

# **Algorithms for GIS:**

Computing visibility on terrains

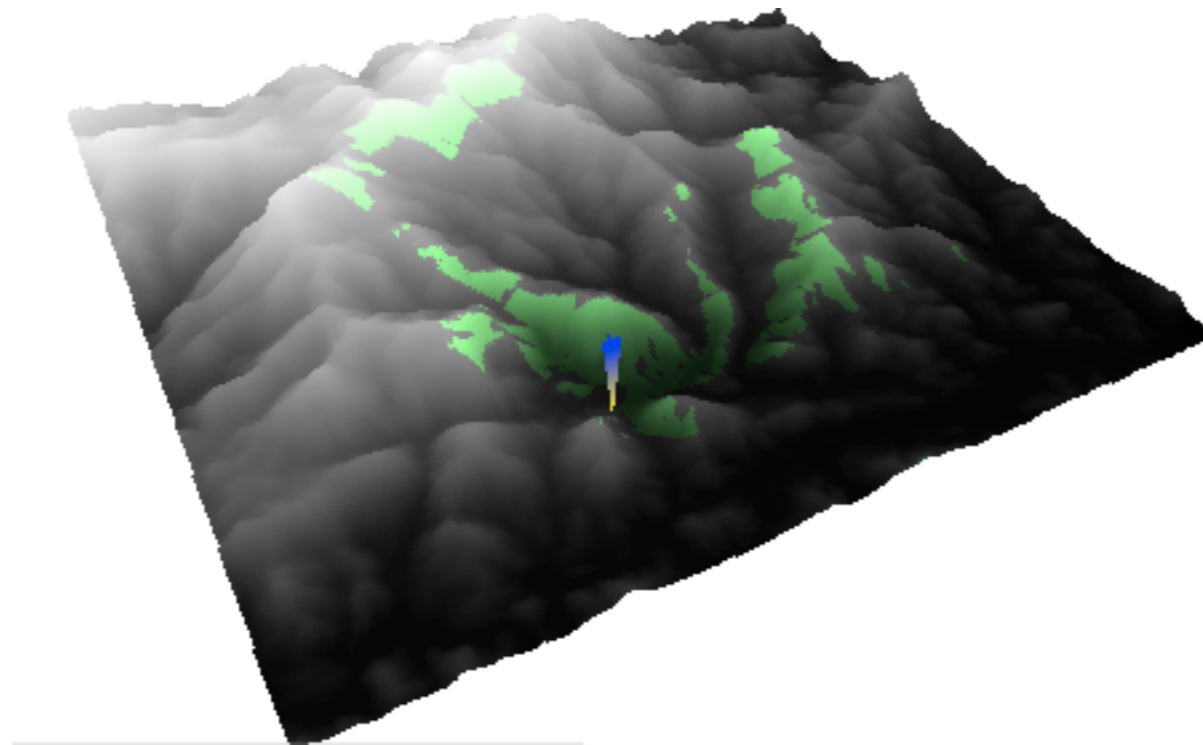
# Visibility on terrains

- Are two points (on a terrain) visible to each other?
- What can one see from a given point (on a terrain)?
- How much does the visible area increase if we stand on a 10ft ladder?
- What is the point with largest visibility?
- What is the point with lowest visibility?
- How to place an ugly pipe in a scenic area?
- How to place a scenic highway?
- What is the cumulative visible area from these set of cell towers?
- Find a set of tower locations to cover the terrain
- ...

# Visibility on terrains

## Problem:

- Terrain  $T$  + viewpoint  $v$
- Compute the **viewshed** of  $v$ : the set of points in  $T$  visible from  $v$



Sierra Nevada, 30m resolution

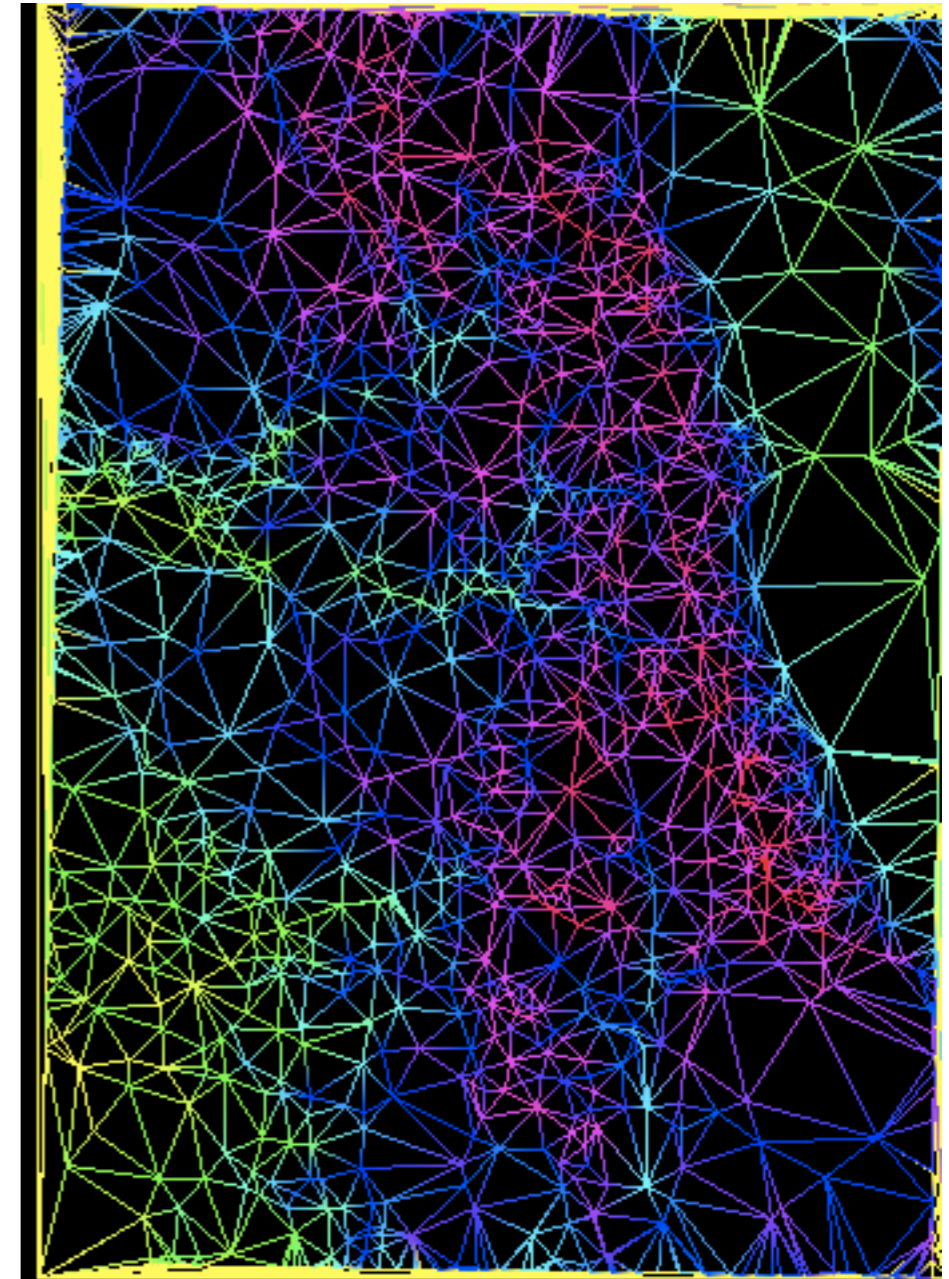
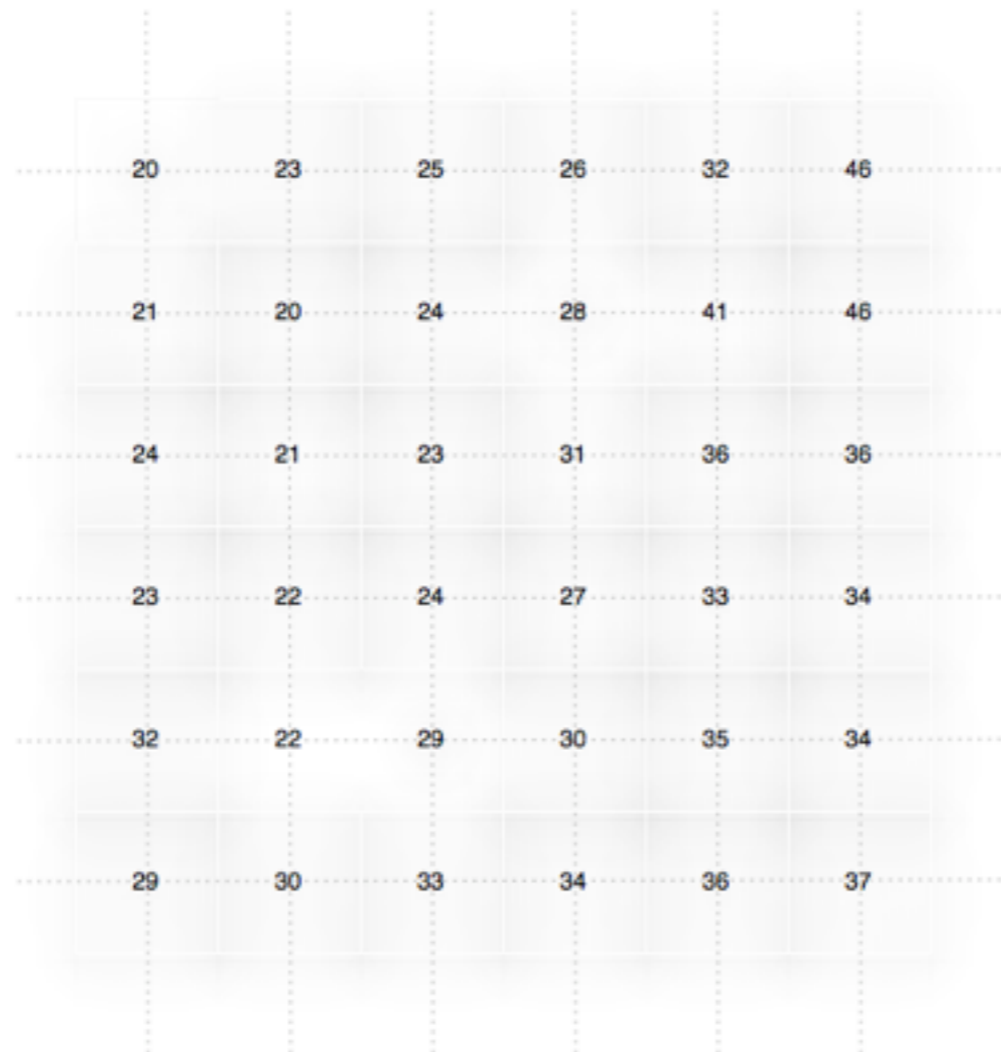
# Visibility on terrains

Input: terrain model (DEM = digital elevation model)

