

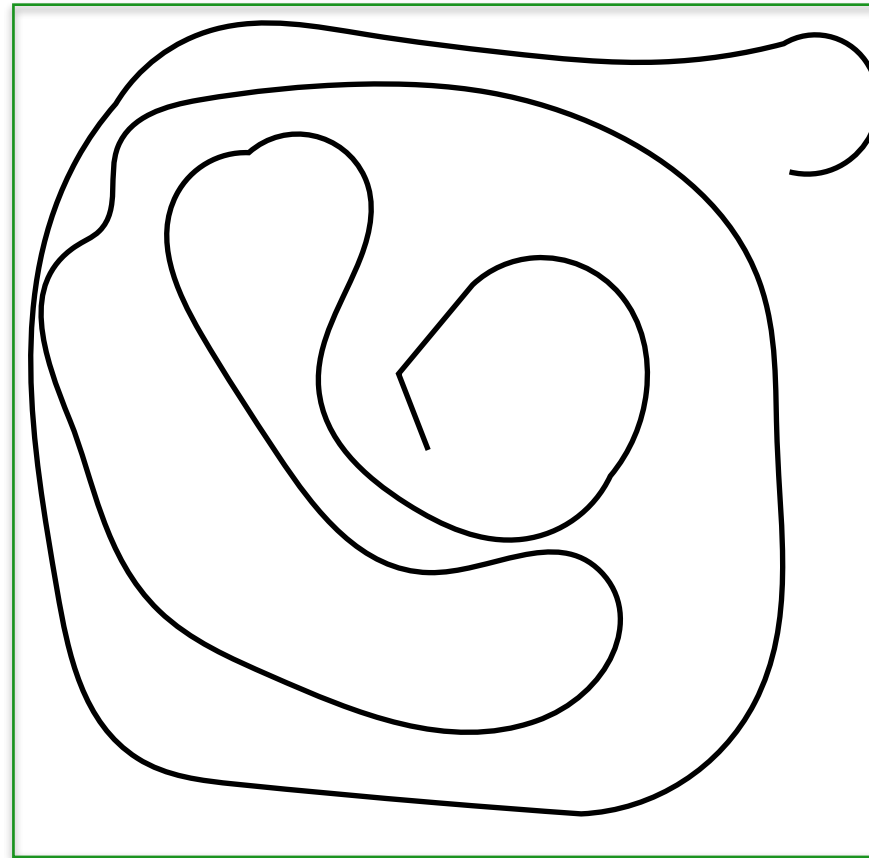
Algorithms for GIS

Space Filling Curves

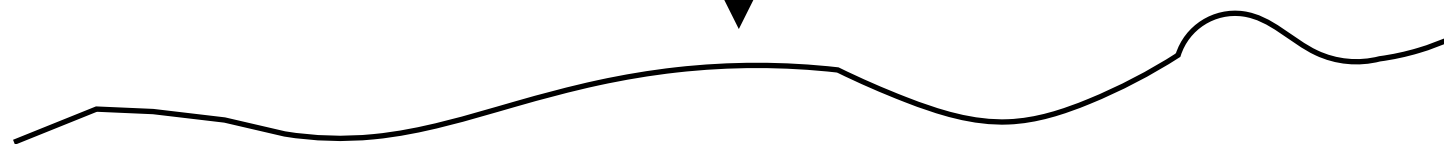
Laura Toma

Bowdoin College

Space filling curves

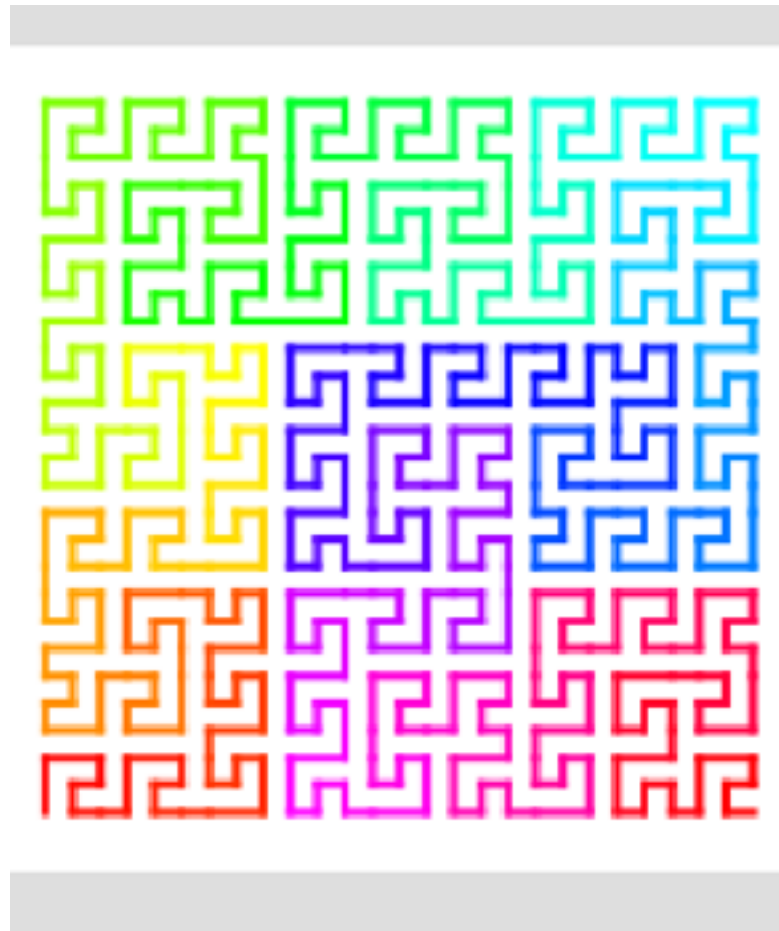


A map from an interval to a square

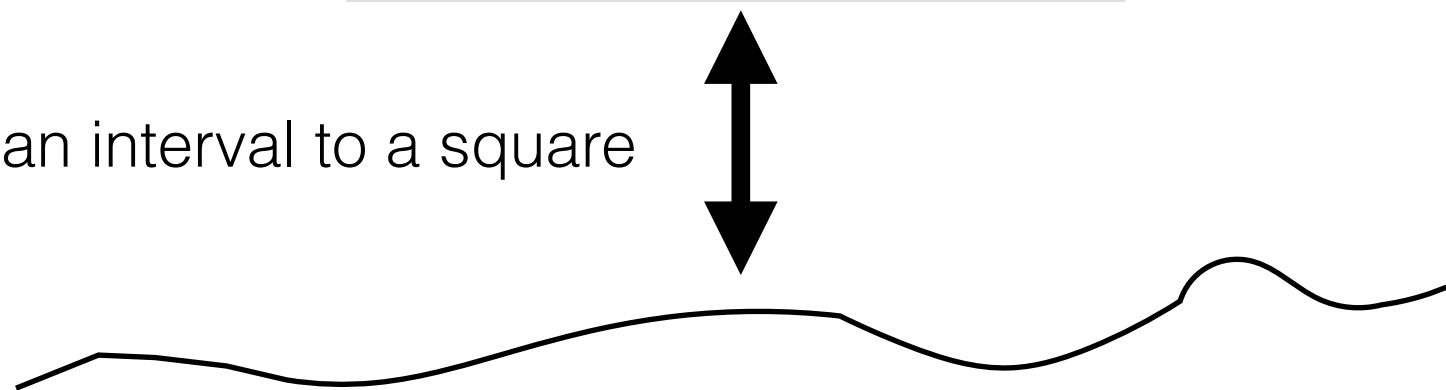


Space filling curves

<https://mathsbyagirl.wordpress.com/tag/curve/>



A map from an interval to a square



Z-order space filling curves

- Assume 2D points with integer coordinates on k bits

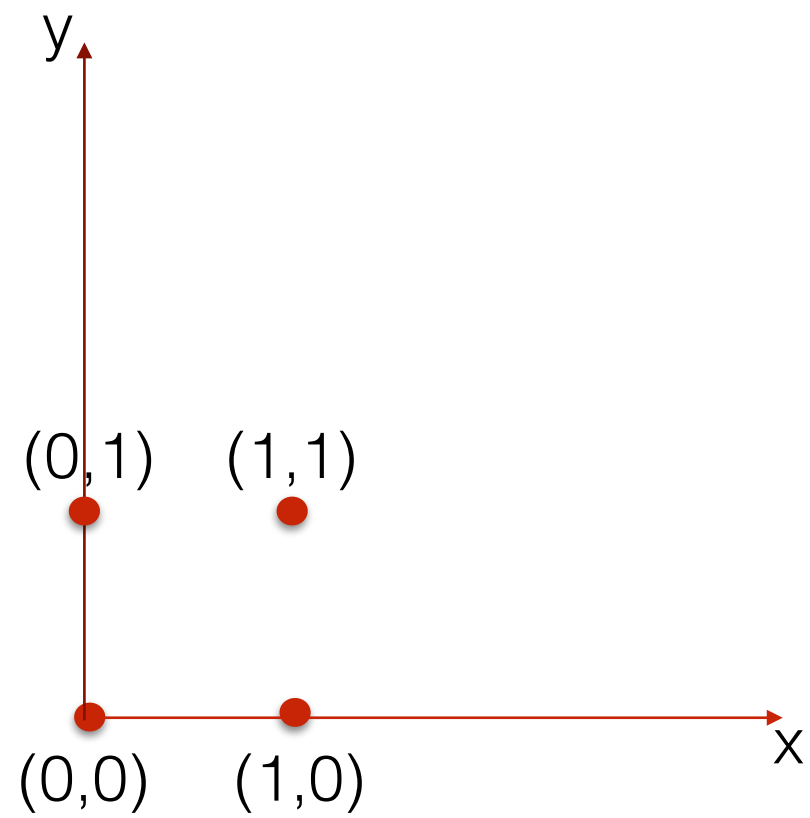
$$p = (x_1x_2x_3\dots x_k, y_1y_2y_3\dots y_k)$$

- Define the Z-index of a point

$$Z_index : \{0,\dots,2^k-1\} \times \{0,\dots,2^k-1\} \longrightarrow \{0,\dots,2^{2k}-1\}$$

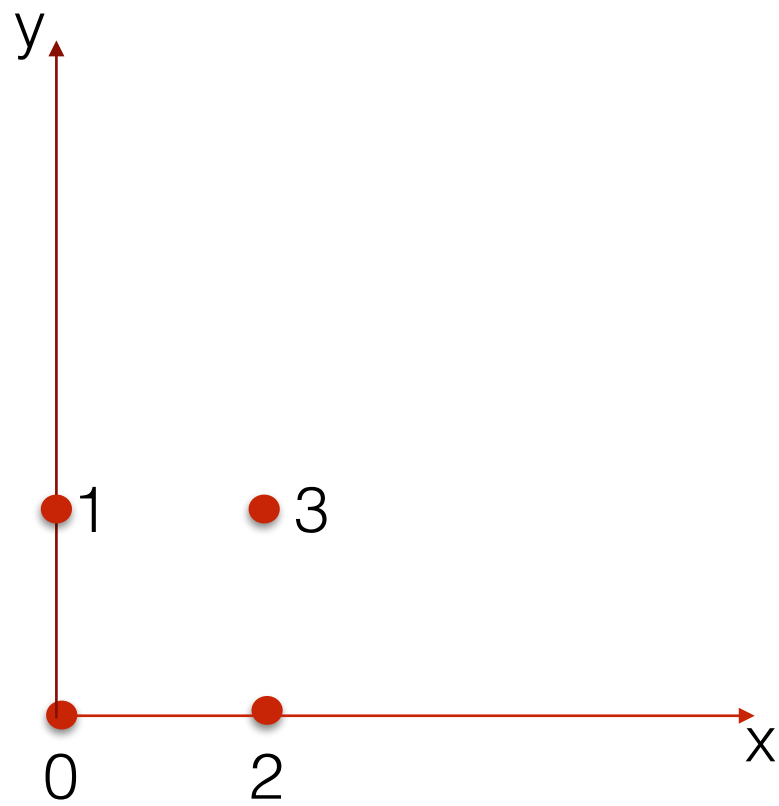
$$Z_index(p) = x_1y_1x_2y_2\dots x_ky_k$$

