

Finding closest pair

Computational Geometry [csci 3250]
 Laura Toma
 Bowdoin College

1

2

3

Given an array of points in 2D, find the closest pair.

4

Given an array of points in 2D, find the closest pair.

5

Given an array of points in 2D, find the closest pair.

Brute force:

- mindist = VERY_LARGE_VALUE
- for all distinct pairs of points p_i, p_j
 - $d = \text{distance}(p_i, p_j)$
 - if ($d < \text{mindist}$): mindist=d

6

Given an array of points in 2D, find the closest pair.

Brute force:

- mindist = VERY_LARGE_VALUE
- for all distinct pairs of points p_i, p_j
 - $d = \text{distance}(p_i, p_j)$
 - if ($d < \text{mindist}$): mindist=d

• Analysis:

- $O(n^2)$ pairs ==> $O(n^2)$ time

7

Given an array of points in 2D, find the closest pair.

Brute force:

- mindist = VERY_LARGE_VALUE
- for all distinct pairs of points p_i, p_j
 - $d = \text{distance}(p_i, p_j)$
 - if ($d < \text{mindist}$): mindist=d

• Analysis:

- $O(n^2)$ pairs ==> $O(n^2)$ time

Can we do better than $O(n^2)$?

8

Given an array of points in 2D, find the closest pair.

Brute force:

- mindist = VERY_LARGE_VALUE
- for all distinct pairs of points p_i, p_j
 - $d = \text{distance}(p_i, p_j)$
 - if ($d < \text{mindist}$): mindist=d

• Analysis:

- $O(n^2)$ pairs ==> $O(n^2)$ time

Can we do better than $O(n^2)$?

Hint: divide-and-conquer

9

Divide-and-conquer

mergesort(array A)

- if A has 1 element, there's nothing to sort, so just return it
- else
 - //divide input A into two halves, A1 and A2*
 - A1 = first half of A
 - A2 = second half of A
 - //sort recursively each half*
 - sorted_first_half = **mergesort**(array A1)
 - sorted_second_half = **mergesort**(array A2)
 - //merge*
 - result = merge_sorted_arrays(sorted_first_half, sorted_second_half)
 - return result

10

Divide-and-conquer

mergesort(array A)

- if A has 1 element, there's nothing to sort, so just return it
- else
 - //divide input A into two halves, A1 and A2*
 - A1 = first half of A
 - A2 = second half of A
 - //sort recursively each half*
 - sorted_first_half = **mergesort**(array A1)
 - sorted_second_half = **mergesort**(array A2)
 - //merge*
 - result = merge_sorted_arrays(sorted_first_half, sorted_second_half)
 - return result

Analysis: $T(n) = 2T(n/2) + O(n) \Rightarrow O(n \lg n)$

11

In general

DC(input P)

- if P is small, solve and return
- else
 - //divide*
 - divide input P into two halves, P1 and P2
 - //recurse*
 - result1 = **DC**(P1)
 - result2 = **DC**(P2)
 - //merge*
 - do_something_to_figure_out_result_for_P
- return result

Analysis: $T(n) = 2T(n/2) + O(\text{merge phase})$

12

In general

DC(input P)

```

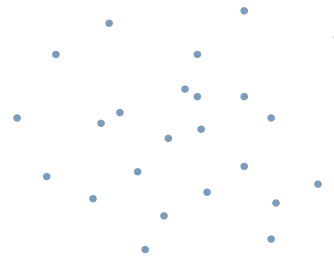
if P is small, solve and return
else
  //divide
  divide input P into two halves, P1 and P2
  //recurse
  result1 = DC(P1)
  result2 = DC(P2)
  //merge
  do_something_to_figure_out_result_for_P
return result
    
```

Analysis: $T(n) = 2T(n/2) + O(\text{merge phase})$

- if merge phase is $O(n)$: $T(n) = 2T(n/2) + O(n) \Rightarrow O(n \lg n)$
- if merge phase is $O(n \lg n)$: $T(n) = 2T(n/2) + O(n \lg n) \Rightarrow O(n \lg^2 n)$