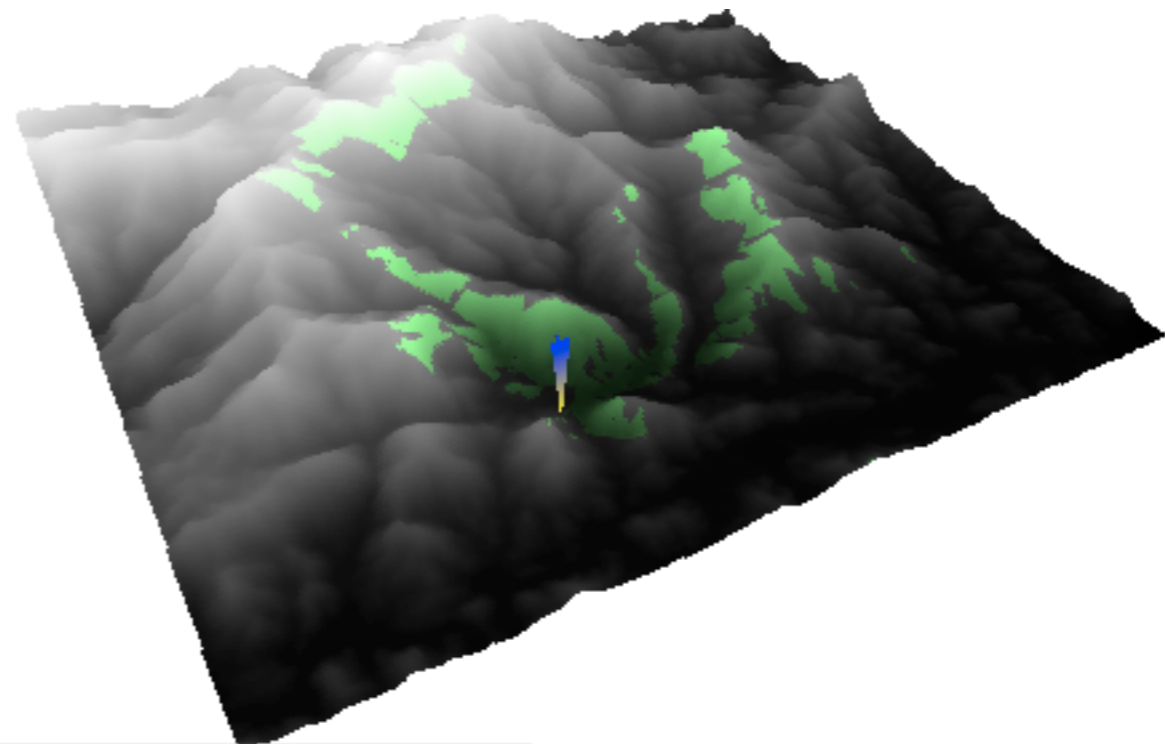
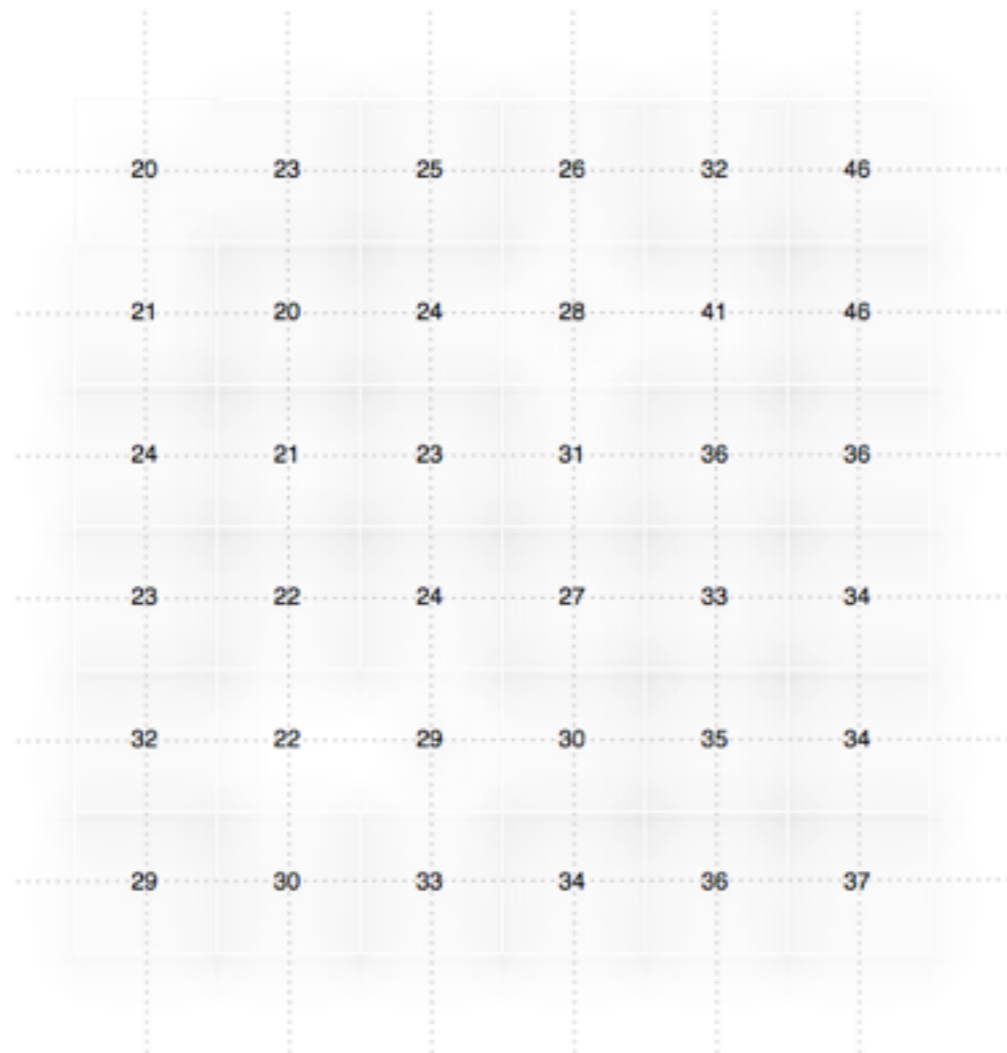
- grid
- TIN (triangulation)

Output: viewshed model

- grid elevation model ==> grid viewshed
- TIN elevation model ==> TIN viewshed

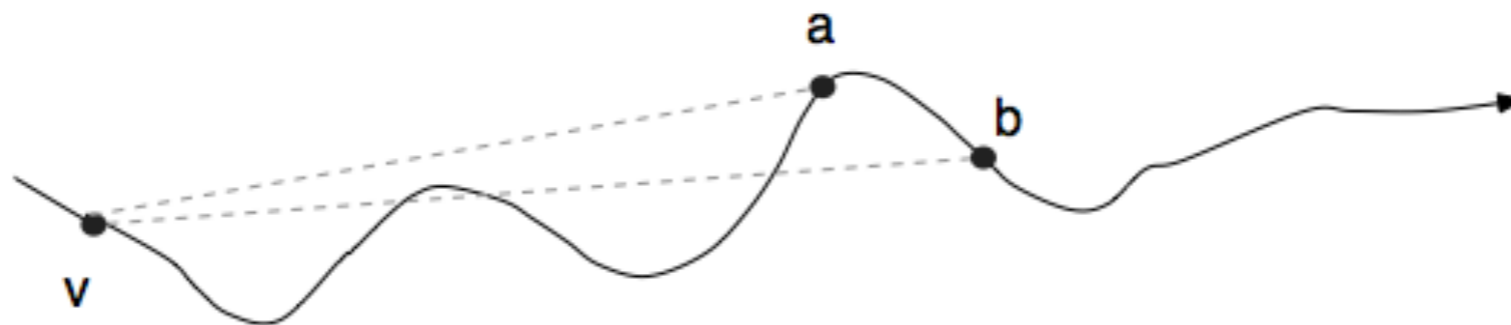
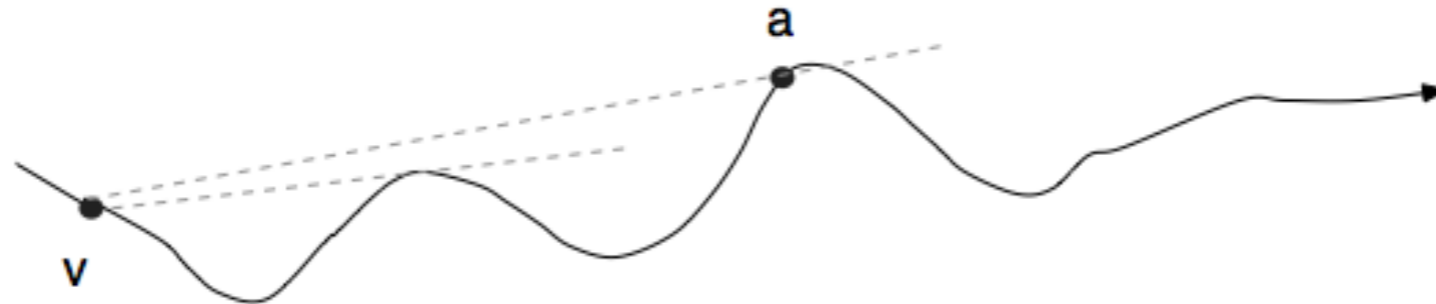


# Visibility on grid terrains



Sierra Nevada, 30m resolution

# Visibility



$(u,v)$  visible iff segment  $uv$  does not intersect  $T$

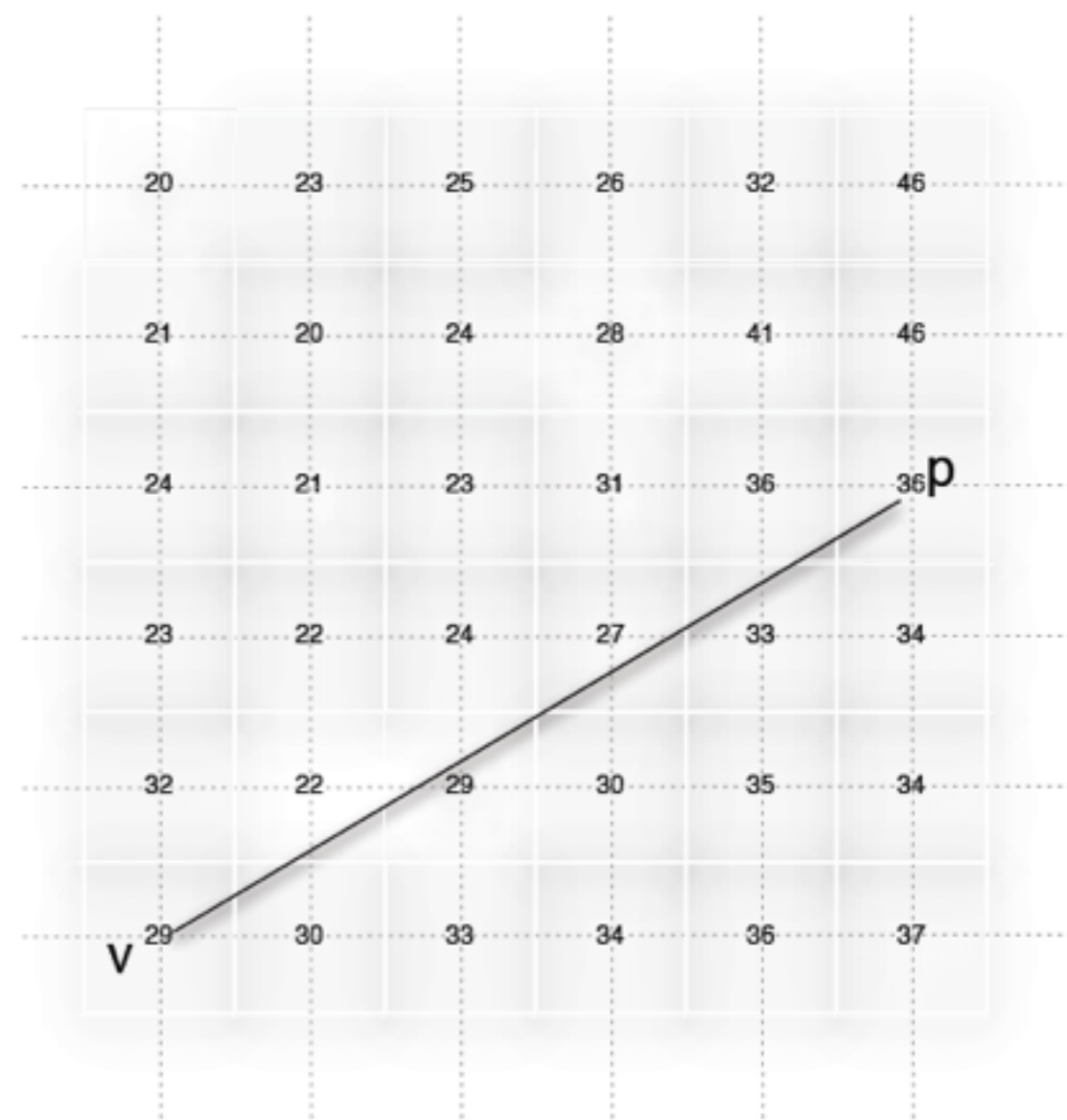
$uv$  is called line-of-sight (LOS)

# Basic viewshed algorithm

Input: elevation grid

Output: visibility grid, each point marked visible/invisible

- For each  $p$  in grid
  - compute intersections between  $vp$  and grid lines
  - if all these points are below  $vp$  then  $p$  is visible