k=1 bit



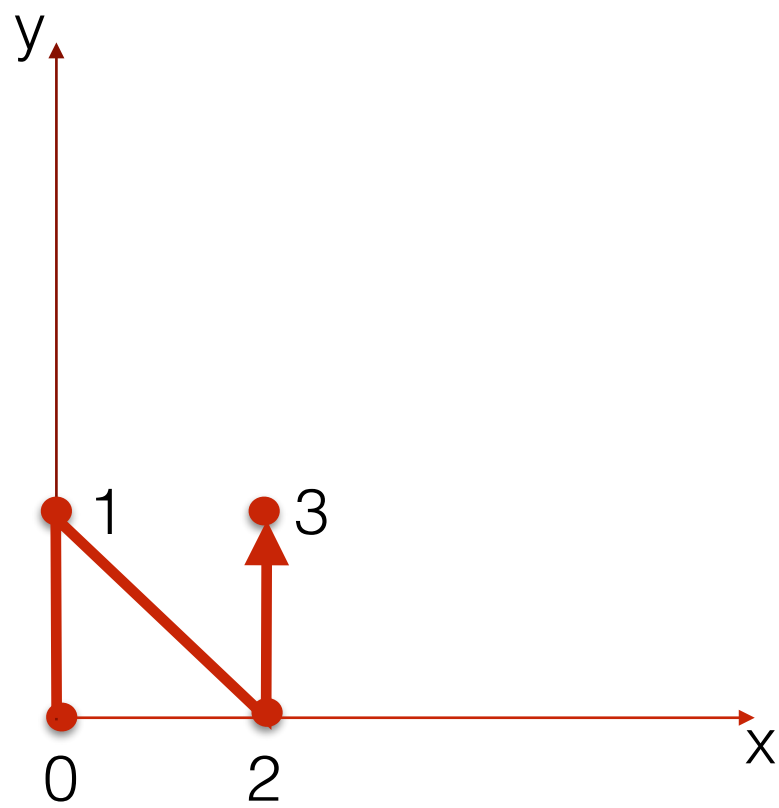
p	Z_index(p)
(0,0)	0
(0,1)	1
(1,0)	2
(1,1)	3

k=1 bit



p	Z_index(p)
(0,0)	0
(0,1)	1
(1,0)	2
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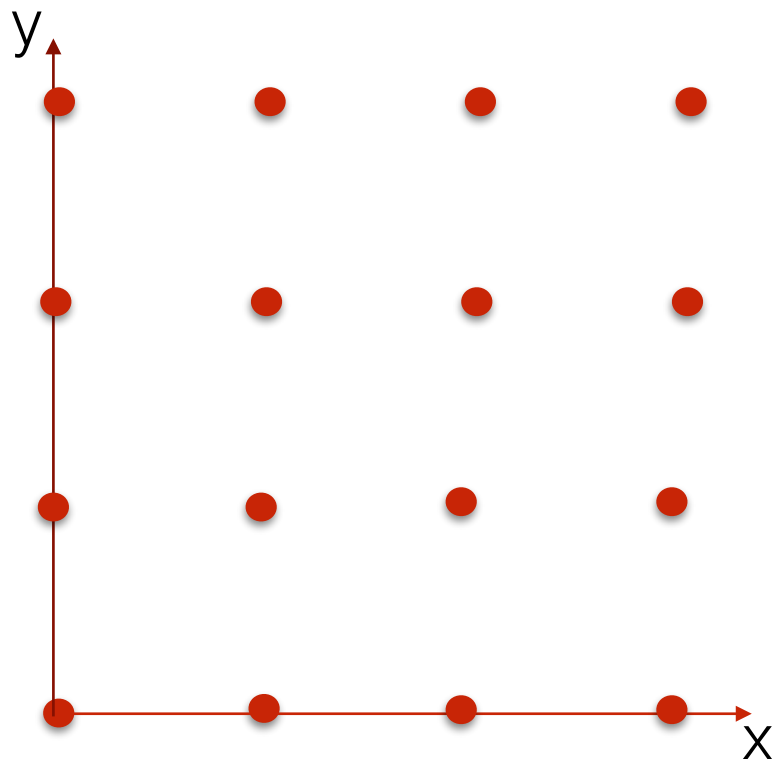
k=1 bit



p	Z_index(p)
(0,0)	0
(0,1)	1
(1,0)	2
(1,1)	3

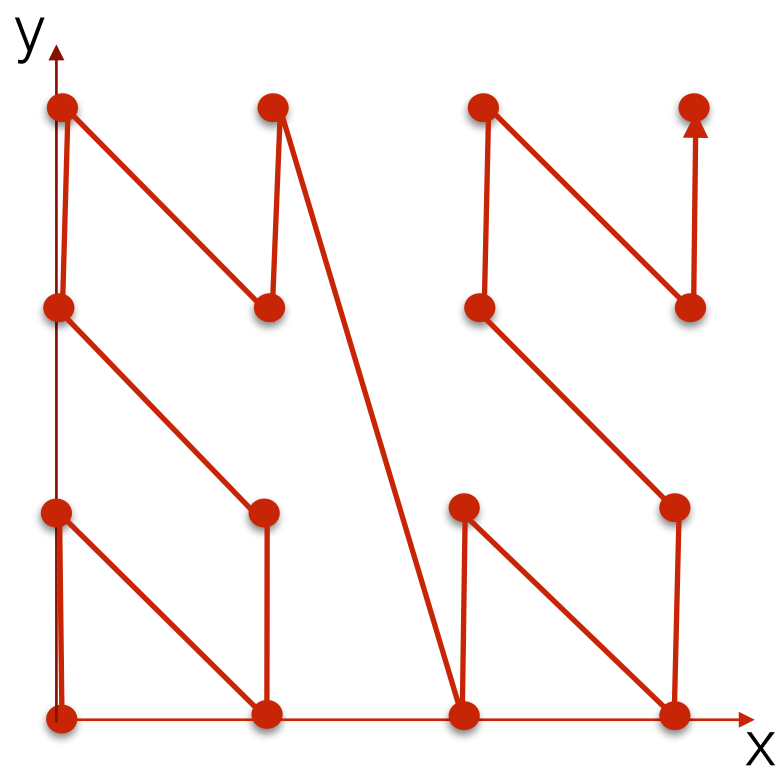
k=2 bits

Find the Z-order!

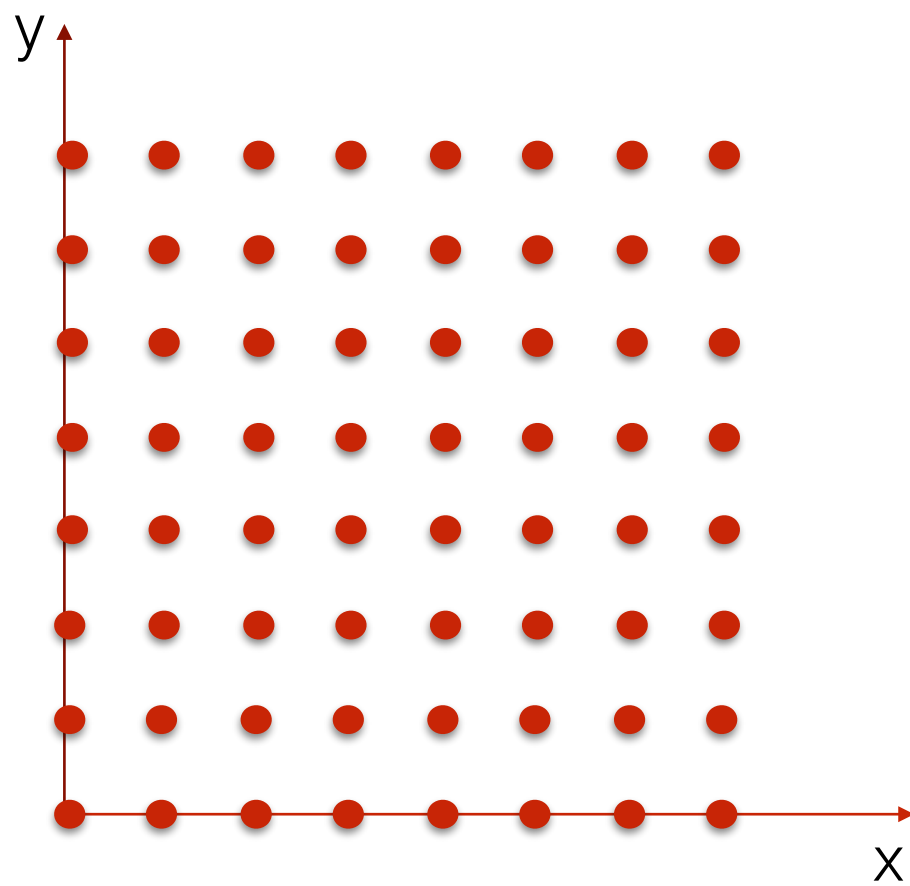


p	Z_index(p)
(00,00)	0000=0
(00,01)	0001=1
(00,10)	0100=4
(00,11)	0101=5
(01,00)	
(01,01)	
(01,10)	
(01,11)	
(10,00)	
(10,01)	
(10,10)	
(10,11)	
(11,00)	
(11,01)	
(11,10)	
(11,11)	

k=2 bits



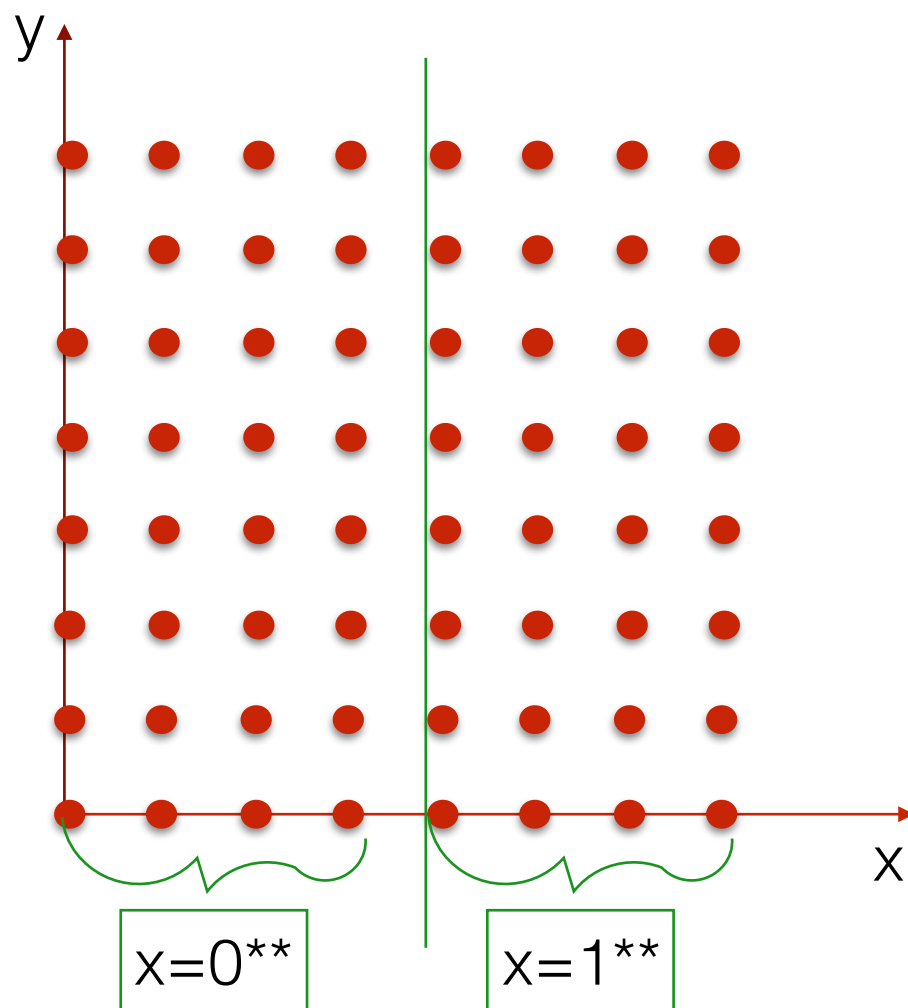
k=3 bits



Find the Z-order!