13

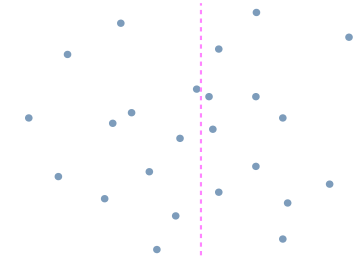
Divide-and-conquer for closest pair



14

Divide-and-conquer for closest pair

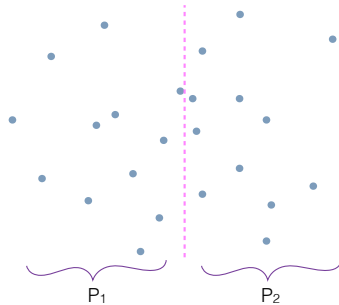
- find vertical line that splits P in half



15

Divide-and-conquer for closest pair

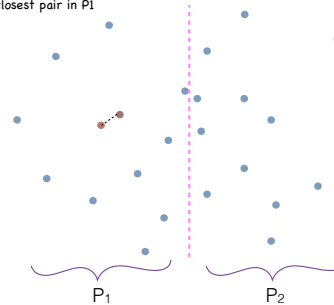
- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line



16

Divide-and-conquer for closest pair

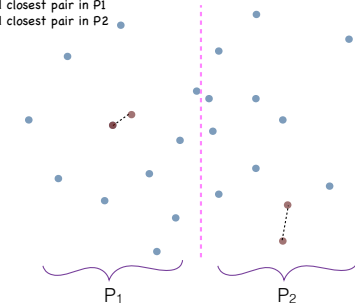
- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1



17

Divide-and-conquer for closest pair

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1
- recursively find closest pair in P_2



18

Divide-and-conquer for closest pair

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1
- recursively find closest pair in P_2
-/NOW WHAT?

How can you find closest pair in P?

19

Divide-and-conquer for closest pair

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- d_1 = find closest pair in P_1
- d_2 = find closest pair in P_2
- for each p in P_1 , for each q in P_2
 - compute distance $d(p,q)$
 - $mindist = \min\{d_1, d_2, d(p,q)\}$

- Is this correct?
- Running time?

20

Divide-and-conquer for closest pair

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- d_1 = find closest pair in P_1
- d_2 = find closest pair in P_2
- for each p in P_1 , for each q in P_2
 - compute distance $d(p,q)$
 - $mindist = \min\{d_1, d_2, d(p,q)\}$

Is this correct?

- YES. The closest pair is either:
 - both points are in P_1 , and then it is found by the recursive call on P_1
 - both points are in P_2 , and then it is found by the recursive call on P_2
 - one point is in P_1 and one in P_2 , and then it is found in the merge phase, because the merge phase consider all such pairs

21

Divide-and-conquer for closest pair

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- d_1 = find closest pair in P_1
- d_2 = find closest pair in P_2
- for each p in P_1 , for each q in P_2
 - compute distance $d(p,q)$
 - $mindist = \min\{d_1, d_2, d(p,q)\}$

Running time?

- $T(n) = 2T(n/2) + O(n^2) \Rightarrow$ solves to $O(n^2)$

22

Refining the merge

Do we need to examine all pairs (p,q) , with p in P_1, q in P_2 ?

Can (p,q) be the closest pair?

23

Refining the merge

Do we need to examine all pairs (p,q) , with p in P_1, q in P_2 ?

Can (p,q) be the closest pair?
Why not? Where do p,q need to lie in order to be the closest pair?

24

Notation: $d = \min \{d_1, d_2\}$

In order for $\text{dist}(p,q)$ to be smaller than d , it must be that both the horizontal and the vertical distance between p and q must be smaller than d .

25

Claim: In order to be candidates for closest pair, points p, q must lie in the d -by- d strip centered at the median.

Proof:

26

Refining the merge

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1
- recursively find closest pair in P_2
-

Fill in the details of the new algorithm's merge phase and analyze it.

27

Refining the merge

- find vertical line that splits P in half
- let P_1, P_2 = set of points to the left/right of line
- recursively find closest pair in P_1
- recursively find closest pair in P_2
- traverse P_1 and select all points P_1' in the strip
- traverse P_2 and select all points P_2' in the strip
- for each p in P_1'
 - for each point q in P_2'
 - compute distance $d(p,q)$
 - $\text{mindist} = \min\{d, d_2, d(p,q)\}$

28

Refining the merge

- Show an example where the strip may contain $\Omega(n)$ points.