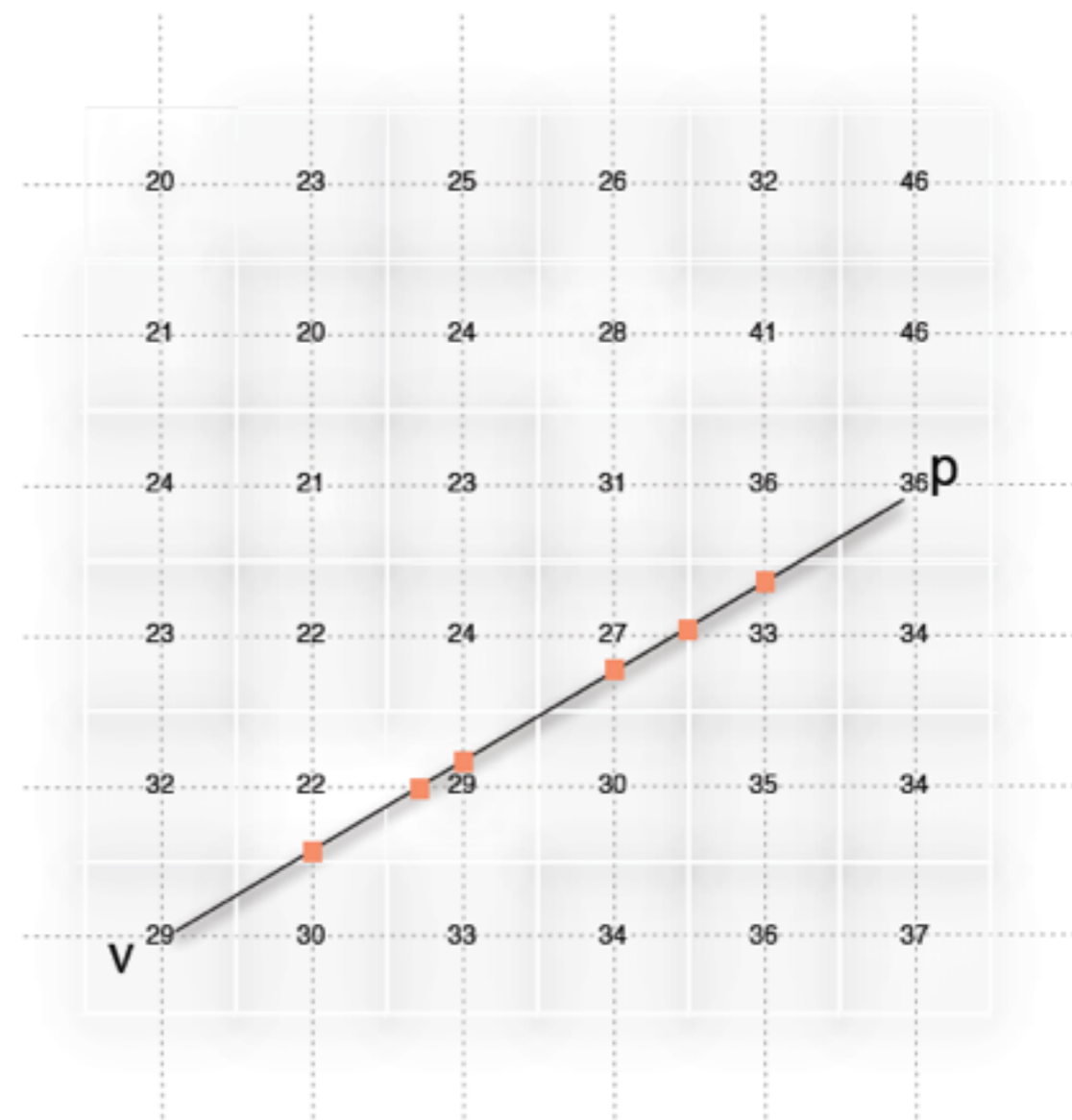


# Basic viewshed algorithm

Input: elevation grid

Output: visibility grid, each point marked visible/invisible

- For each  $p$  in grid
  - compute intersections between  $vp$  and grid lines
  - if all these points are below  $vp$  then  $p$  is visible





# Basic viewshed algorithm

Input: elevation grid

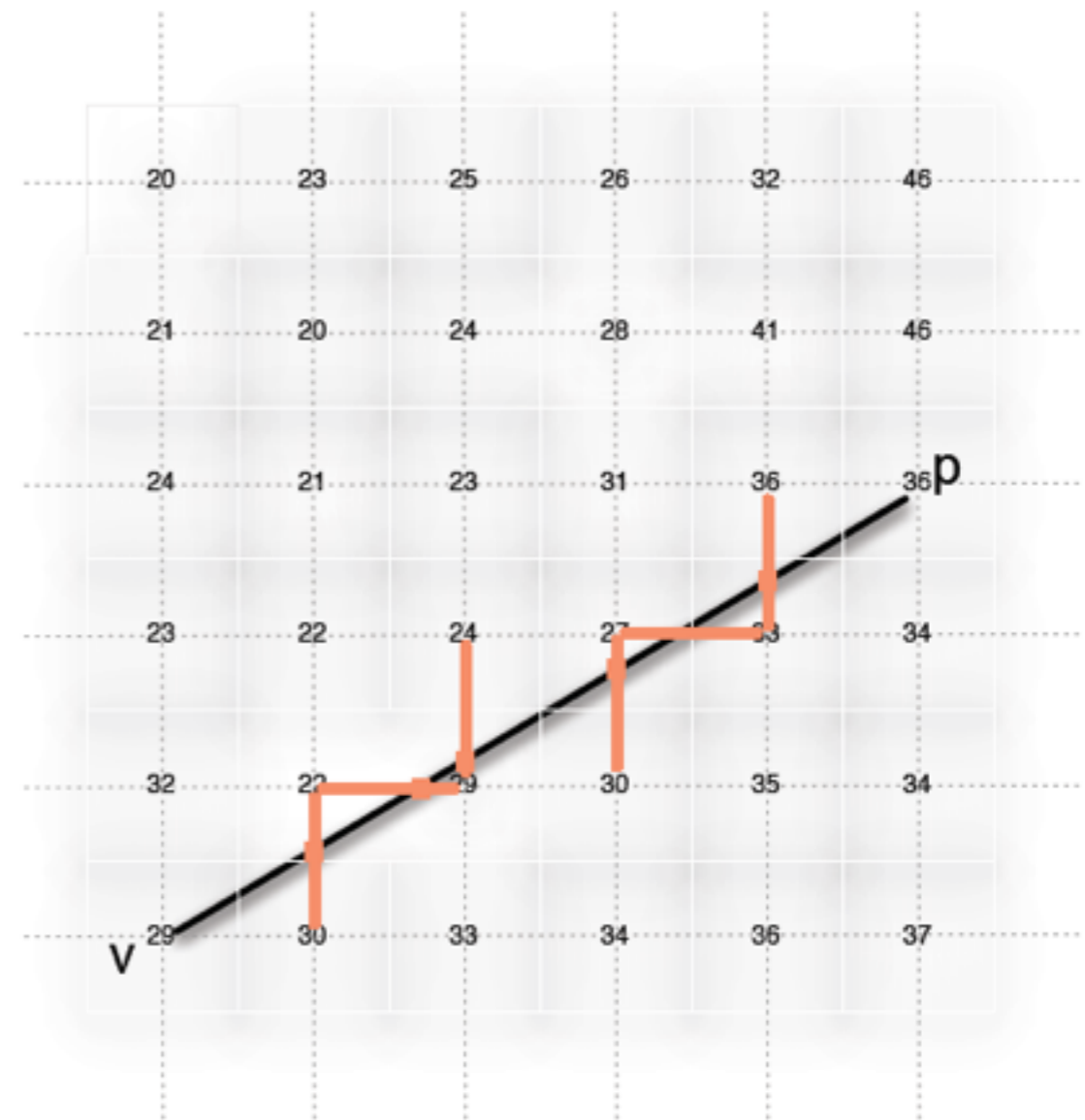
Output: visibility grid, each point marked visible/invisible

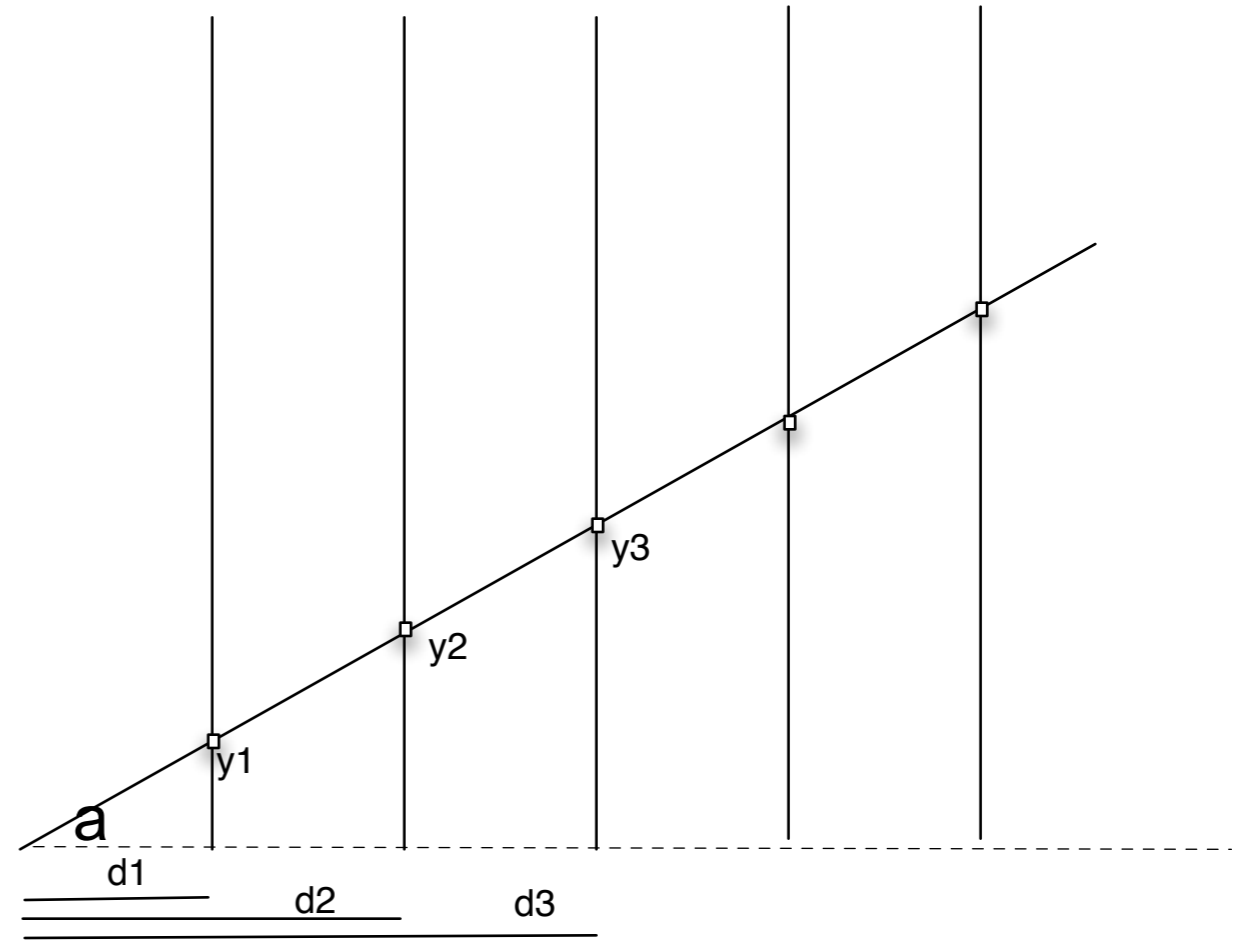
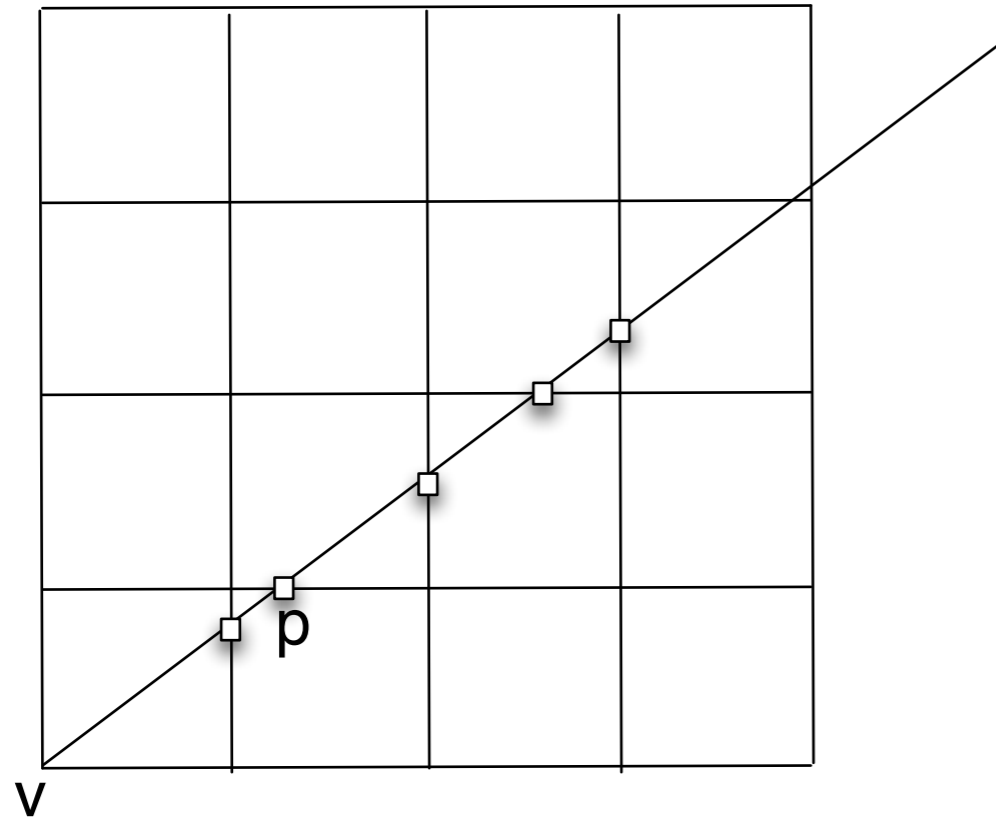
- For each  $p$  in grid
  - compute intersections between  $vp$  and grid lines
  - if all these points are below  $vp$  then  $p$  is visible