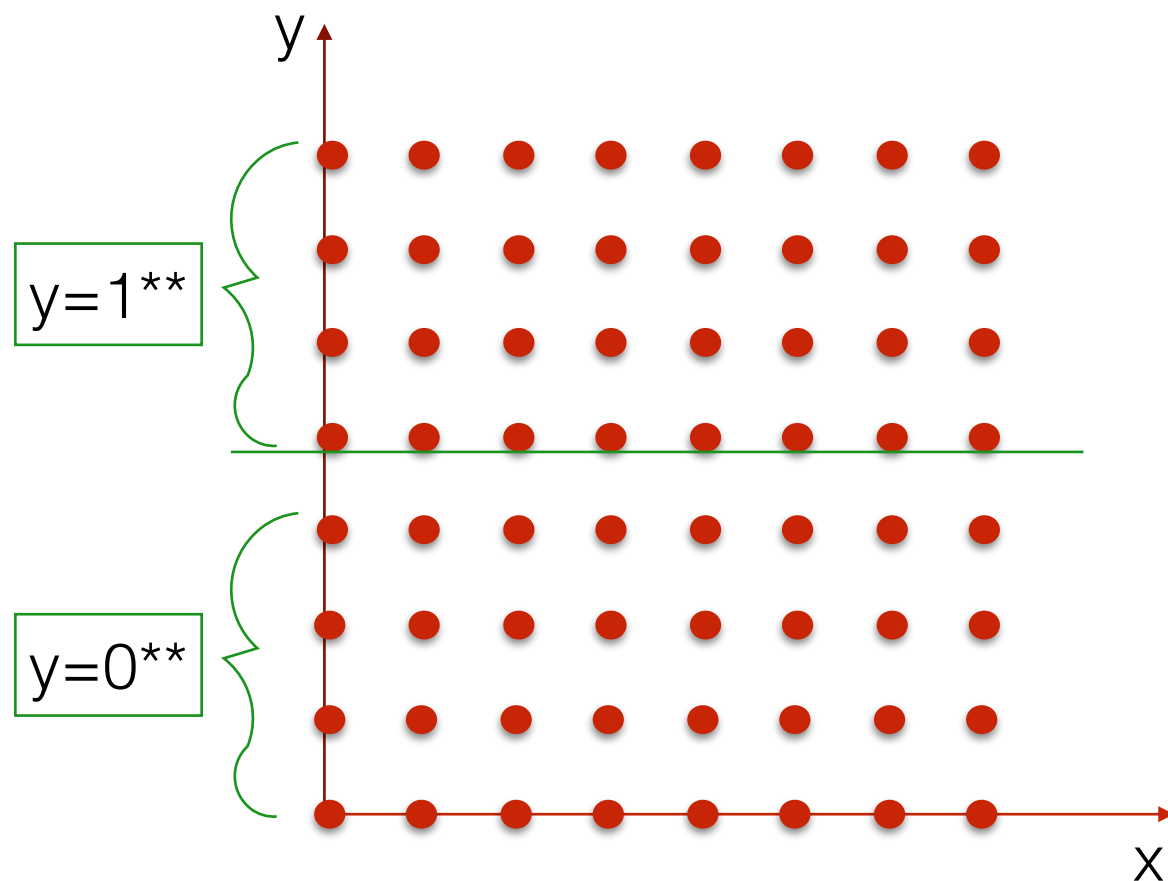
Computing the Z-index

- Consider an x-coordinate $x_1x_2x_3$ in the square $[0, \dots, 8)$
 - $x_1=0$ means the point will reside in the first half
 - $x_1=1$ means the point will reside in the second half