- What does this imply for the running time?

29

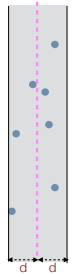
Refining the merge

- Ok, so this is not yet enough
- But ... we also know that the vertical distance between p and q cannot be greater than d .

30

Refining the merge

- Consider a point p in the stripe. How many points below it, at most, could be candidates for the closest pair (p,q) ?



31

Refining the merge

- Consider a point p in the stripe. How many points below it, at most, could be candidates for the closest pair (p,q) ?

p,q must lie in $2d$ -by- d rectangle



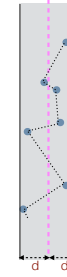
any pair of points in the left side must be at least d away

any pair of points in the right side must be at least d away

32

Refining the merge

Claim:
A point p needs to check at most 5 points following p in y -order.



Note: Assume no duplicate points.

33

Refining the merge

- Put all these together and write down the algorithm.
- Analyze the running time.

34

Refining the merge

```

closestPair(P)
//divide
• find vertical line that splits P in half
• let  $P_1, P_2$  = set of points to the left/right of line
• call  $\text{closestPair}(P_1)$ ; let  $d_1$  be the returned closest distance
• call  $\text{closestPair}(P_2)$ ; let  $d_2$  be the returned closest distance
//merge
• let  $d = \min\{d_1, d_2\}$ 
• Strip= empty
• for all  $p$  in  $P_1$ : if  $x_p > x_{\text{vertical}} - d$ : add  $p$  to Strip
• for all  $p$  in  $P_2$ : if  $x_p < x_{\text{vertical}} + d$ : add  $p$  to Strip
• sort Strip by  $y$ -coord
• initialize  $\text{mindist}=d$ 
• for each  $p$  in Strip in sorted order
  • compute its distance to the 5 points that come after it in sorted order
  • if any of these is smaller than  $\text{mindist}$ , update  $\text{mindist}$ 
• return  $\text{mindist}$ 
    
```



35

Refining the merge

```

closestPair(P)
//divide
• find vertical line that splits P in half
• let  $P_1, P_2$  = set of points to the left/right of line
• call  $\text{closestPair}(P_1)$ ; let  $d_1$  be the returned closest distance
• call  $\text{closestPair}(P_2)$ ; let  $d_2$  be the returned closest distance
//merge
• let  $d = \min\{d_1, d_2\}$ 
• Strip= empty
• for all  $p$  in  $P_1$ : if  $x_p > x_{\text{vertical}} - d$ : add  $p$  to Strip
• for all  $p$  in  $P_2$ : if  $x_p < x_{\text{vertical}} + d$ : add  $p$  to Strip
• sort Strip by  $y$ -coord
• initialize  $\text{mindist}=d$ 
• for each  $p$  in Strip in sorted order
  • compute its distance to the 5 points that come after it in sorted order
  • if any of these is smaller than  $\text{mindist}$ , update  $\text{mindist}$ 
• return  $\text{mindist}$ 
    
```

Analysis: ?

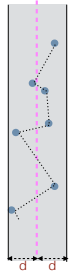


36

Refining the merge

closestPair(P)

- ```
//divide
```
- find vertical line that splits P in half
  - let  $P_1, P_2$  = set of points to the left/right of line
  - call `closestPair(P1)`; let  $d_1$  be the returned closest distance
  - call `closestPair(P2)`; let  $d_2$  be the returned closest distance
- ```
//merge
```
- let $d = \min\{d_1, d_2\}$
 - Strip= empty
 - for all p in P_1 : if $x_p > x_{\text{vertical}} - d$: add p to Strip
 - for all p in P_2 : if $x_p < x_{\text{vertical}} + d$: add p to Strip
 - sort Strip by y-coord
 - initialize $\text{mindist} = d$
 - for each p in Strip in sorted order
 - compute its distance to the 5 points that come after it in sorted order
 - if any of these is smaller than mindist , update mindist
 - return mindist



Analysis: $T(n) = 2T(n/2) + O(n \lg n) \Rightarrow O(n \lg^2 n)$

37

Divide-and-conquer for closest pair

- Avoiding the sort

38

Divide-and-conquer for closest pair

- Describe in full detail how to avoid sorting at every level, and give the detailed pseudocode. Include an explanation for how to find the vertical line that splits P in half.

39