Assume grid of  $n$  points

$(\sqrt{n} \times \sqrt{n})$

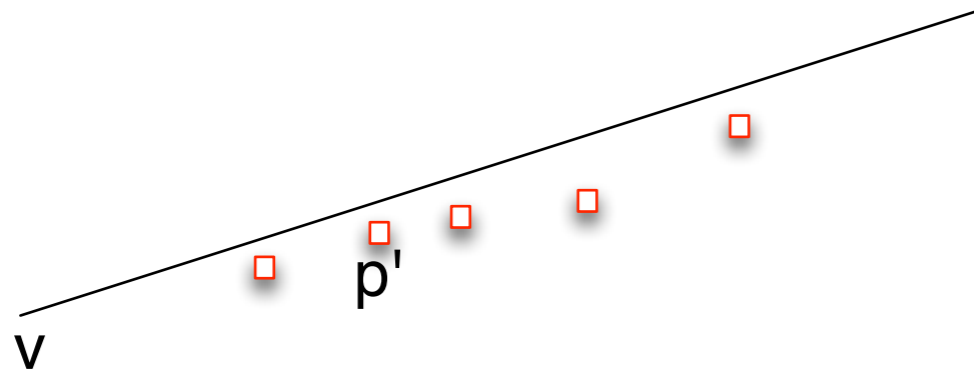
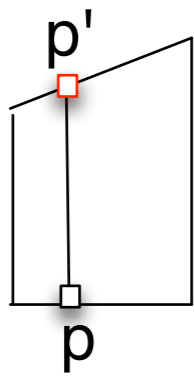
Running time:  $O(n\sqrt{n})$





$$y1 = d1 \tan a$$

$$y2 = d2 \tan a$$

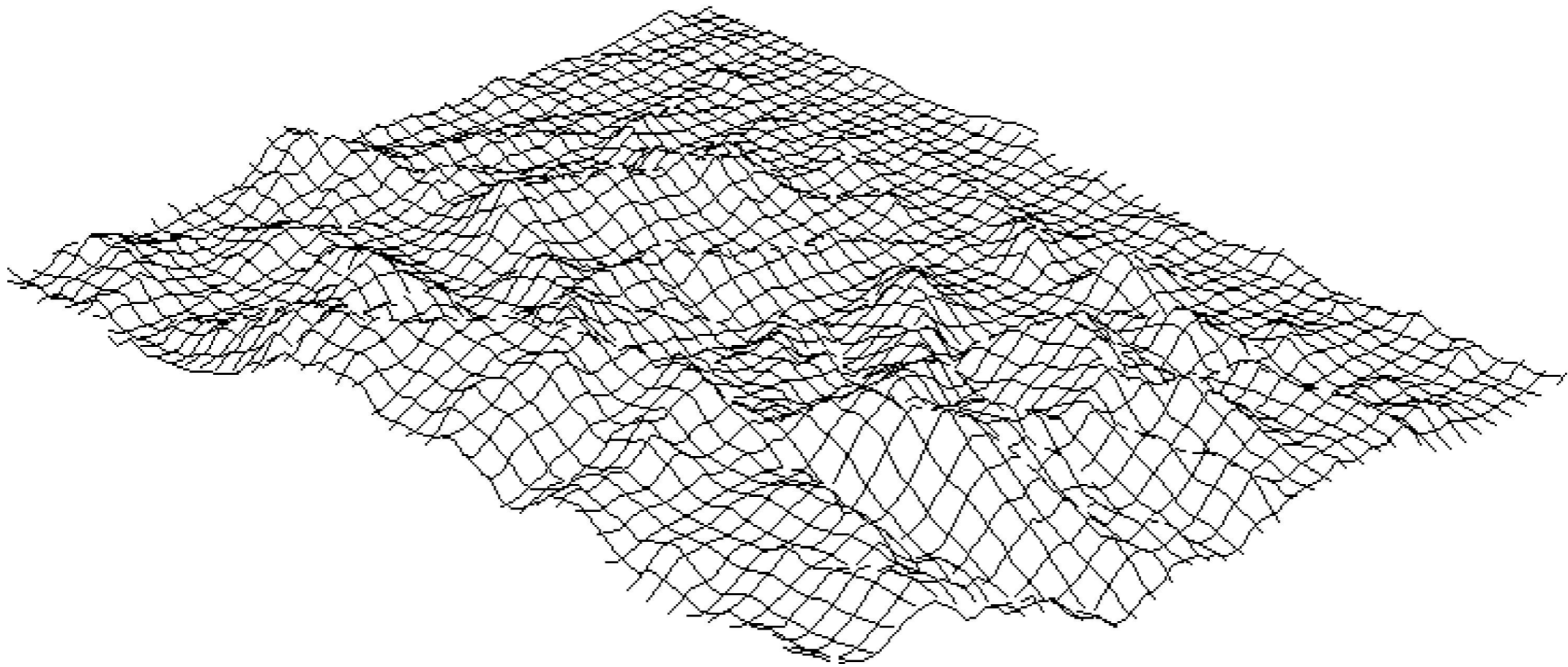


# Viewshed on grids

Grid of  $n$  points:  
 $\sqrt{n} \times \sqrt{n}$

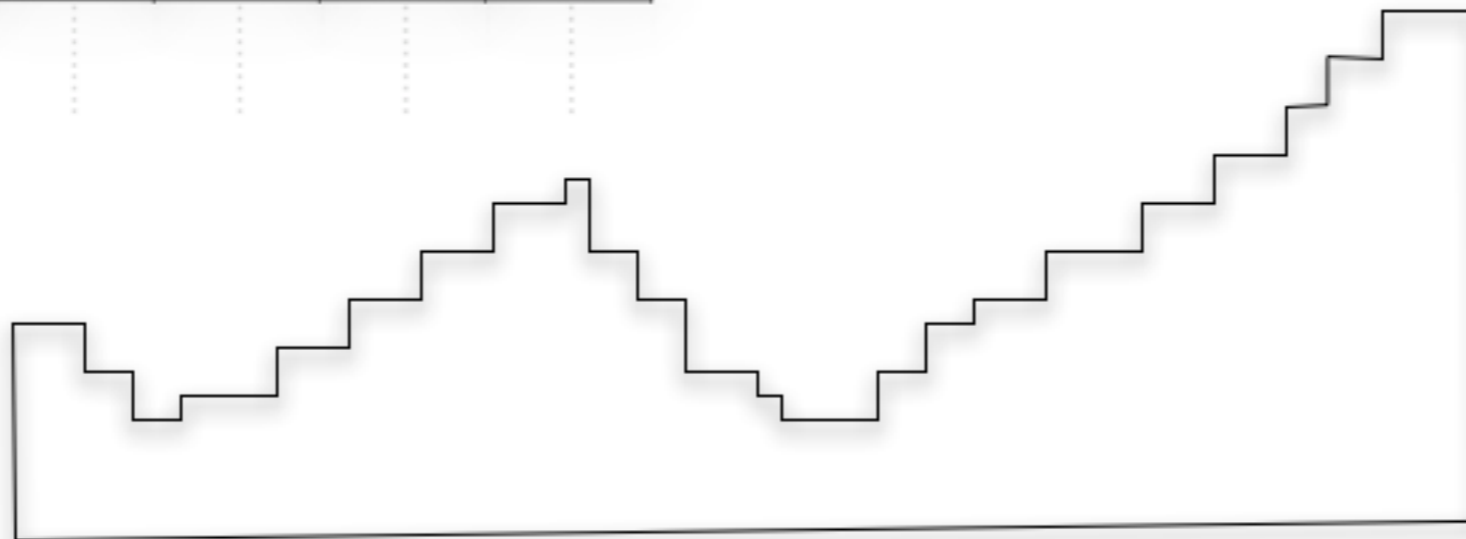
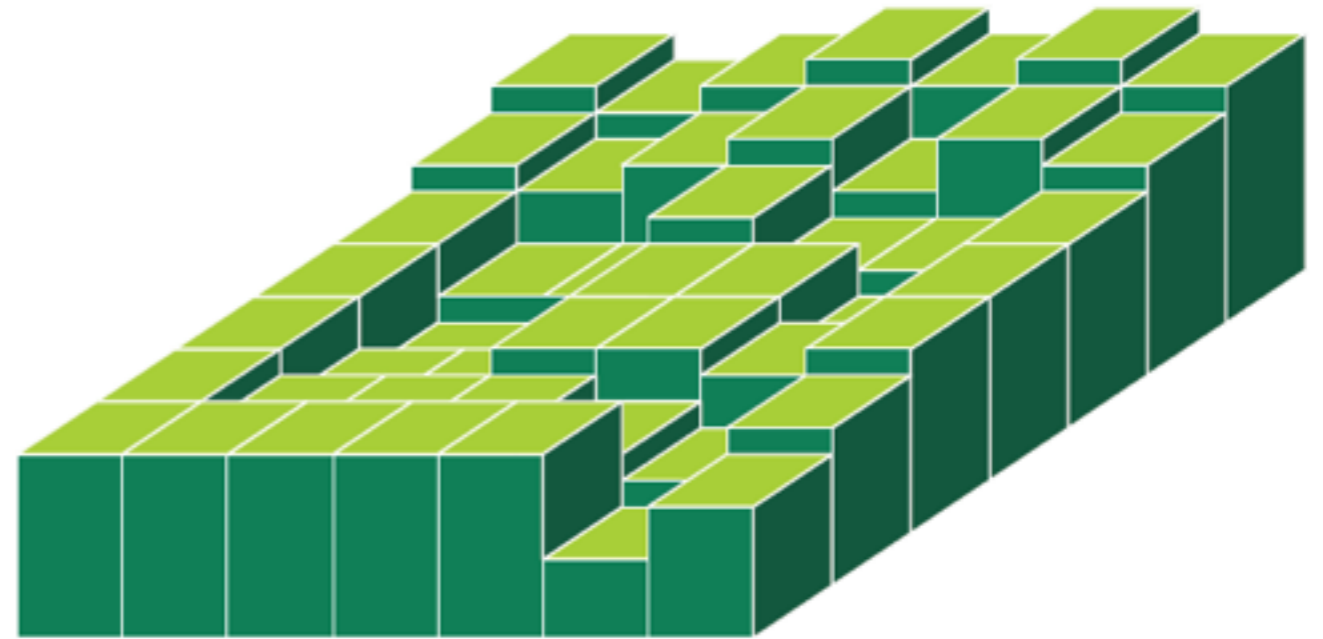
- The straightforward  $O(n \sqrt{n})$  algorithm
  - uses linear interpolation
  - “exact” as much as data allows
- Better?
- Van Kreveld, using different model
  - nearest neighbor interpolation
  - $O(n \lg n)$