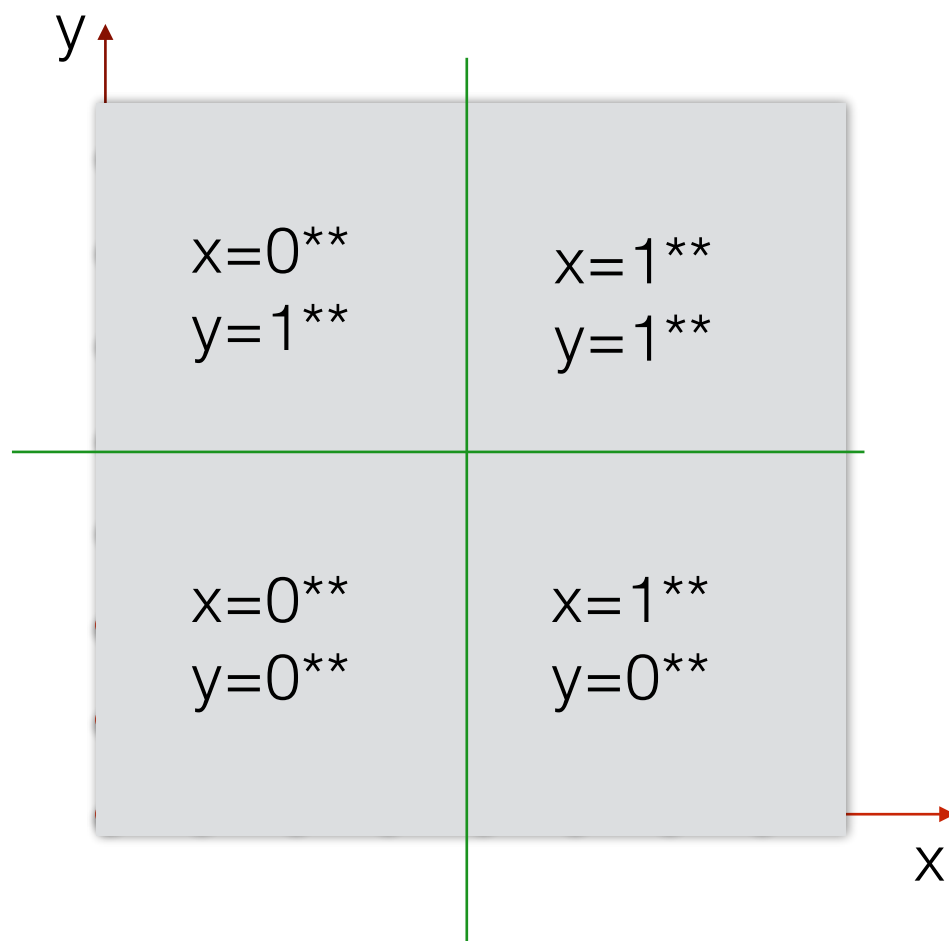
Computing the Z-index

- Consider an y-coordinate $y_1y_2y_3$ in the square $[0,\dots,8)$
 - $y_1=0$ means the point will reside in the first half
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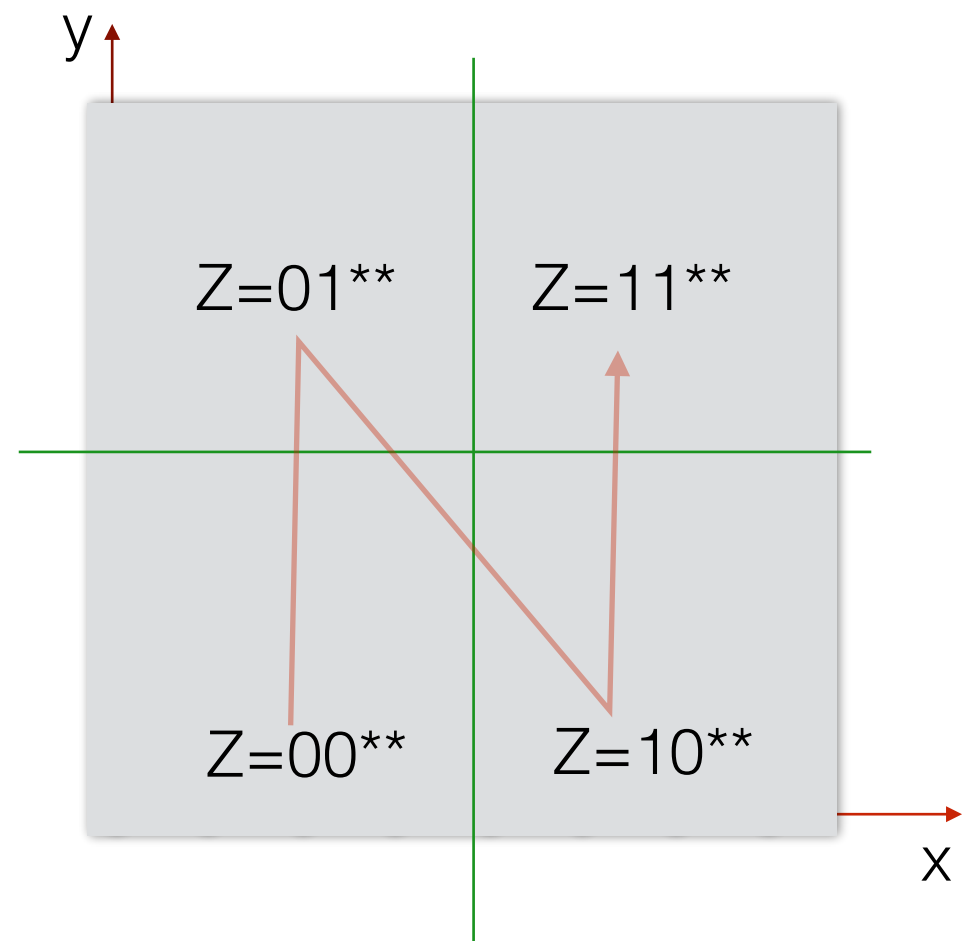
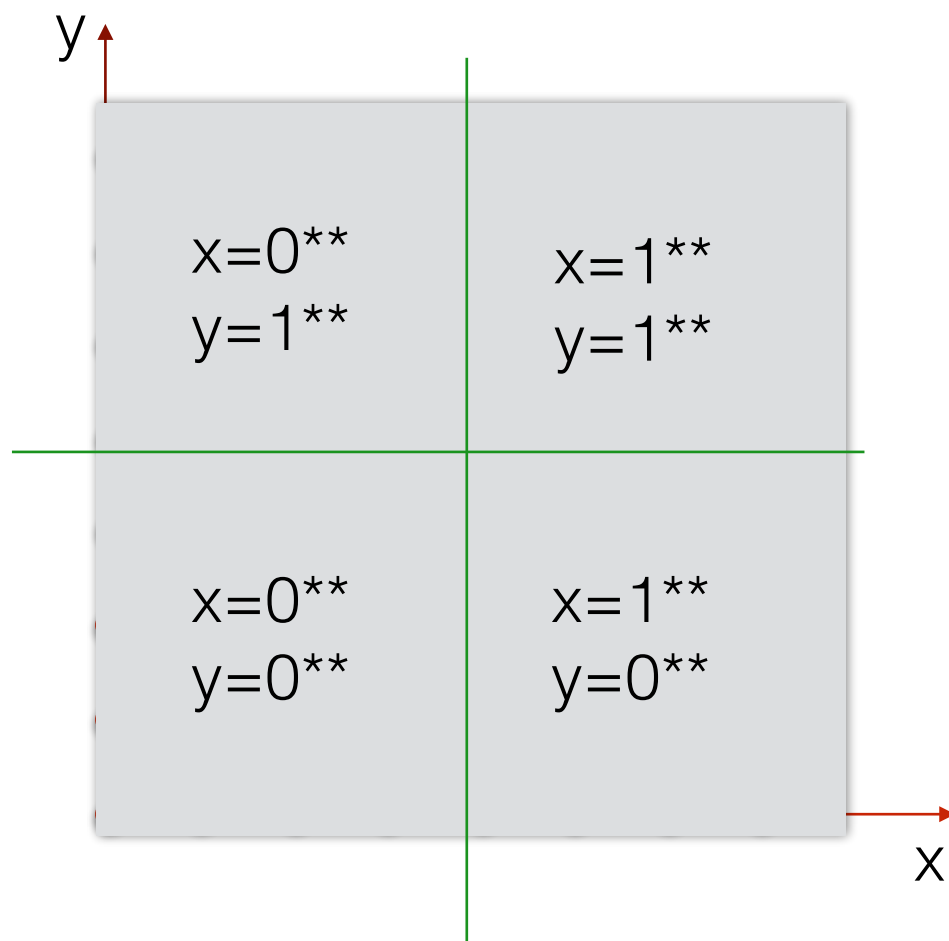
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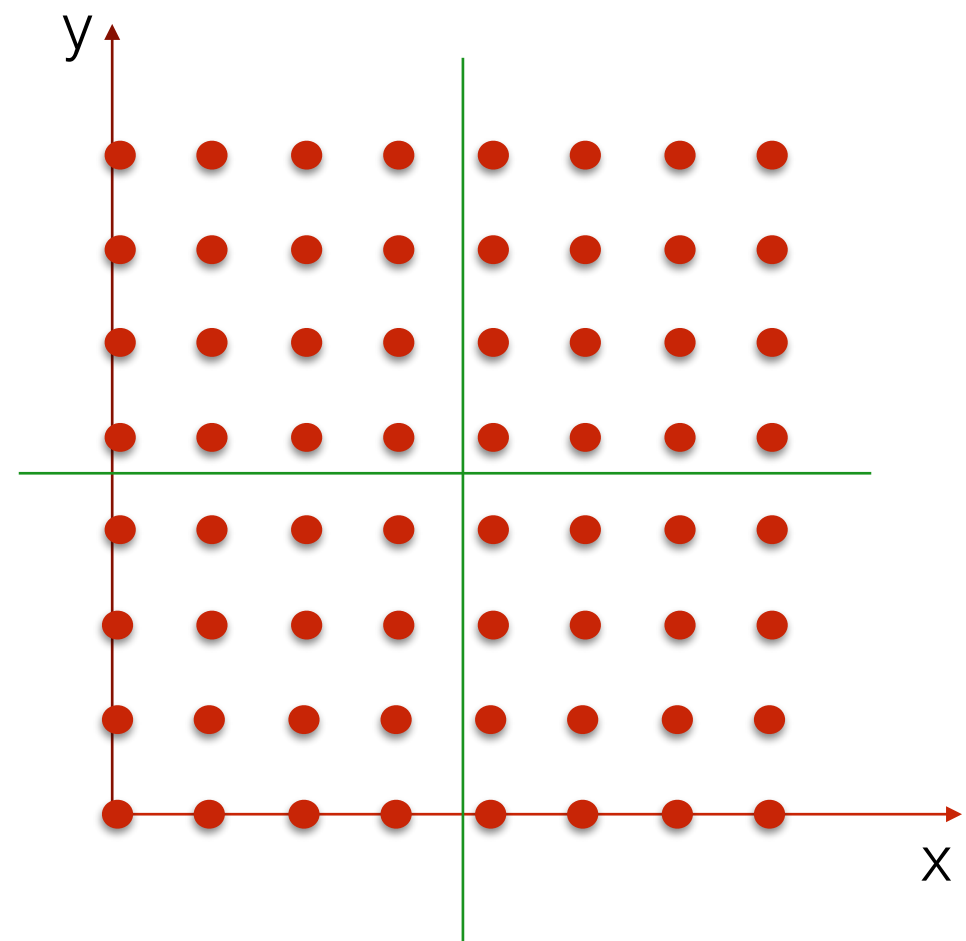
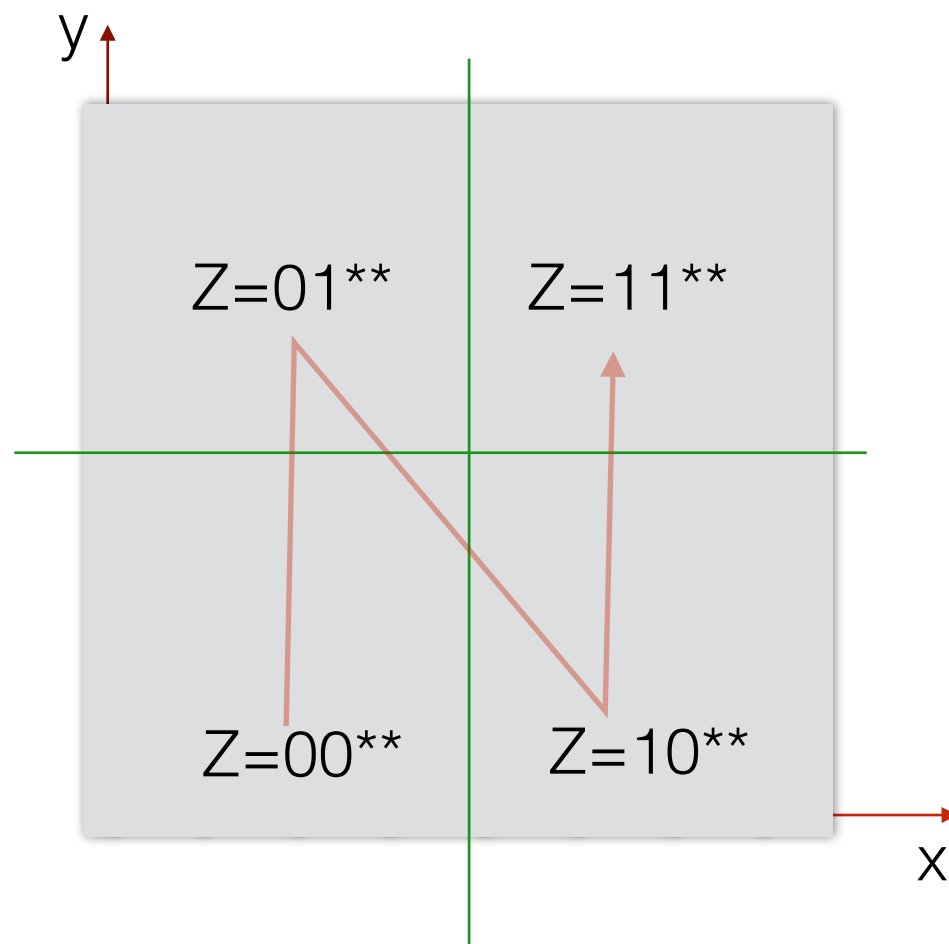
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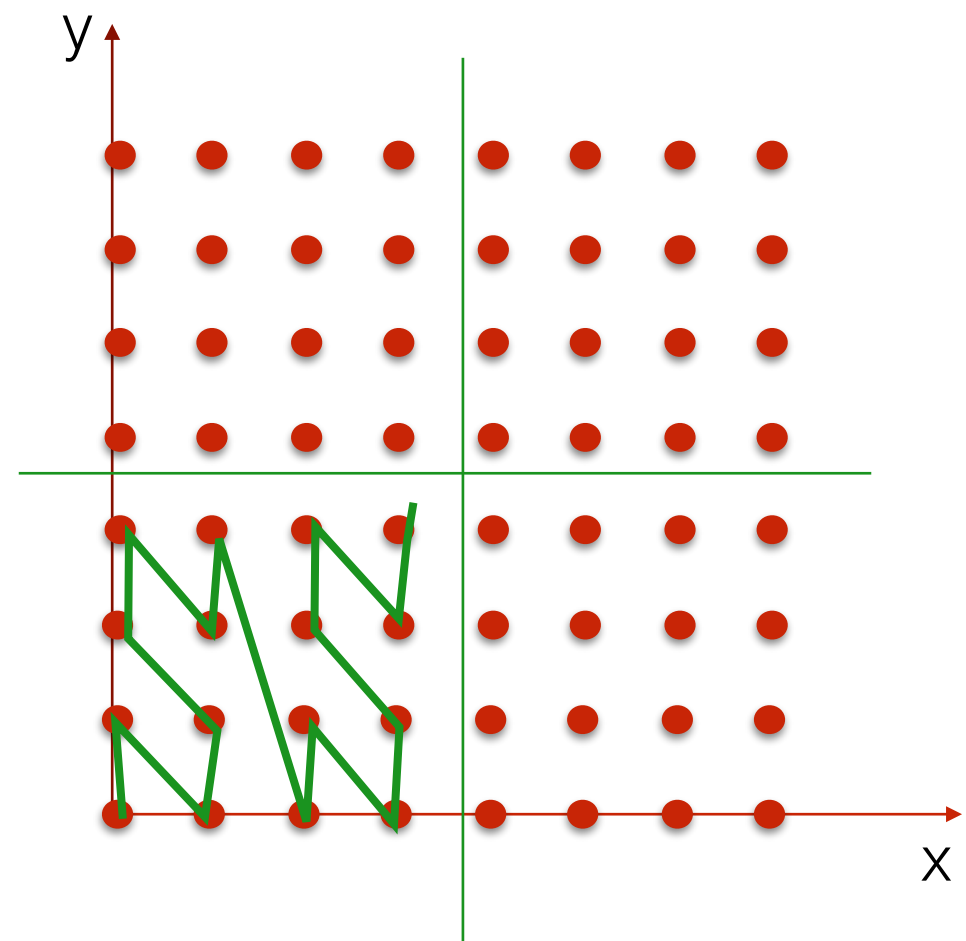
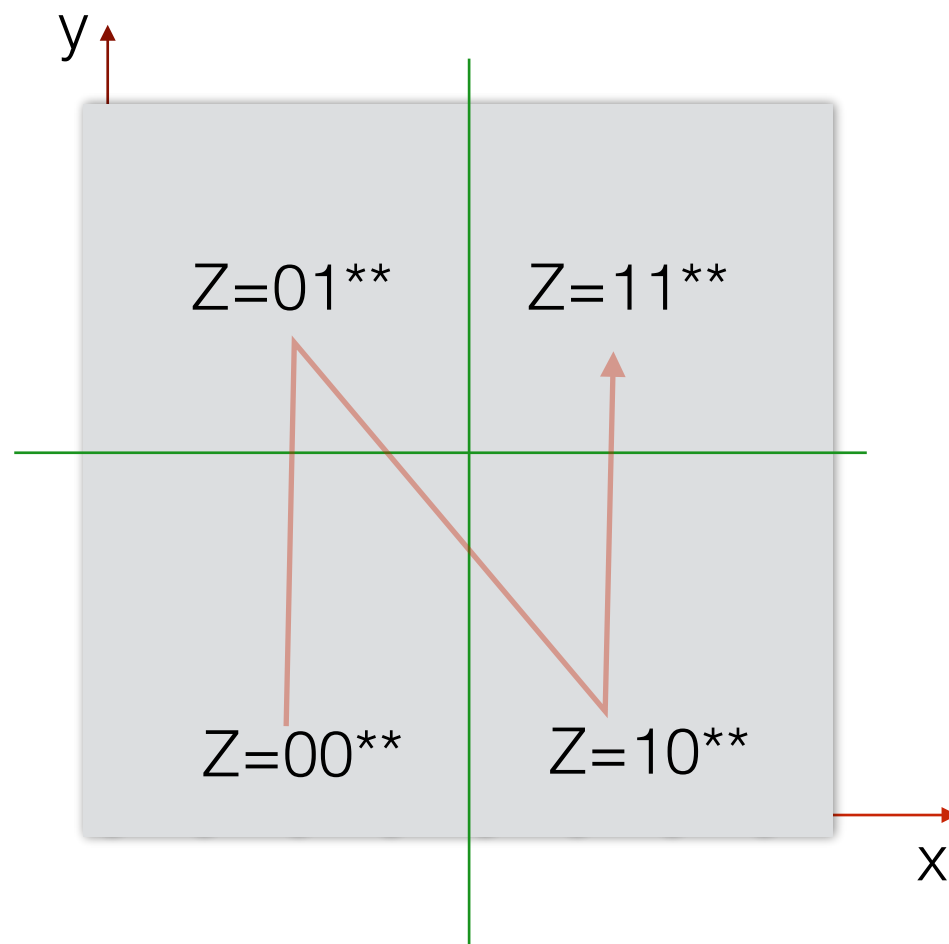
