$= (A^0 A^1 A^2 A^3) \underbrace{\Lambda^T \eta \Lambda}_{\eta} \begin{pmatrix} B^0 \\ B^1 \\ B^2 \\ B^3 \end{pmatrix}$$

$$= \sum \sum A^{\mu} \eta_{\mu\nu} B^{\nu}$$

Einstein's

Principle of relativity

(Lorentz)

All the laws of physics are invariant under boosts

- ie
- Eqs of physics have the same form in reference frames related by Lorentz transformations.

They must be expressed in terms of quantities covariant under Lorentz transformations

Lorentz-scalar = Lorentz scalar

4-vector = 4-vector

tensor = tensor

eg wave equation

$$-\frac{1}{c^2} \frac{\partial^2 A}{\partial t^2} + \frac{\partial^2 A}{\partial x^2} + \frac{\partial^2 A}{\partial y^2} + \frac{\partial^2 A}{\partial z^2} = 0 \quad (\text{invariant under rotations})$$

Although not invariant under Galilean boosts, it is invariant under Lorentz boosts (see 3rd class)

Proof: Define 4-gradient $\partial^\mu = \begin{cases} -\frac{1}{c} \frac{\partial}{\partial t} & \mu = 0 \\ \frac{\partial}{\partial x^i} & \mu = 1, 2, 3 \end{cases}$

[minus sign necessary so that ∂^μ txs as 4-vector]

This transforms as a 4-vector

$$\text{wave eqn} \Rightarrow (-\partial^0 \partial_0 + \partial^1 \partial_1 + \partial^2 \partial_2 + \partial^3 \partial_3) A = 0$$

$$\left(\sum_{\mu, \nu=0}^3 \partial^\mu \eta_{\mu\nu} \partial^\nu \right) A = 0$$

Lorentz scalar [called d'Alembertian]

→ invariant under Lorentz txs

just talk about this

probably skip

NOT DONE IN
CLASS

Why " $\partial^0 = -\partial_0$?

$$x^{\mu'} = \Lambda^{\mu'}_{\nu} x^{\nu}$$

$$\Lambda^{\mu'}_{\nu} \eta^{\nu\lambda} \frac{\partial A}{\partial x^{\lambda}} = \Lambda^{\mu'}_{\nu} \eta^{\nu\lambda} \frac{\partial A}{\partial x^{\kappa}} \frac{\partial x^{\kappa}}{\partial x^{\lambda}}$$

$$= \underbrace{\Lambda^{\mu'}_{\nu} \eta^{\nu\lambda} \Lambda^{\kappa}_{\lambda}}_{\eta^{\mu'\kappa}} \frac{\partial A}{\partial x^{\kappa}}$$

$$\therefore \Lambda^{\mu'}_{\nu} (\eta^{\nu\lambda} \partial_{\lambda} A) = \eta^{\mu'\kappa} (\partial_{\kappa} A)'$$

$$\therefore \Lambda^{\mu'}_{\nu} \partial^{\nu} A = \partial^{\mu'} A'$$

ie ∂^{μ} is a 4-vector

4-gradient $\frac{\partial \psi}{\partial x^\mu} = \begin{pmatrix} \frac{\partial \psi}{\partial x^0} \\ \frac{\partial \psi}{\partial x^1} \\ \frac{\partial \psi}{\partial x^2} \\ \frac{\partial \psi}{\partial x^3} \end{pmatrix} = \begin{pmatrix} \frac{1}{c} \frac{\partial \psi}{\partial t} \\ \vec{\nabla} \psi \end{pmatrix}$

NOT
DONE

V2

NOT DONE

Exercise:

Show that

$\frac{\partial \psi}{\partial x^\mu}$ does not transform as a 4-vector

but $\partial^\mu \psi \equiv \eta^{\mu\nu} \frac{\partial \psi}{\partial x^\nu}$ does.