# Grids with linear interpolation

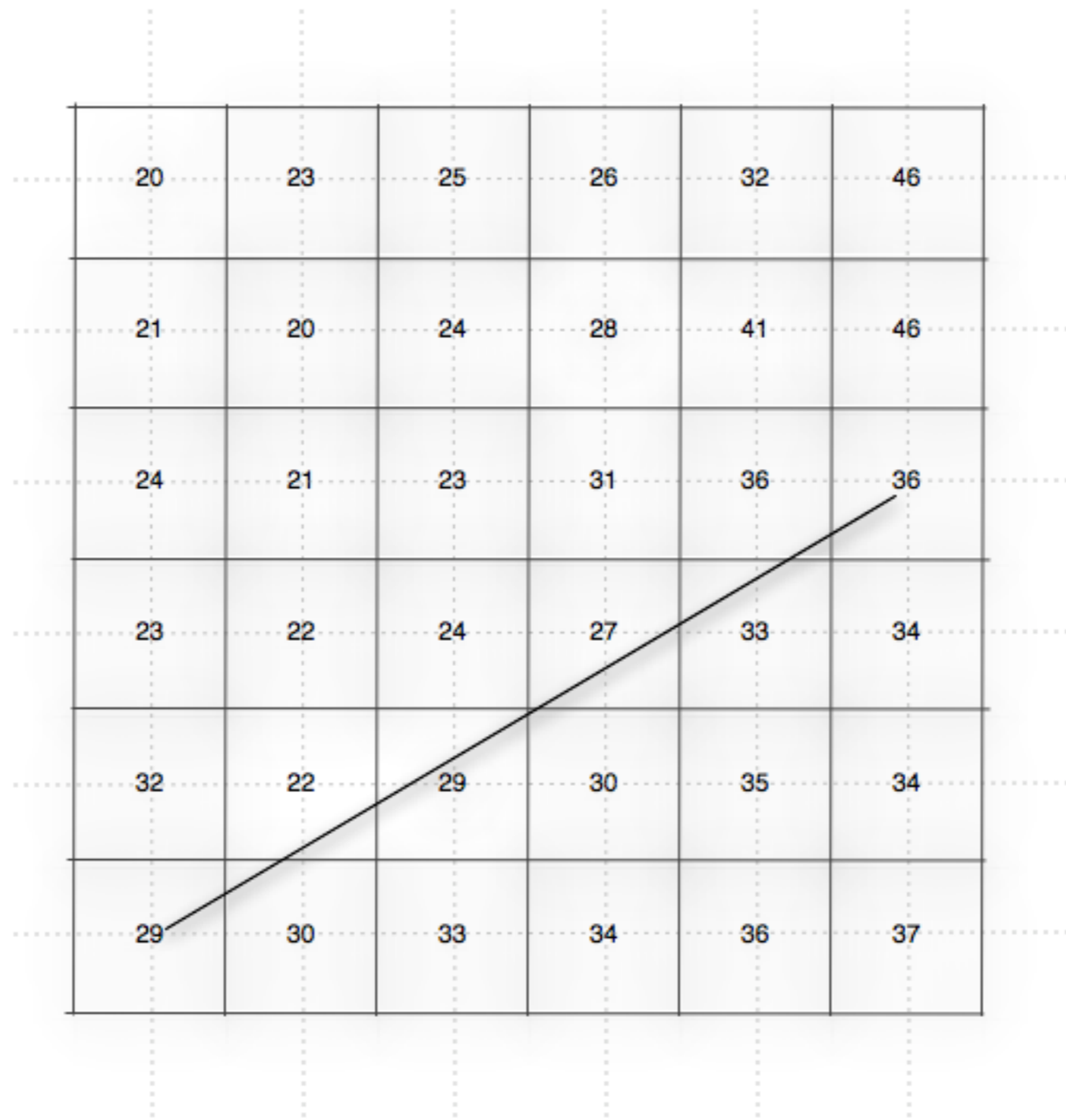


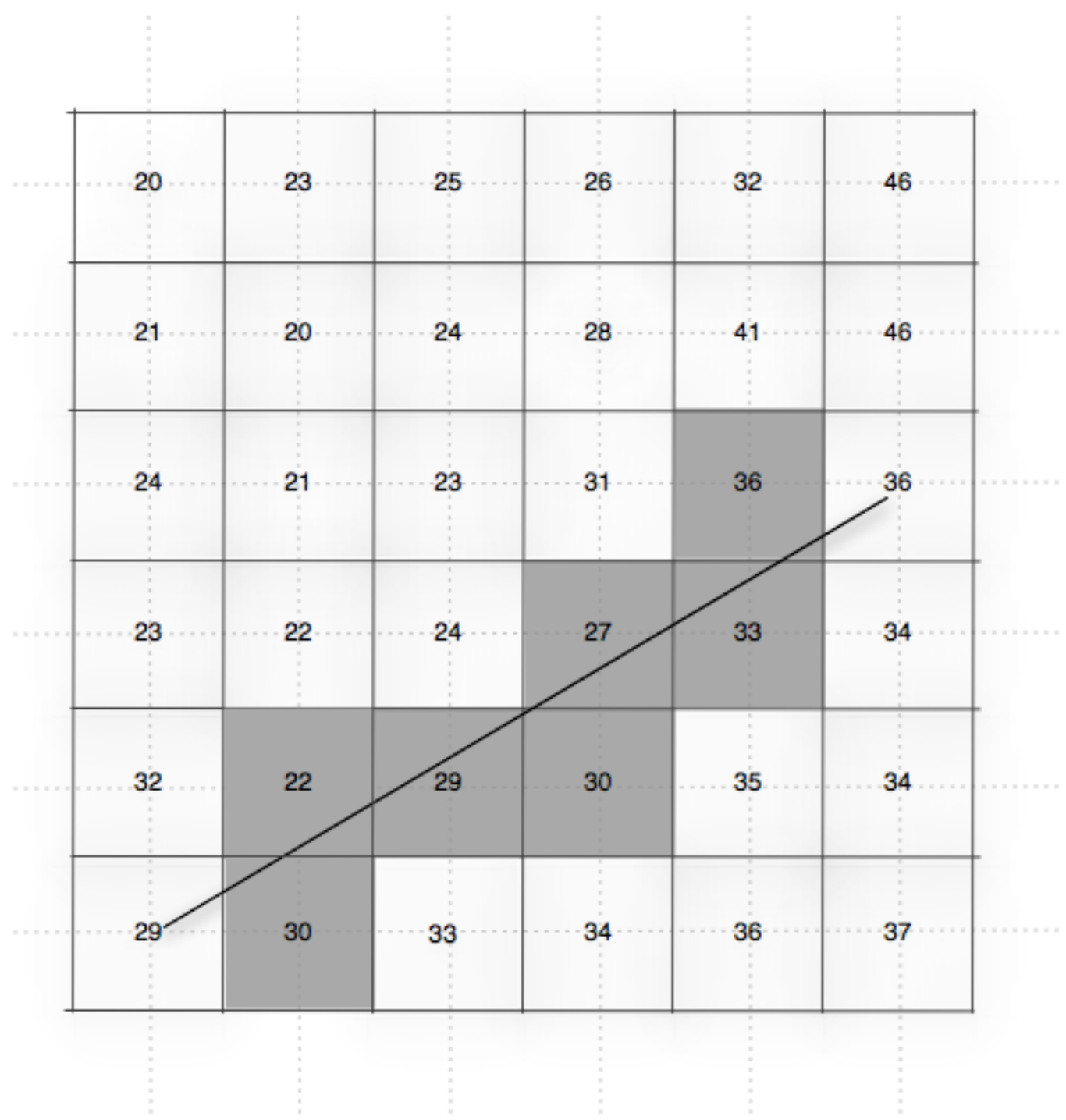
# Grids with nearest neighbor interpolation

20	23	25	26	32	46
21	20	24	28	41	46
24	21	23	31	36	36
23	22	24	27	33	34
32	22	29	30	35	34
29	30	33	34	36	37

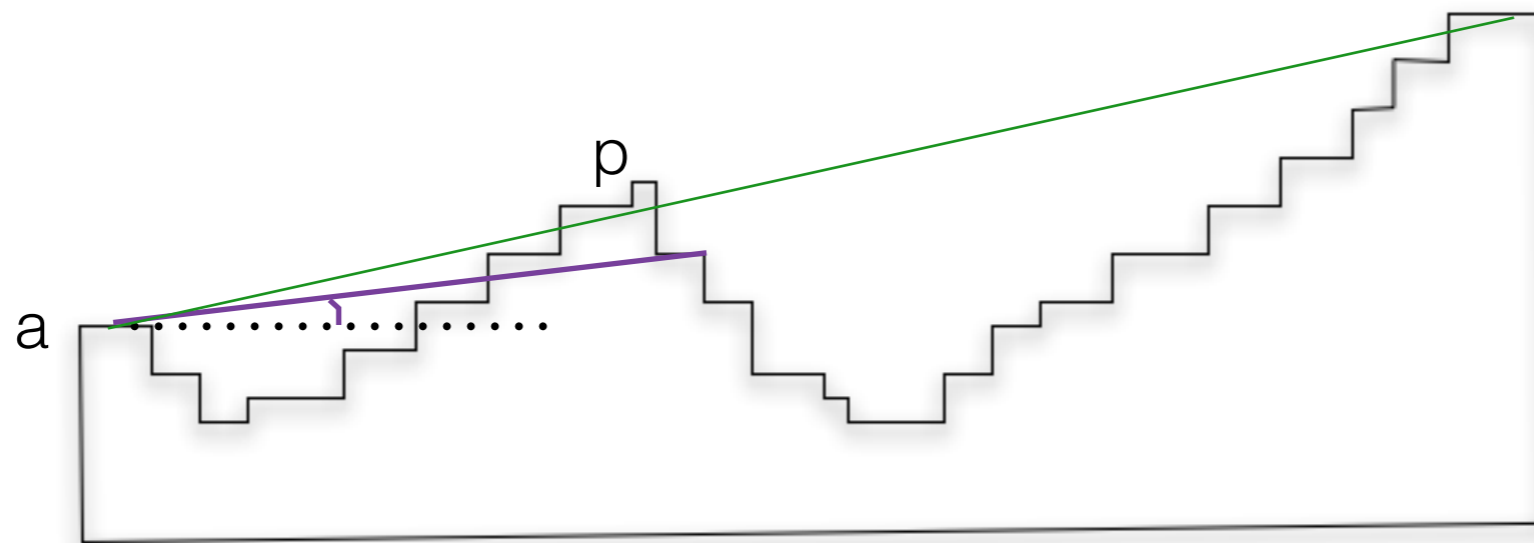


20	23	25	26	32	46
21	20	24	28	41	46
24	21	23	31	36	36
23	22	24	27	33	34
32	22	29	30	35	34
29	30	33	34	36	37