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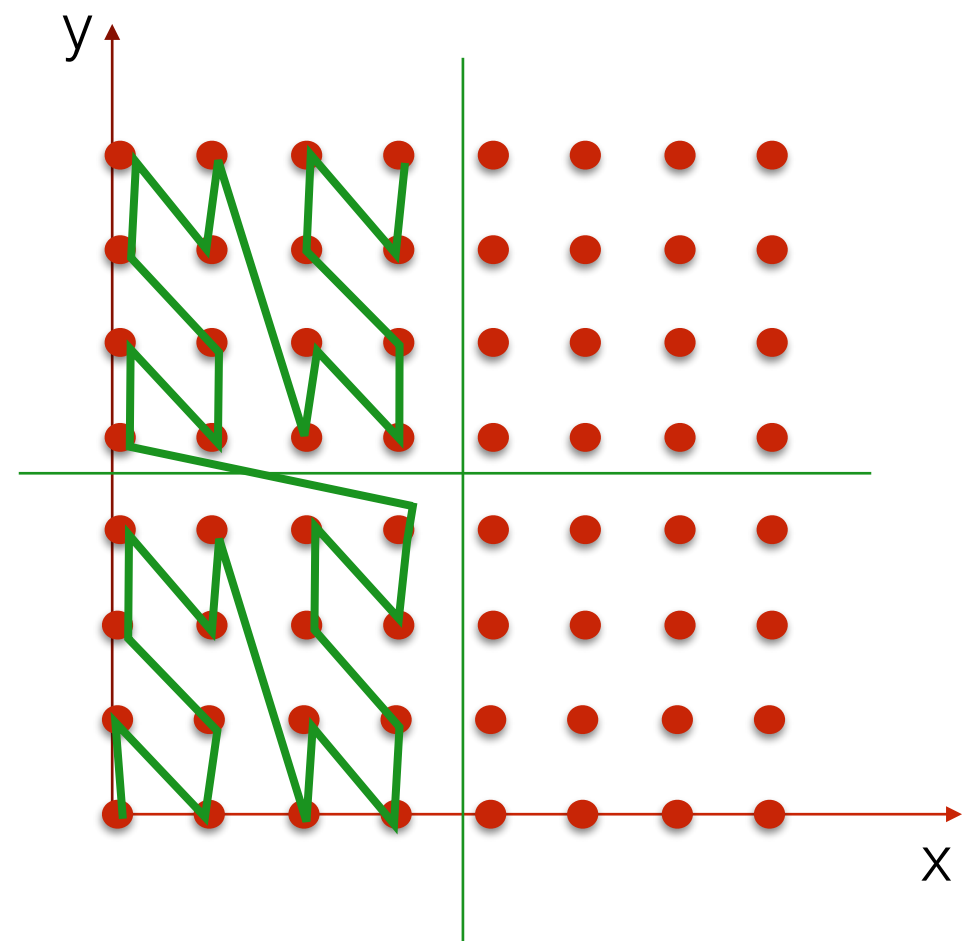
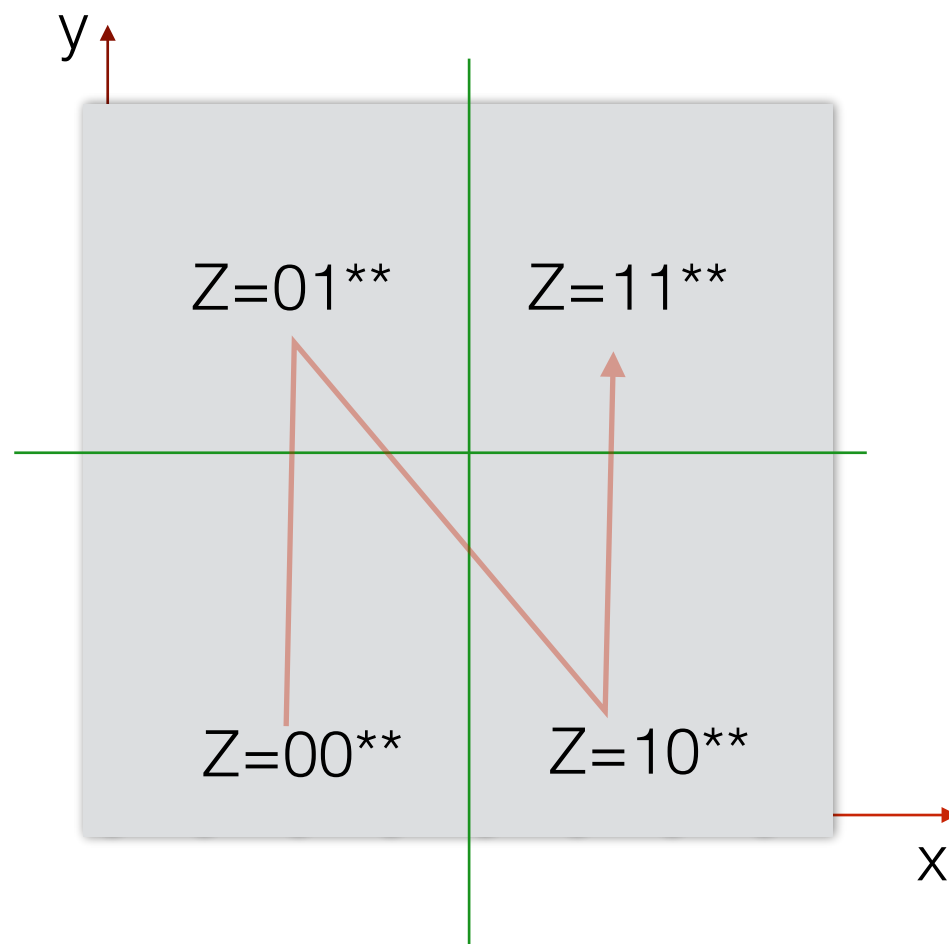
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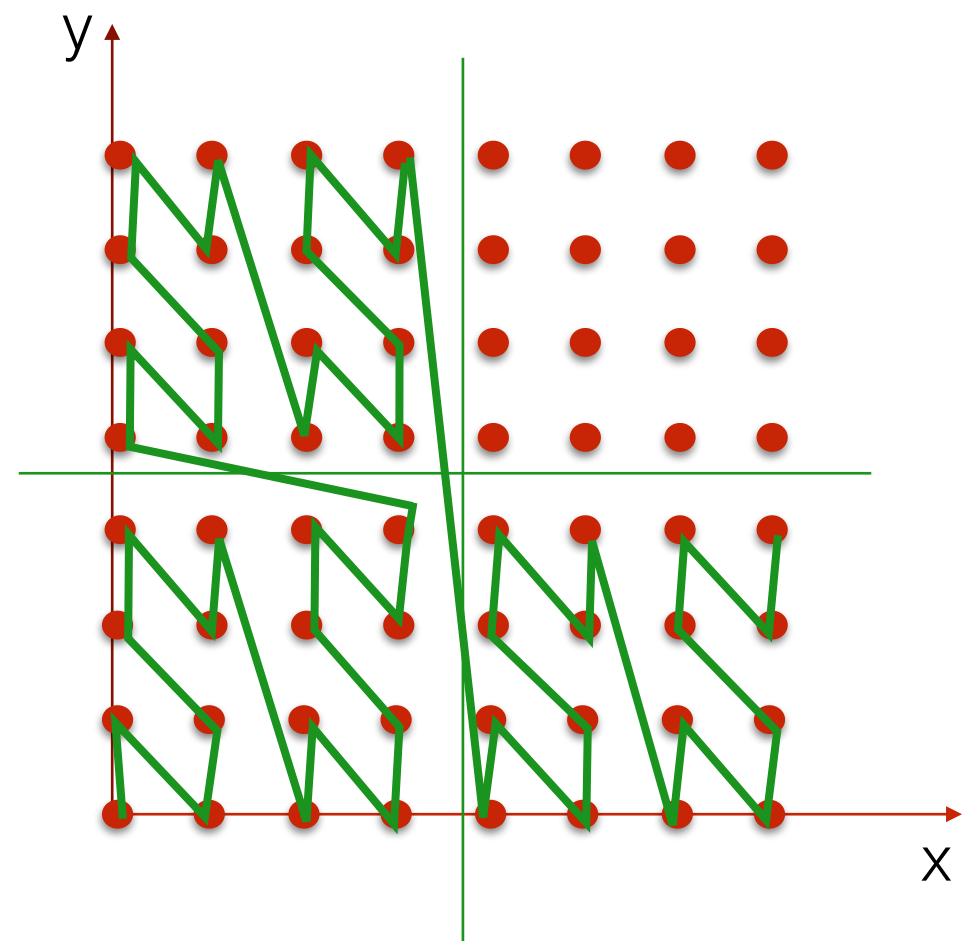
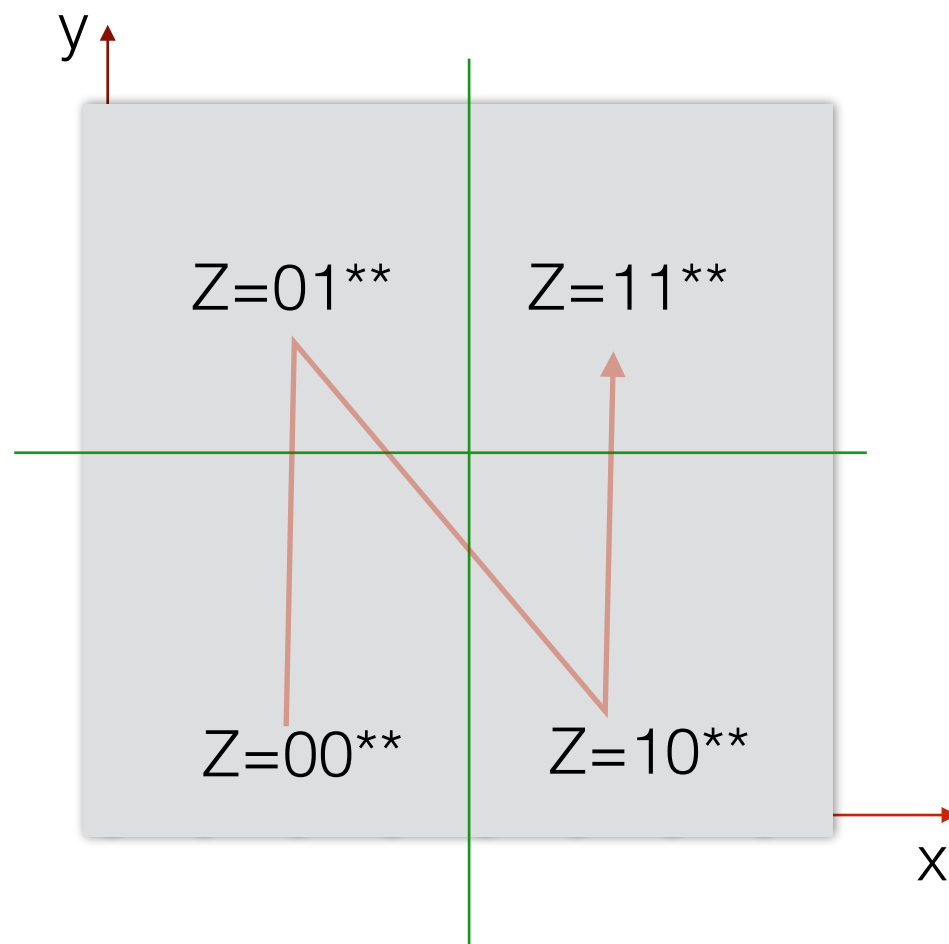
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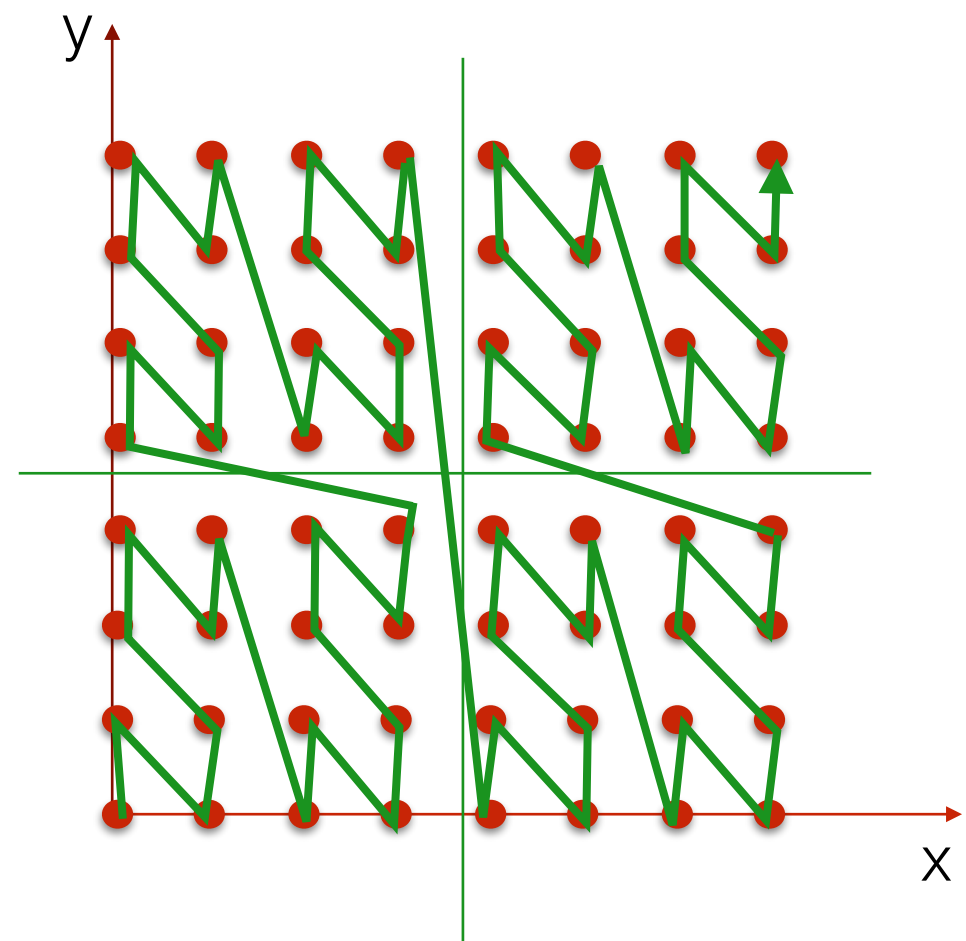
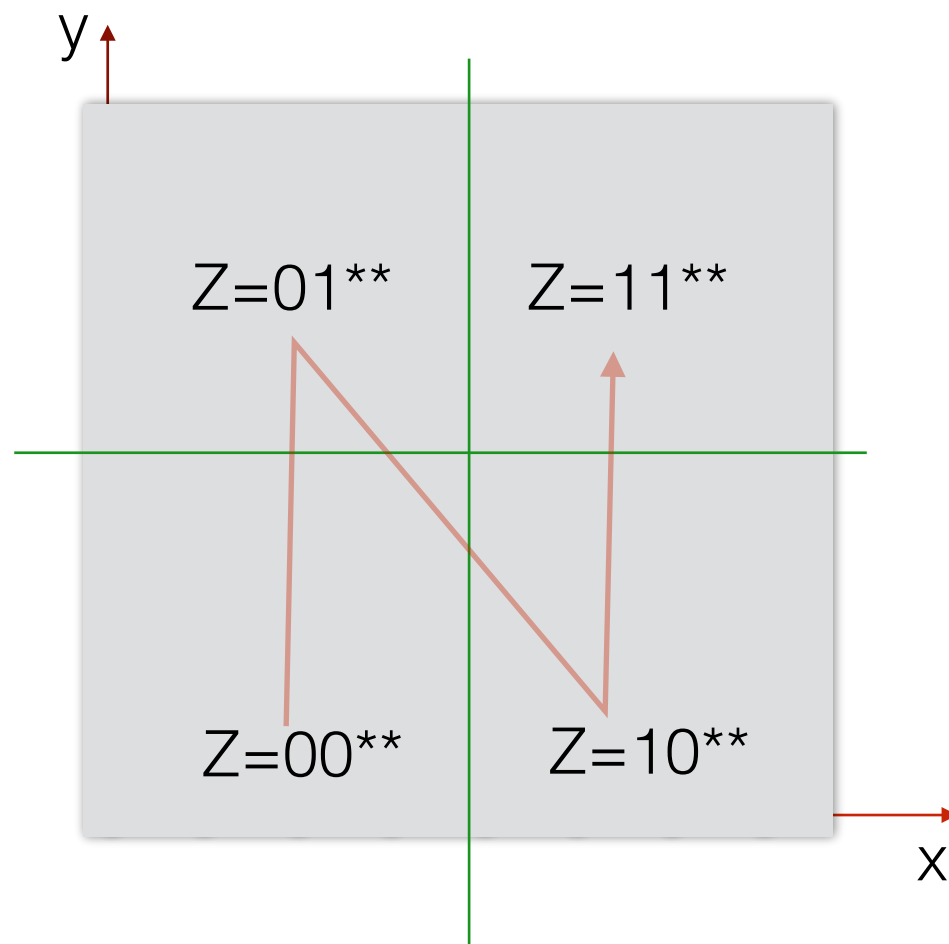
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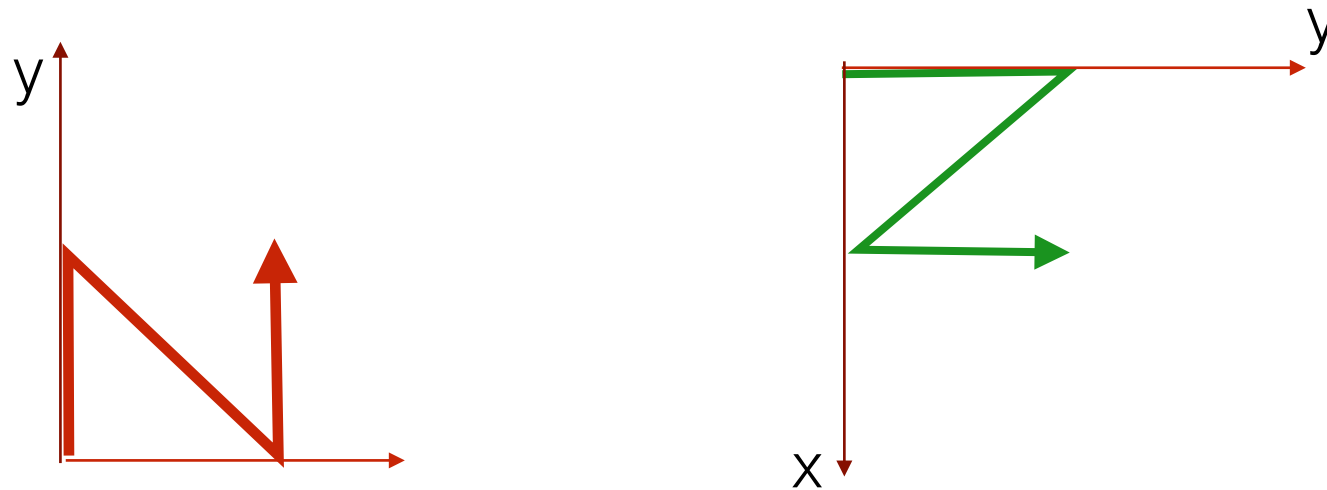
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Z-order space filling curves