$\eta^{\mu\nu} = \text{inverse of } \eta_{\mu\nu}$

$$\eta^{\mu\nu} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

$$\partial^\mu \psi = \begin{pmatrix} -1 & 0 \\ 0 & \mathbb{I} \end{pmatrix} \begin{pmatrix} -\frac{1}{c} \frac{\partial \psi}{\partial t} \\ \vec{\nabla} \psi \end{pmatrix} = \begin{pmatrix} -\frac{1}{c} \frac{\partial \psi}{\partial t} \\ \vec{\nabla} \psi \end{pmatrix}$$

invariant $\eta_{\mu\nu} \partial^\mu \partial^\nu \psi = 0$

$$= -\frac{1}{c^2} \frac{\partial^2 \psi}{\partial t^2} + \nabla^2 \psi = 0,$$

$$\frac{\partial^2 \psi}{\partial t^2} - c^2 \nabla^2 \psi = 0$$

wave eqn

~~Eraser~~

$$t' = \gamma t - \gamma \beta x$$
$$x' = -\gamma \beta t + \gamma x$$

NOT
DONE

$$t = \gamma t' + \gamma \beta x'$$
$$x = \gamma \beta t' + \gamma x'$$

$$\frac{\partial \psi}{\partial t'} = \gamma \frac{\partial \psi}{\partial t} + \gamma \beta \frac{\partial \psi}{\partial x}$$

$$\frac{\partial \psi}{\partial x'} = \gamma \beta \frac{\partial \psi}{\partial t} + \gamma \frac{\partial \psi}{\partial x}$$

$$\left(-\frac{\partial \psi}{\partial t'} \right) = \gamma \left(-\frac{\partial \psi}{\partial t} \right) - \gamma \beta \left(\frac{\partial \psi}{\partial x} \right)$$

$$\left(+\frac{\partial \psi}{\partial x'} \right) = -\gamma \beta \left(-\frac{\partial \psi}{\partial t} \right) + \gamma \left(\frac{\partial \psi}{\partial x} \right)$$

$$A_0 \begin{pmatrix} -\frac{\partial \psi}{\partial t'} \\ \frac{\partial \psi}{\partial x'} \end{pmatrix} \text{ transforms as } \begin{pmatrix} t' \\ x' \end{pmatrix}$$

Let two events A + B have spacetime coordinates $x_A^\mu + x_B^\mu$

Let $\Delta x^\mu = x_B^\mu - x_A^\mu = \begin{pmatrix} c\Delta t \\ \Delta x \\ \Delta y \\ \Delta z \end{pmatrix}$ be the spacetime separation between events

Δx^μ is a 4-vector

Define the spacetime interval Δs^2 between A and B as

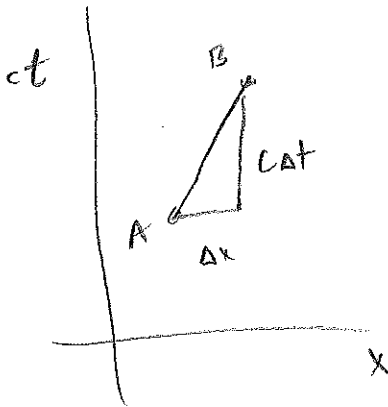
$$\Delta s^2 = \sum \sum \Delta x^\mu \eta_{\mu\nu} \Delta x^\nu = -(c\Delta t)^2 + (\Delta x)^2 + (\Delta y)^2 + (\Delta z)^2$$

Since Δs^2 is a Lorentz scalar (same in all IFFs)

we may evaluate it in any convenient frame

Given two events A & B, suppose it is possible to travel from A to B at constant velocity $\vec{v}$ ($< c$).

Then $\Delta \vec{x} = \vec{v} \Delta t$.



Spacetime interval between A & B is

$$\begin{aligned}\Delta s^2 &= -(c \Delta t)^2 + (\Delta \vec{x})^2 \\ &= -(c \Delta t)^2 + (\vec{v} \Delta t)^2 \\ &= -c^2 (\Delta t)^2 \left(1 - \frac{v^2}{c^2}\right) \\ &= -\frac{c^2 (\Delta t)^2}{\gamma^2}\end{aligned}$$

The proper time between events $\Delta \tau$ is the time between them in a frame (if one exists) in which they occur at the same place.
Evaluate Δs^2 in the frame

$$\Delta s^2 = -(c \Delta \tau)^2 + 0$$

Since Δs^2 is invariant $\Rightarrow -c^2 (\Delta \tau)^2 = -\frac{c^2}{\gamma^2} (\Delta t)^2$

$$\Rightarrow \Delta t = \gamma \Delta \tau \quad (\text{time dilation})$$

Proper time between events is less than the time between them in any other frame (since $\gamma \geq 1$)