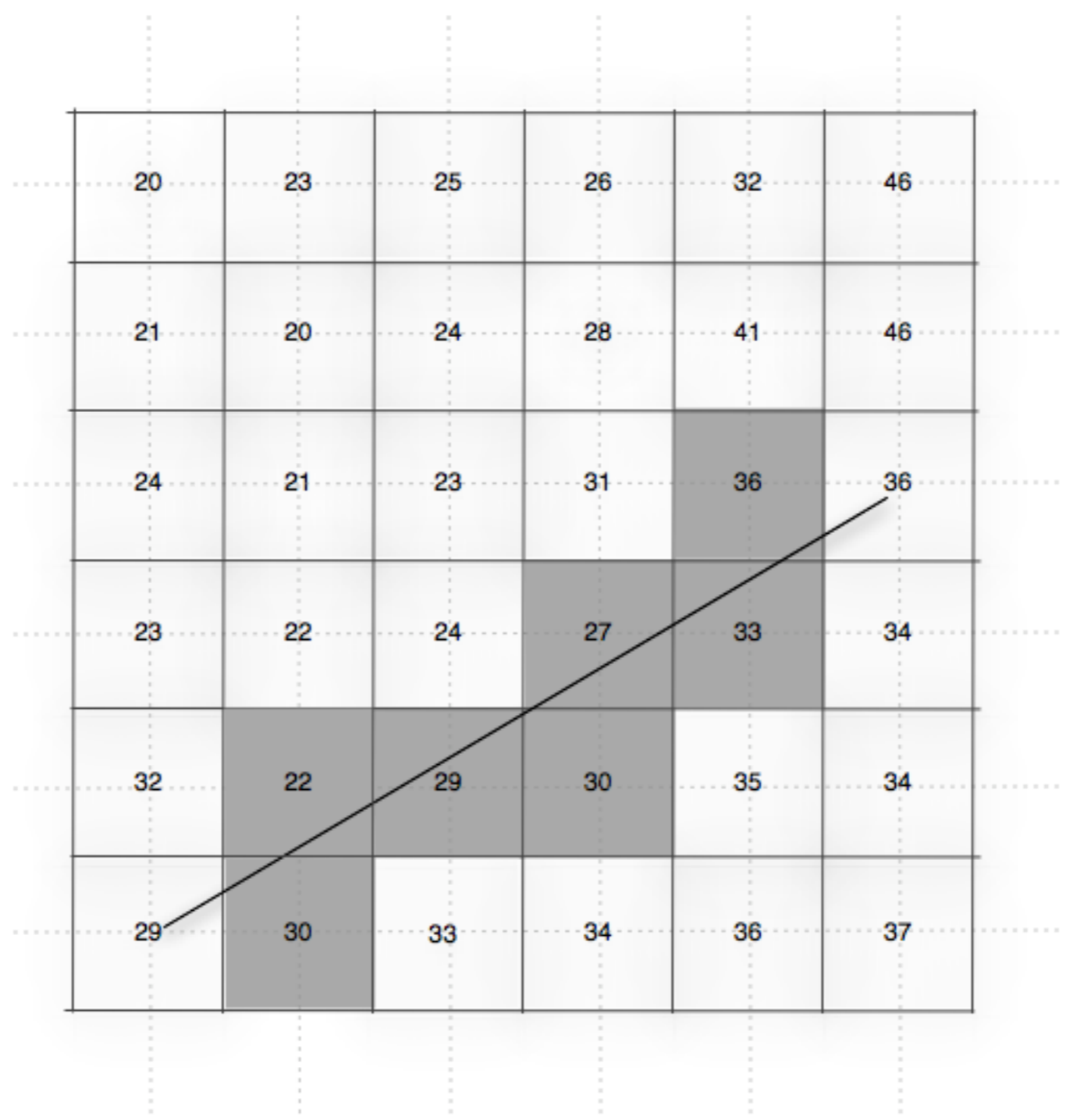


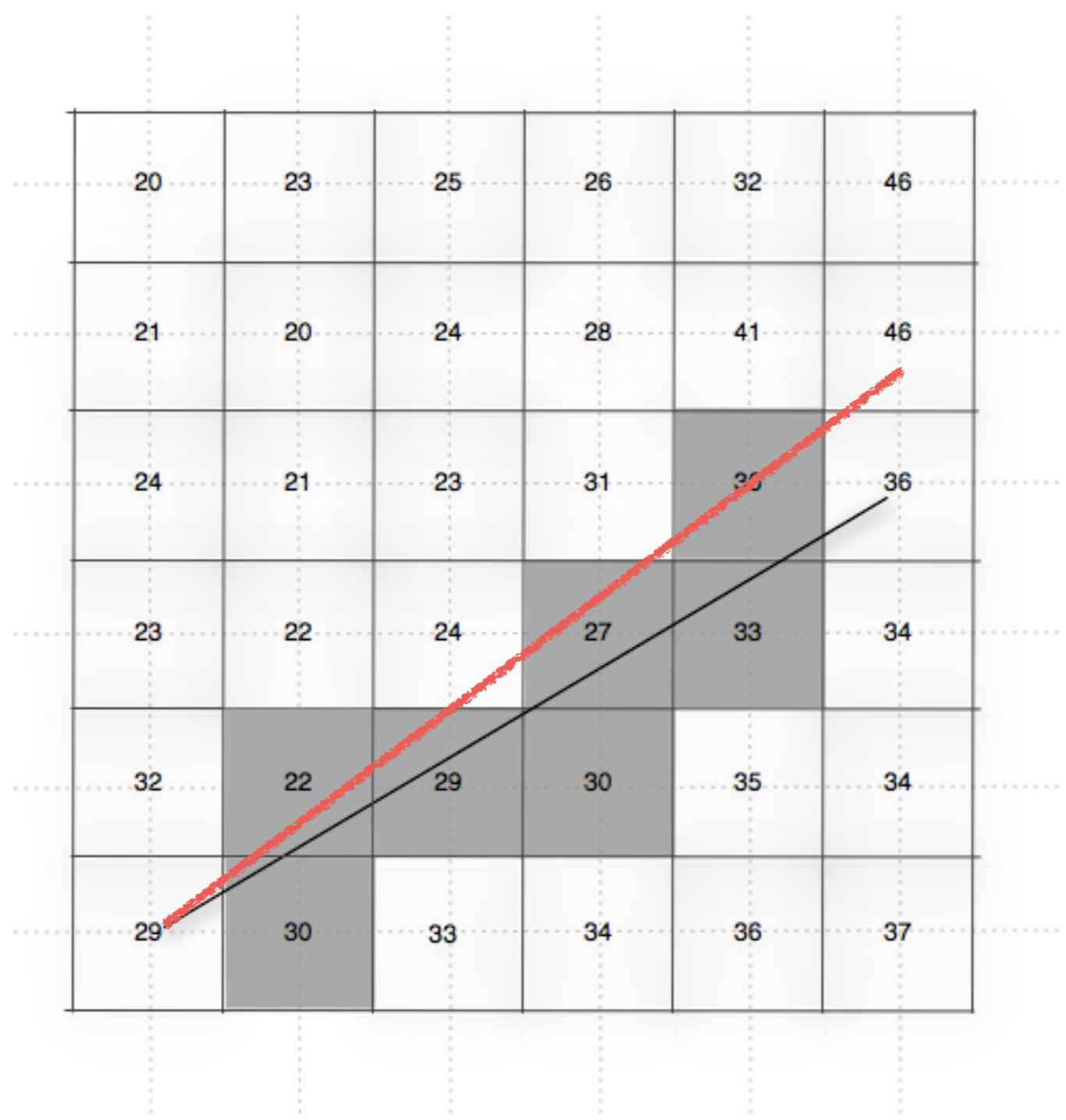


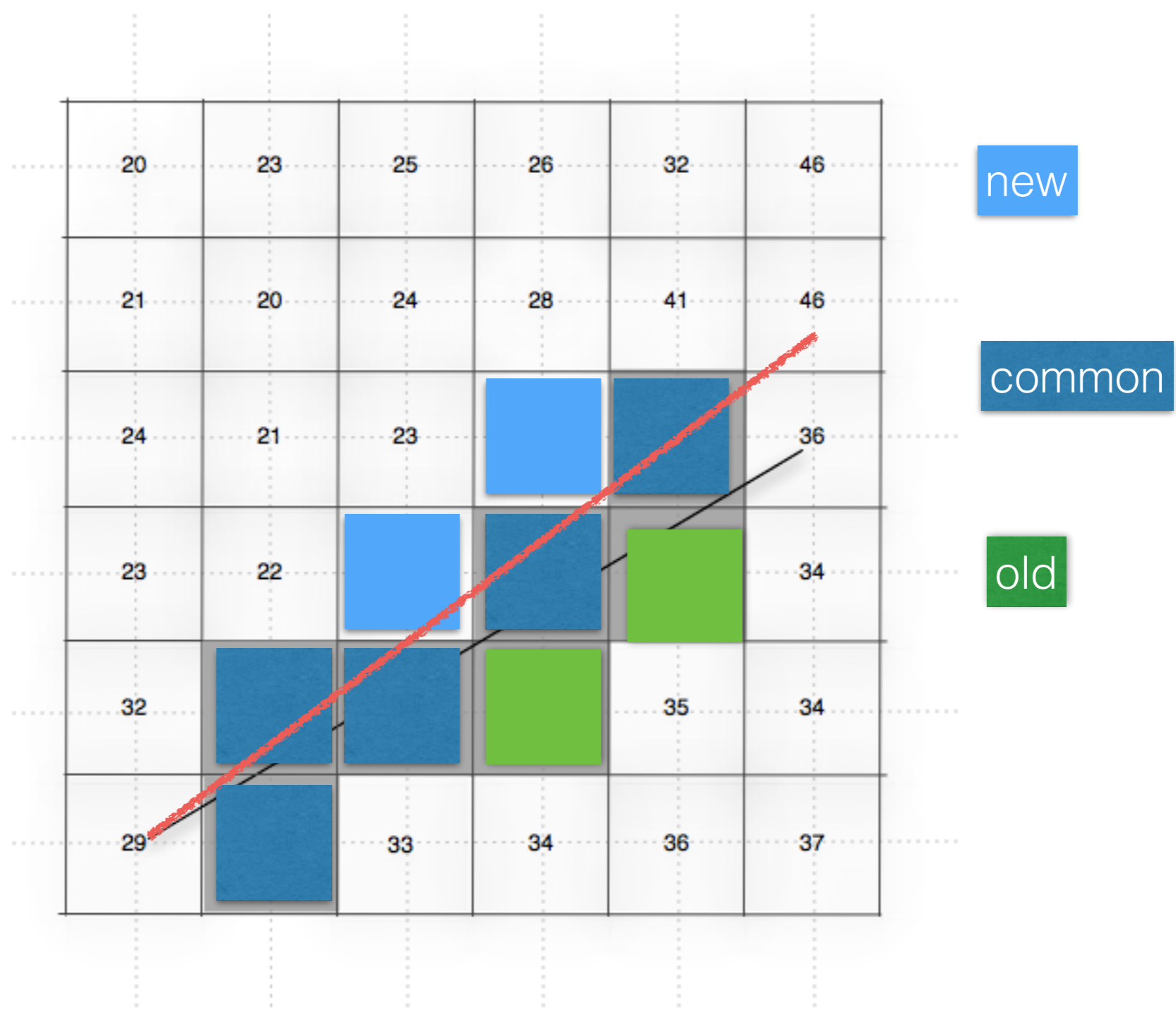


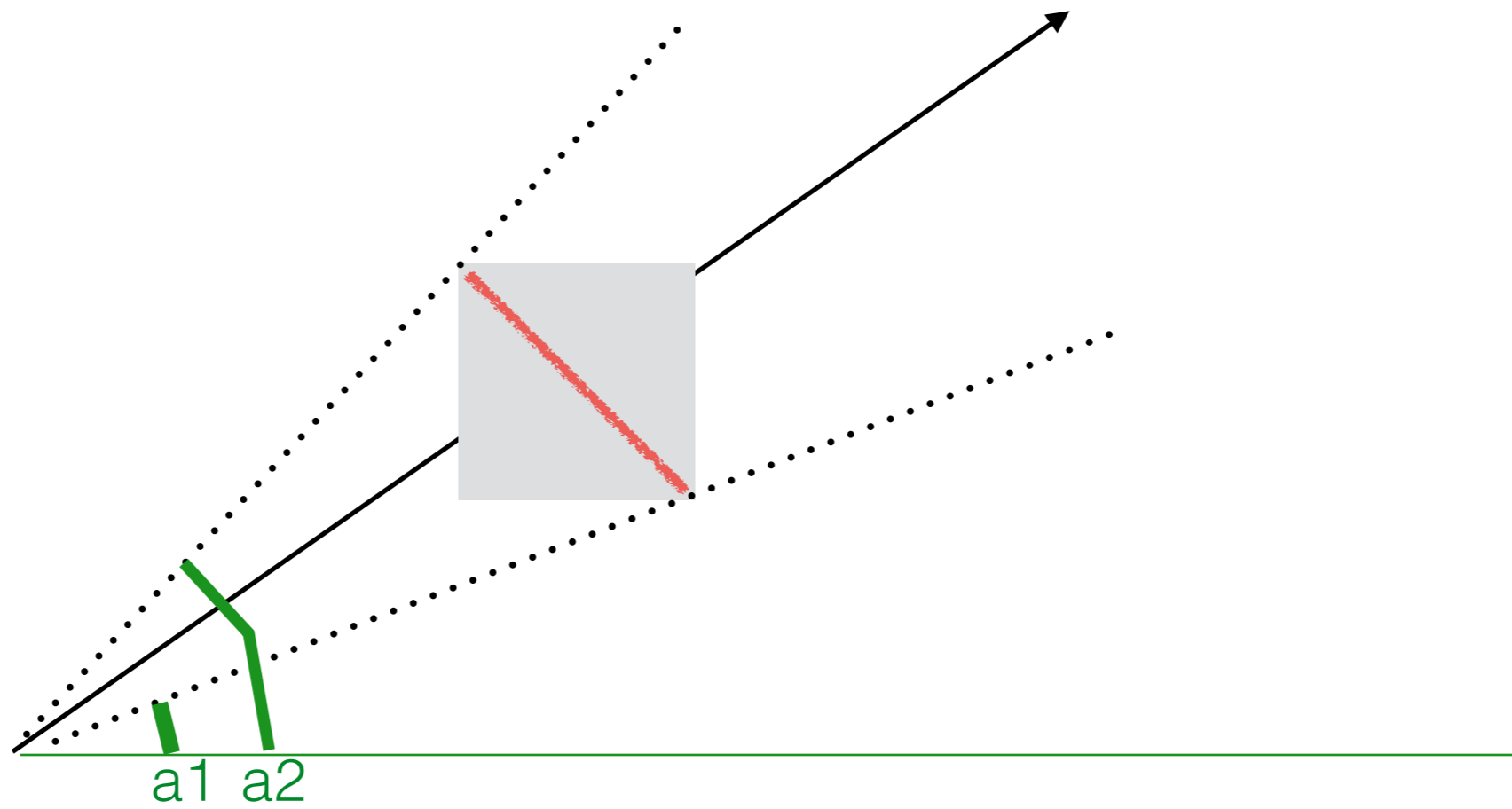


$$\text{vertical slope}(p,a) = (h_p - h_a) / d(a,p)$$

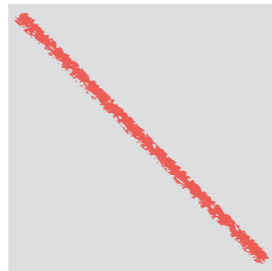




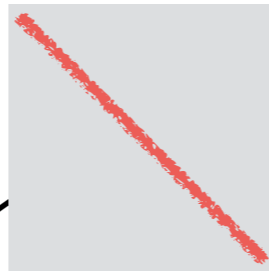