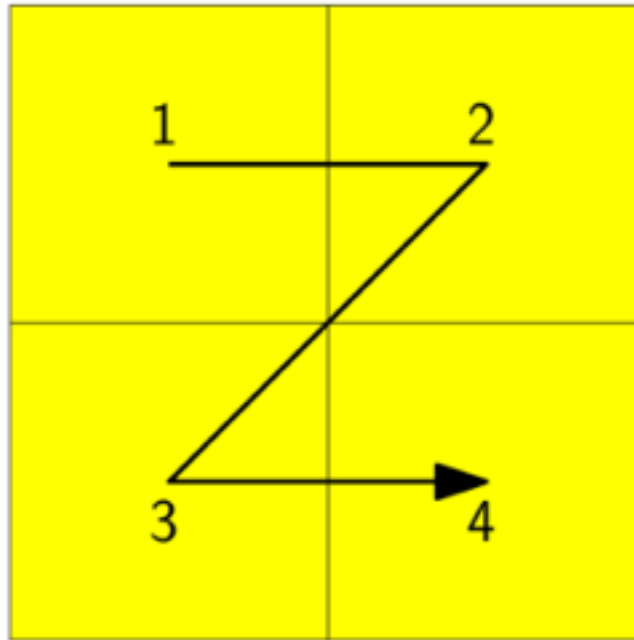
- Other Z-orders can be obtained similarly



- Can be extended to work with decimal numbers in $[0,1)$
 - make values positive (add smallest value)
 - divide all values by max value
 - \Rightarrow now we got values in $[0,1)$ $p=(.1100, .0101)$