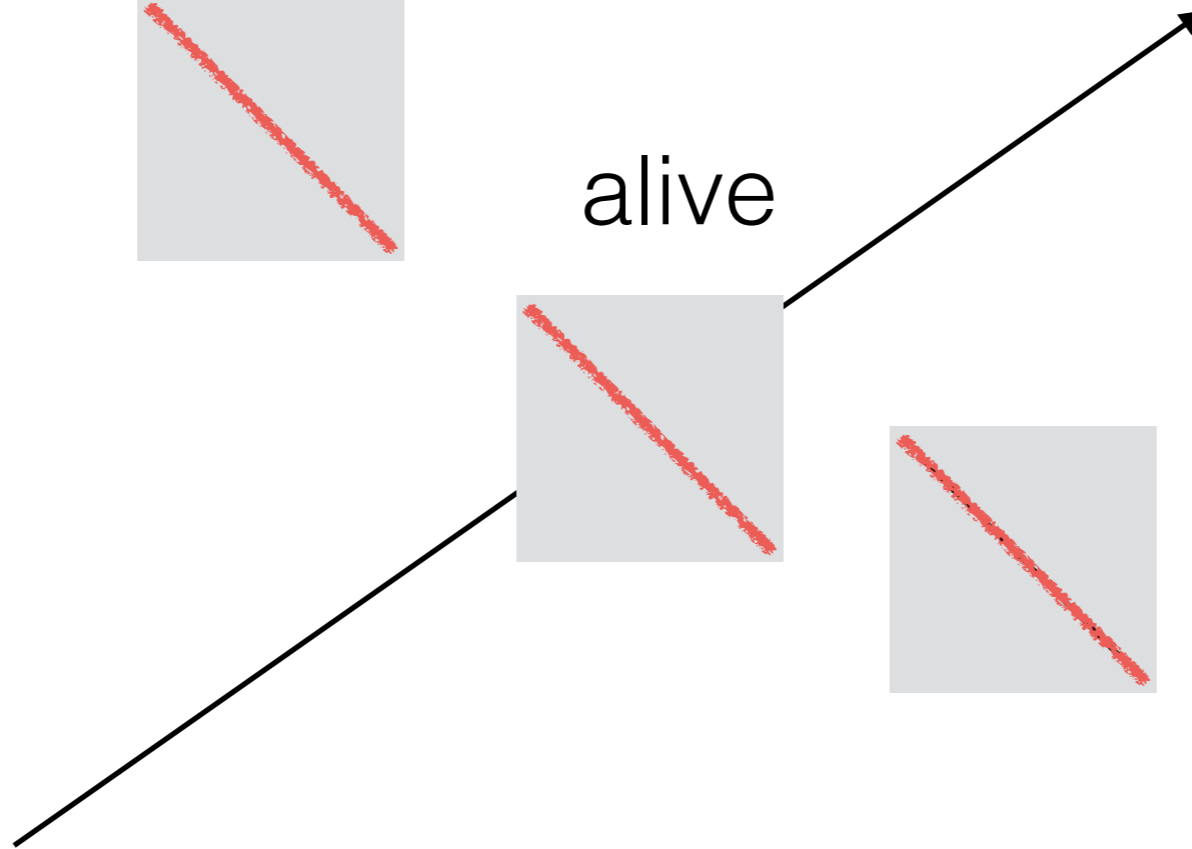
future



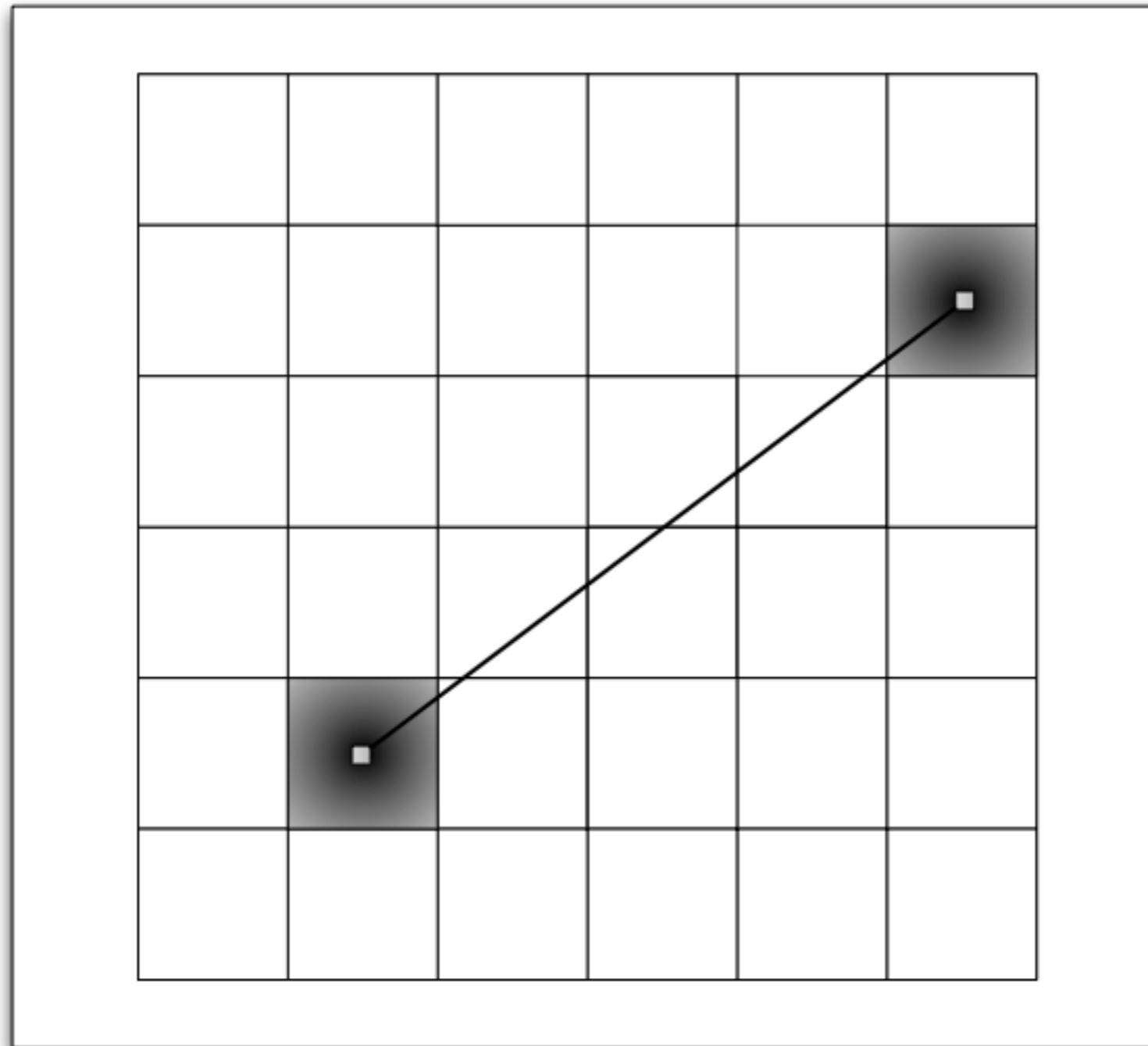
alive



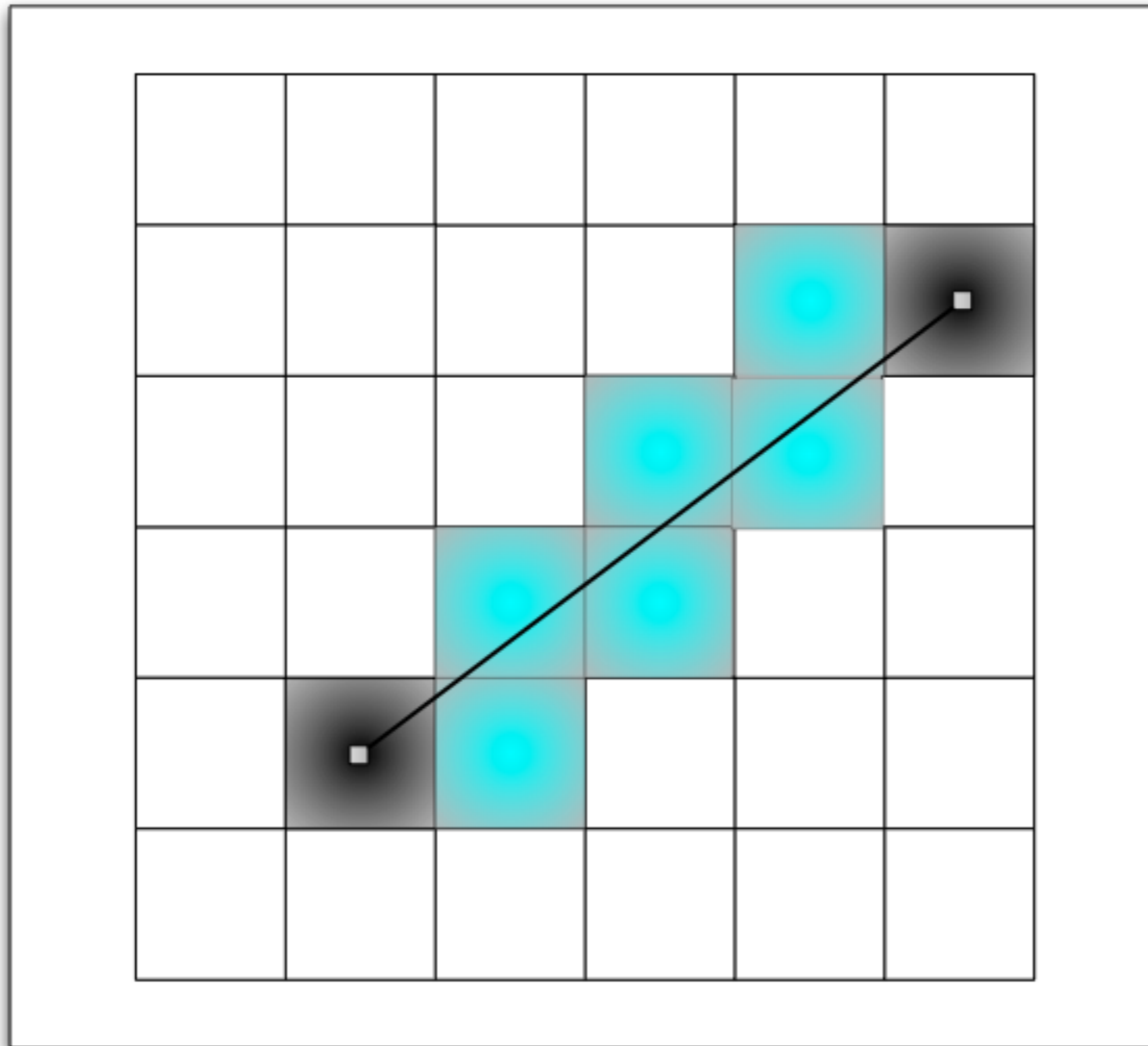
dead



# Van Kreveld's radial sweep algorithm

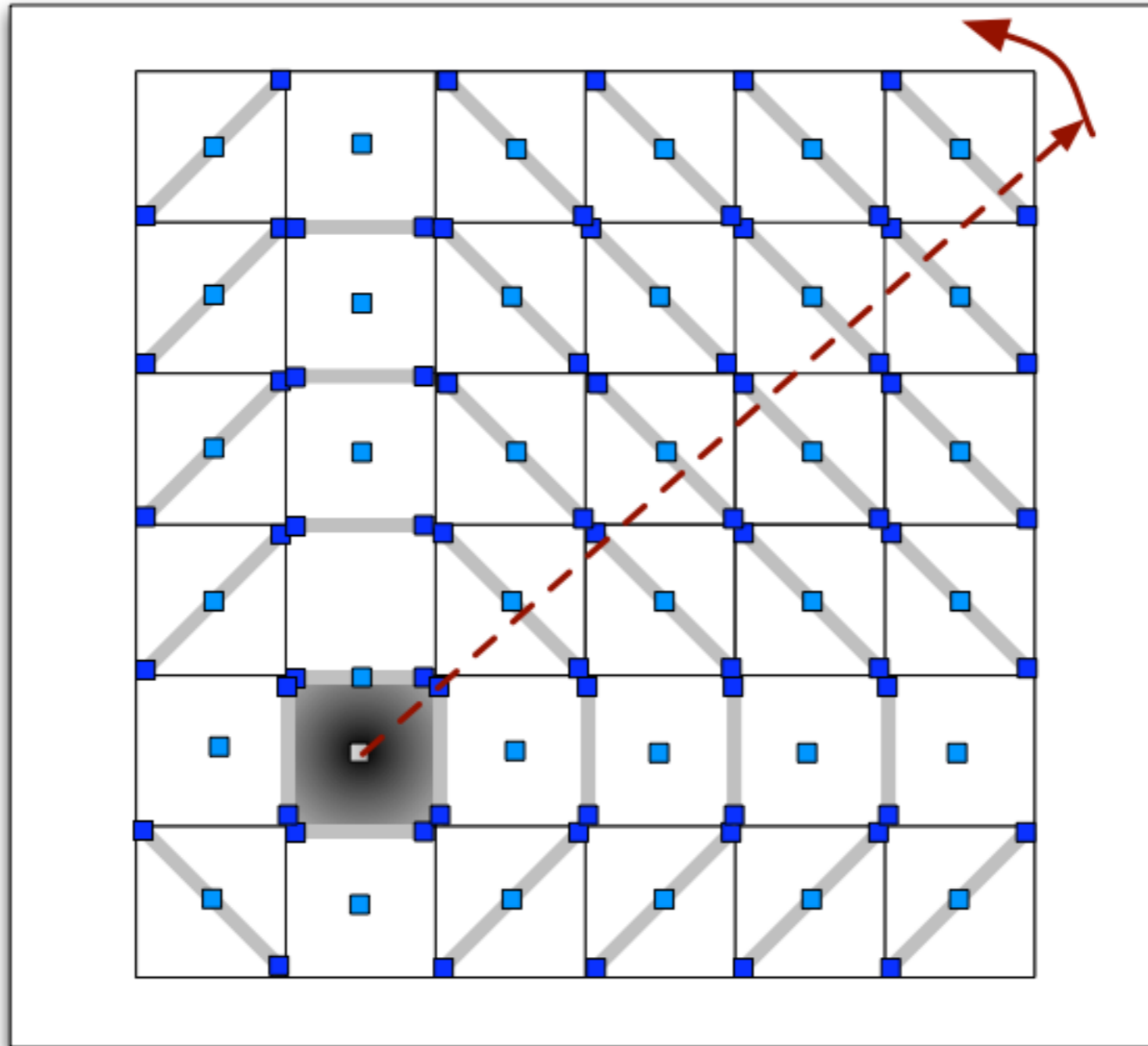


# Van Kreveld's radial sweep algorithm

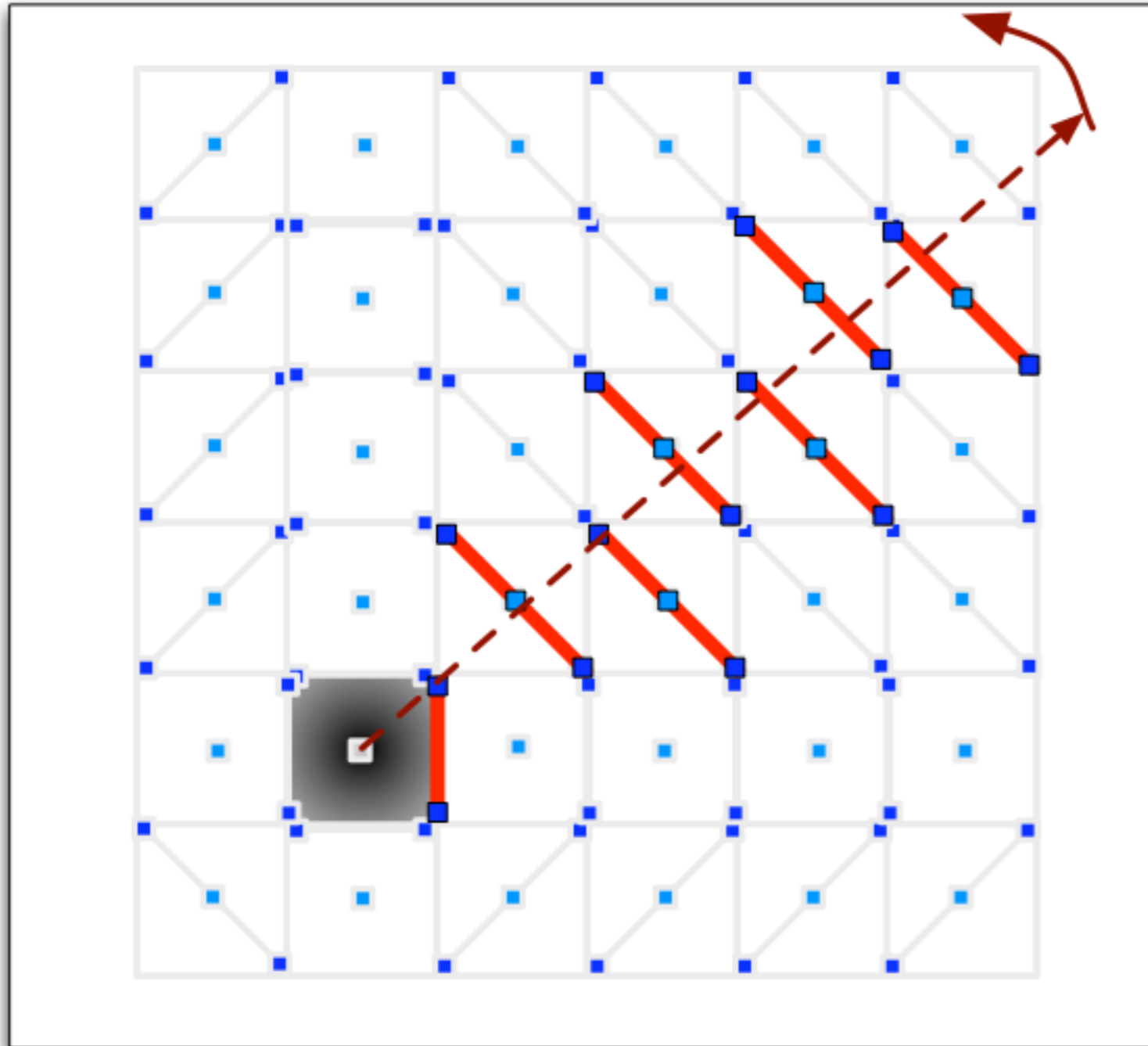