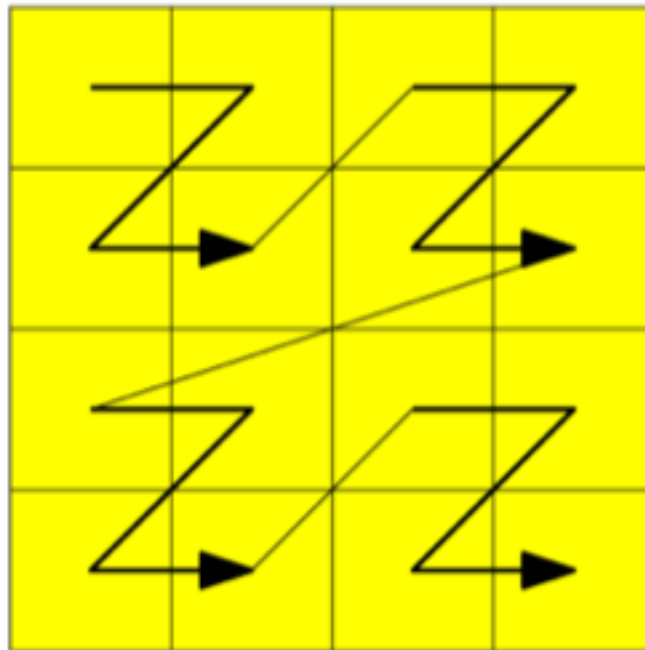
Z-order and quadtrees

visit quadrants recursively in this order: NW, NE, SW, SE



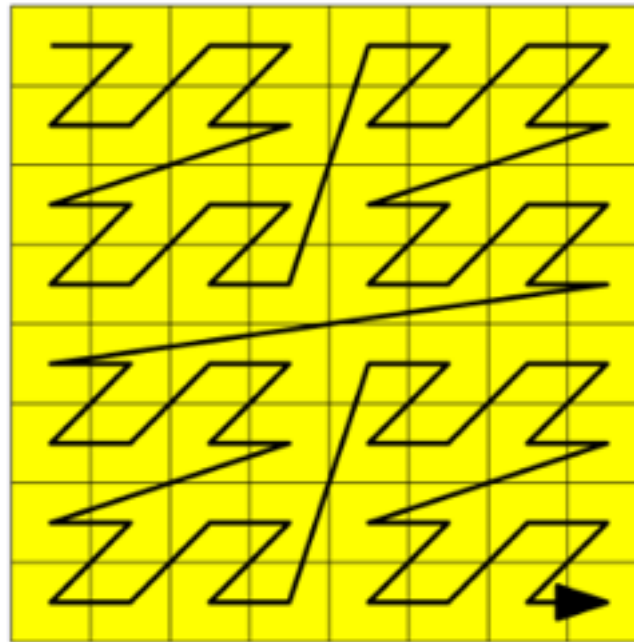
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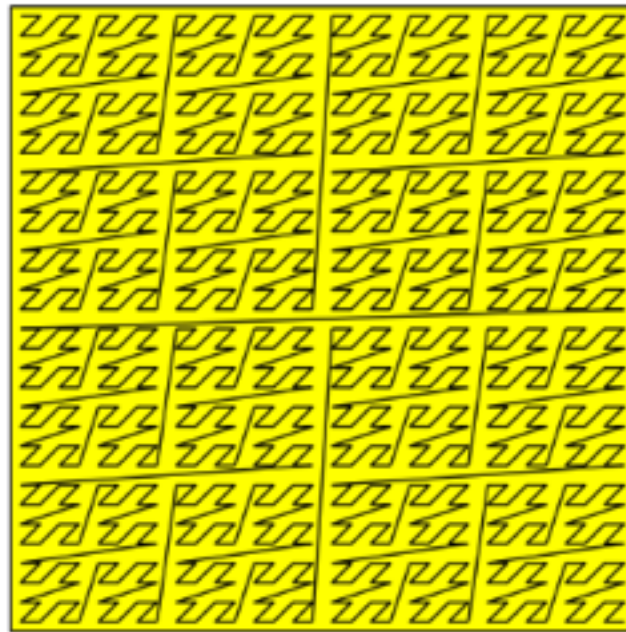
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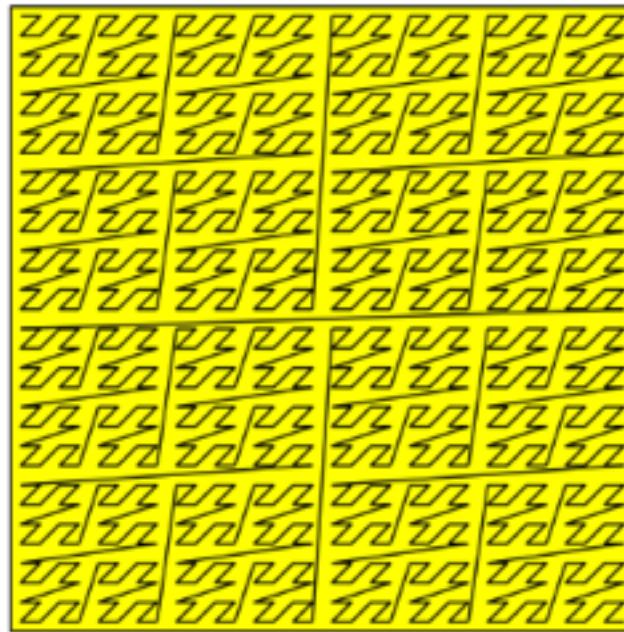
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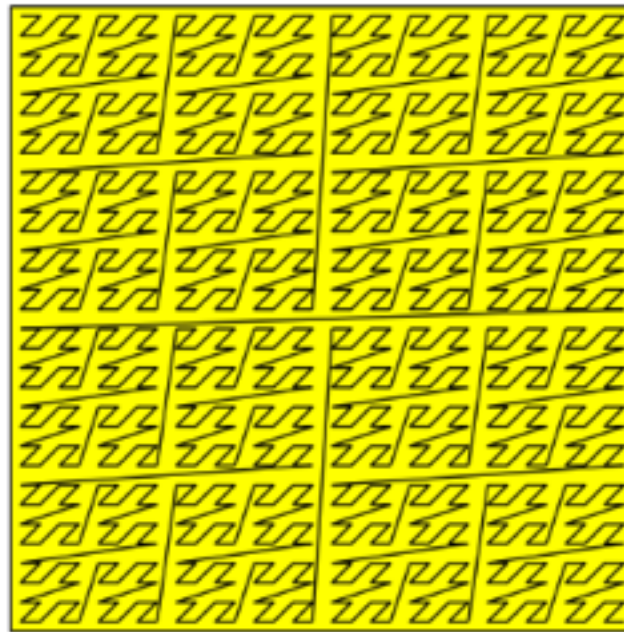
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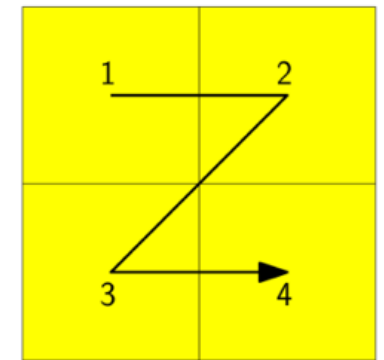
visit quadrants recursively in this order: NW, NE, SW, SE

Where is the very first point visited?

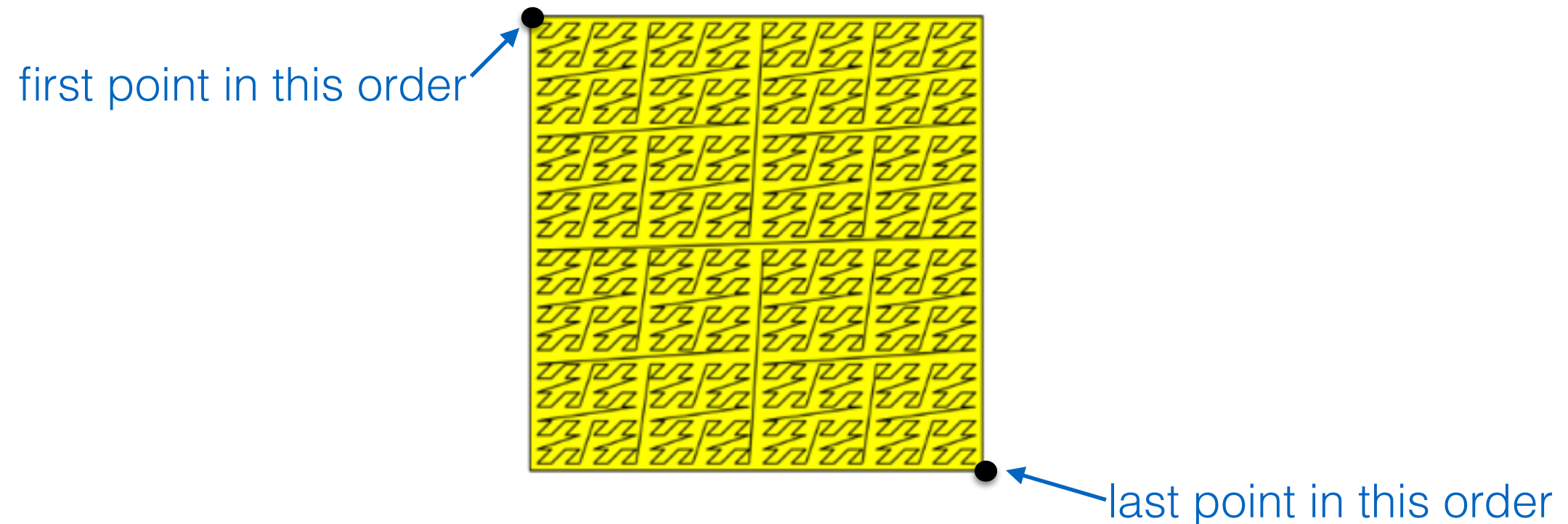


- At the limit, it will reach all points in the square ==> space filling curve

Z-order and quadtrees

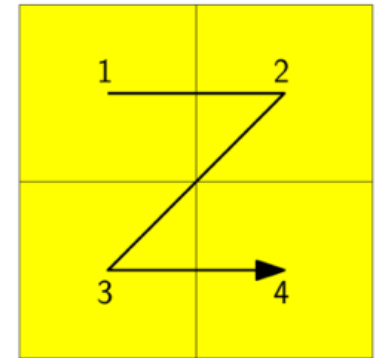


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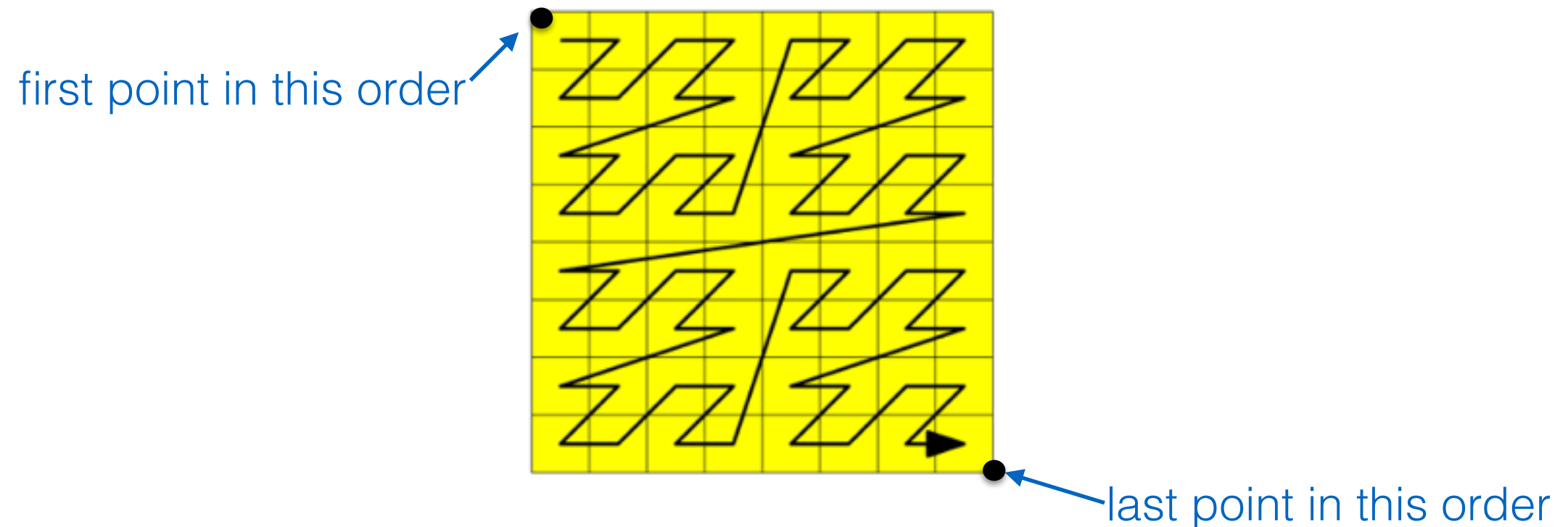


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Z-order and quadtrees



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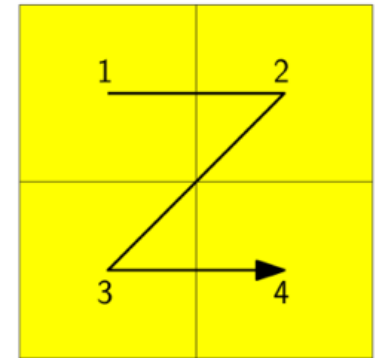
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first point in this order