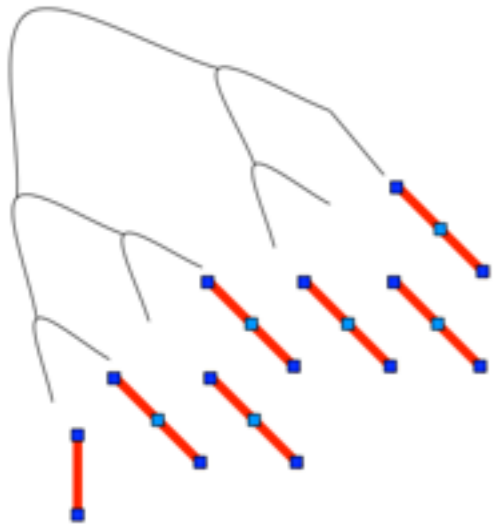




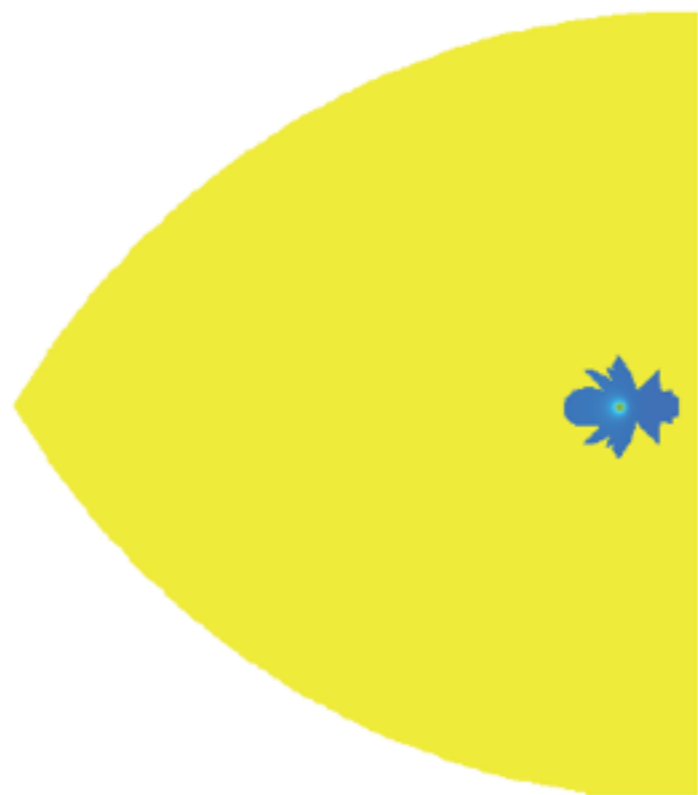
# Van Kreveld's radial sweep algorithm



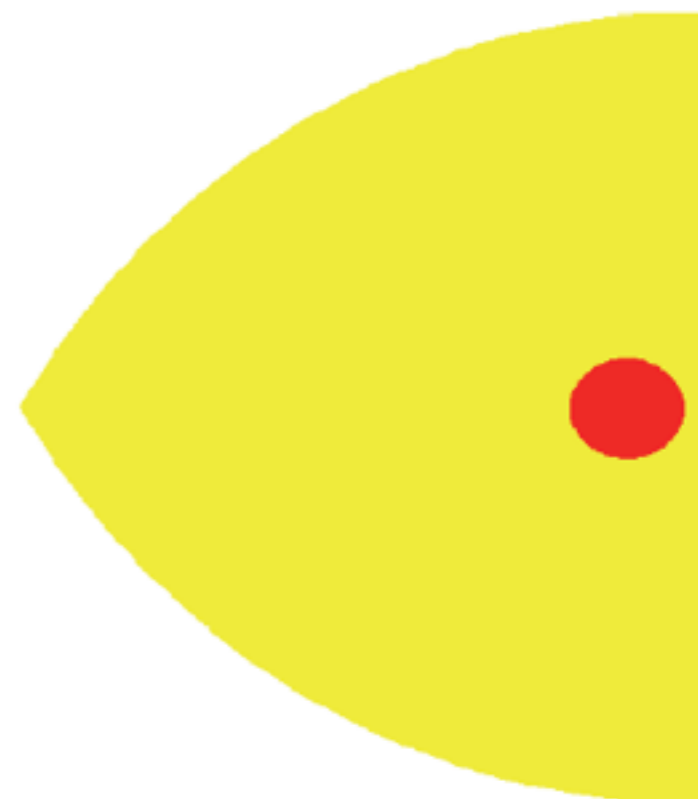
# Van Kreveld's radial sweep algorithm



# Accuracy!!



with ioradial from  
Fishman et al 2009



with GRASS