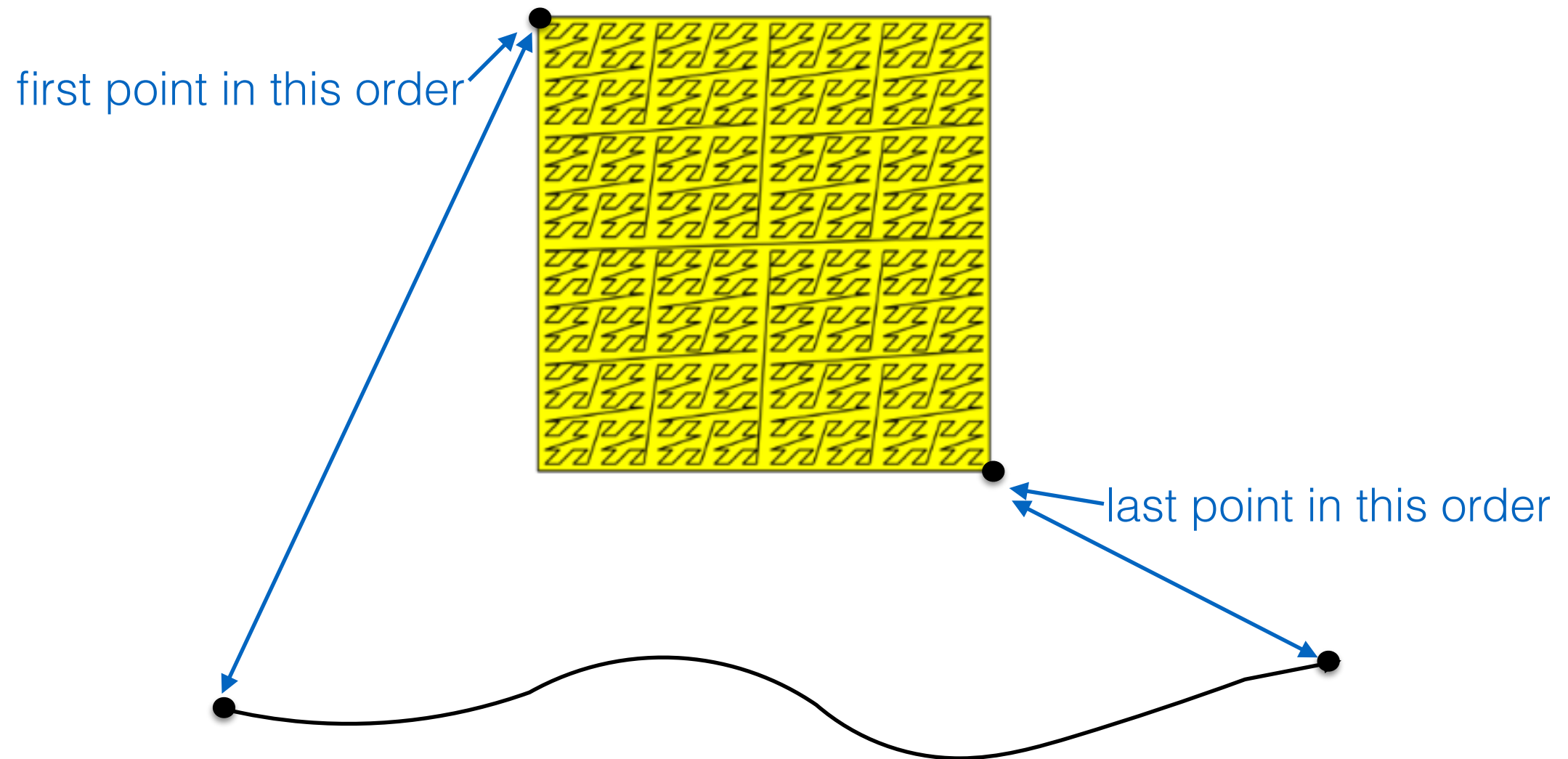
last point in this order

- Every point in the square will be visited by this curve
- $2D \implies 1D$

Z-order and quadtrees

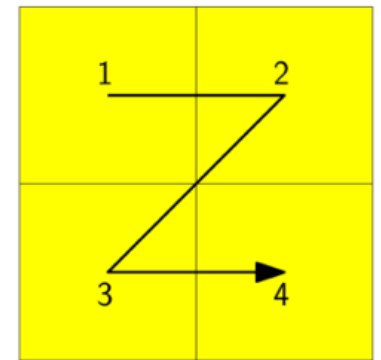


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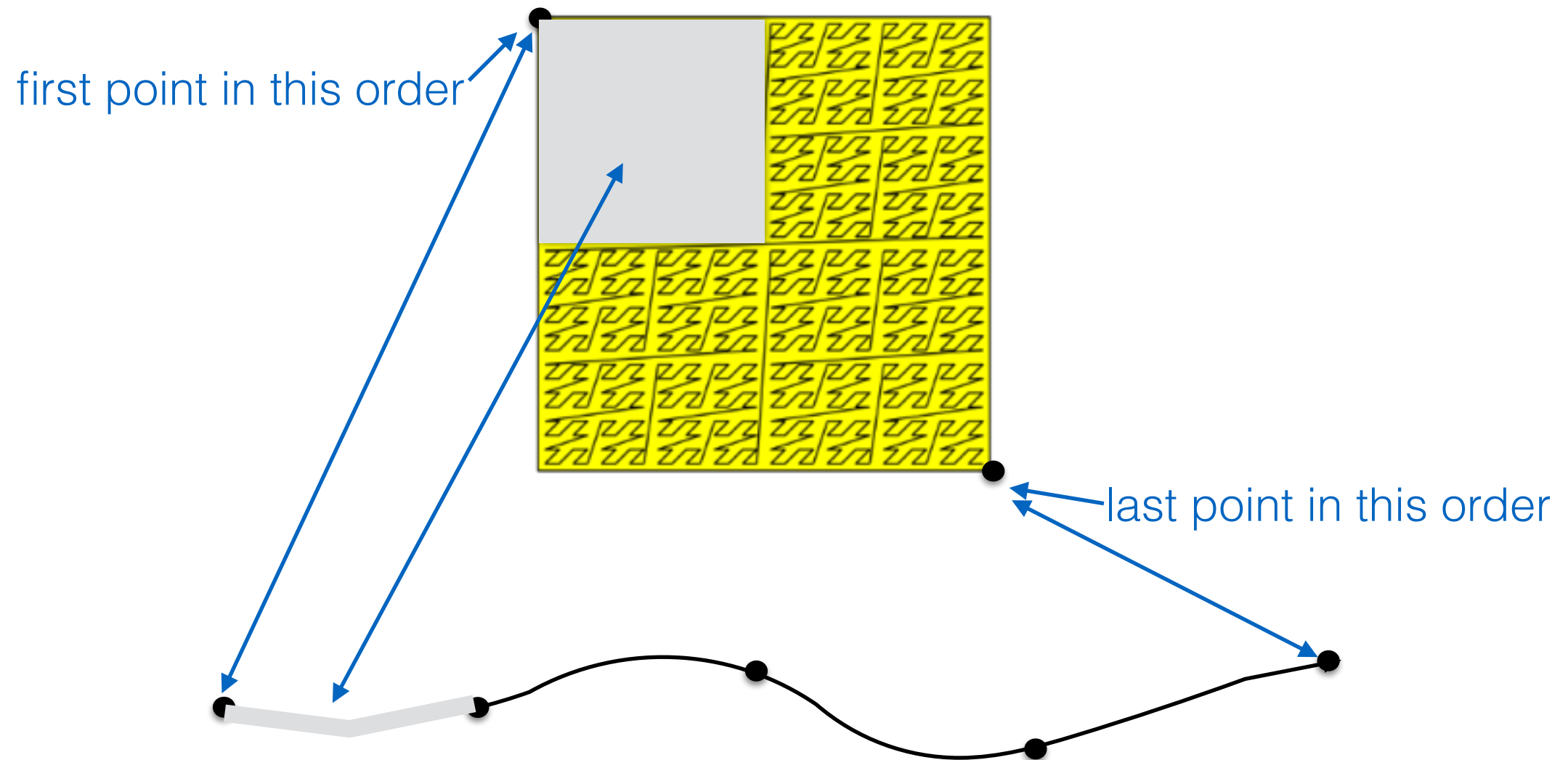


- We visit quadrant 1 before we visit quadrant 2:
==> All points in quadrant 1 comes before all points in quadrant 2

Z-order and quadtrees

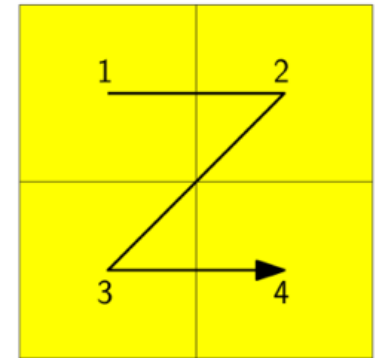


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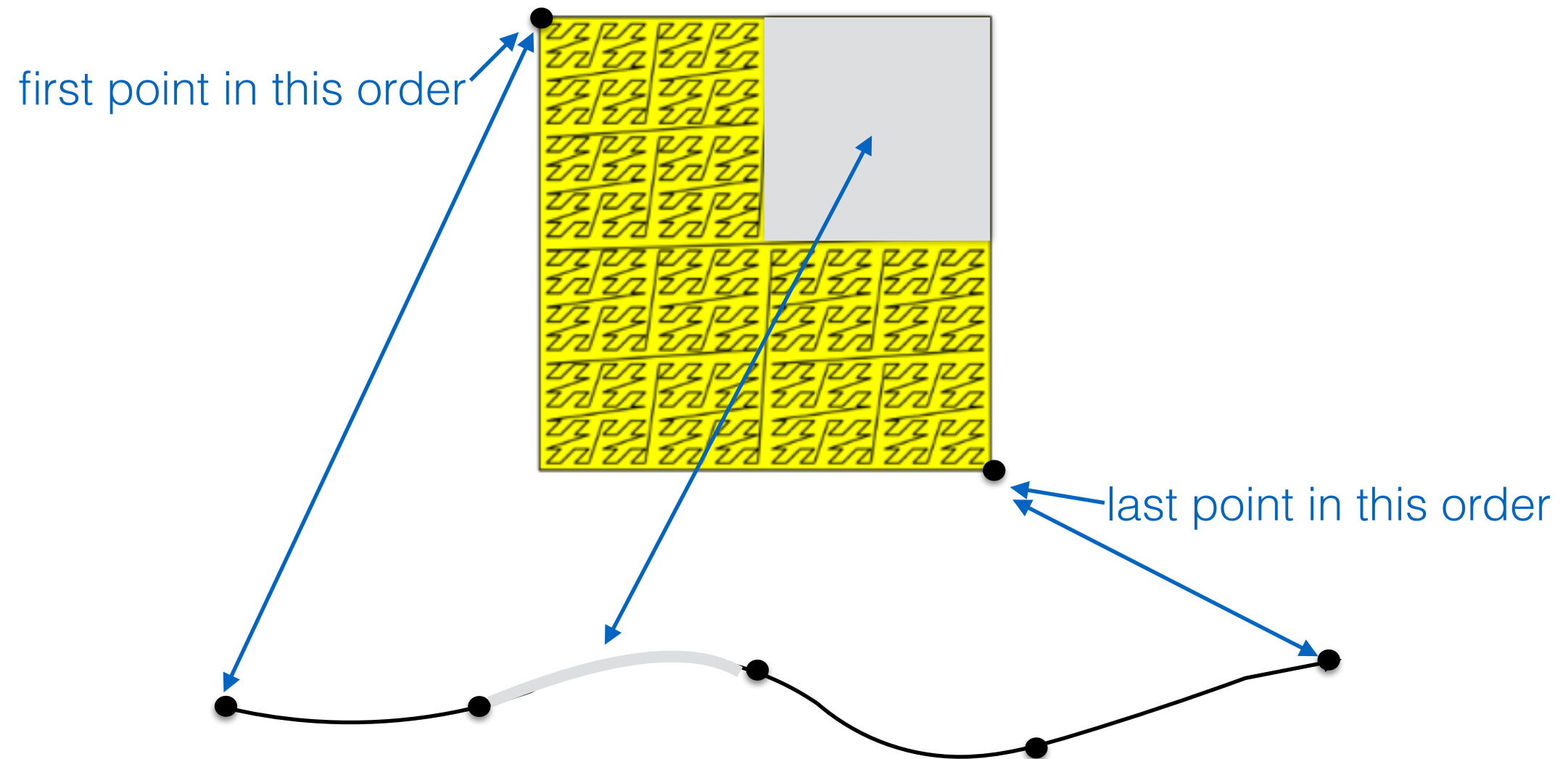


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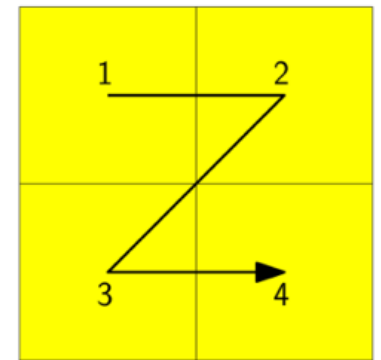
Z-order and quadtrees



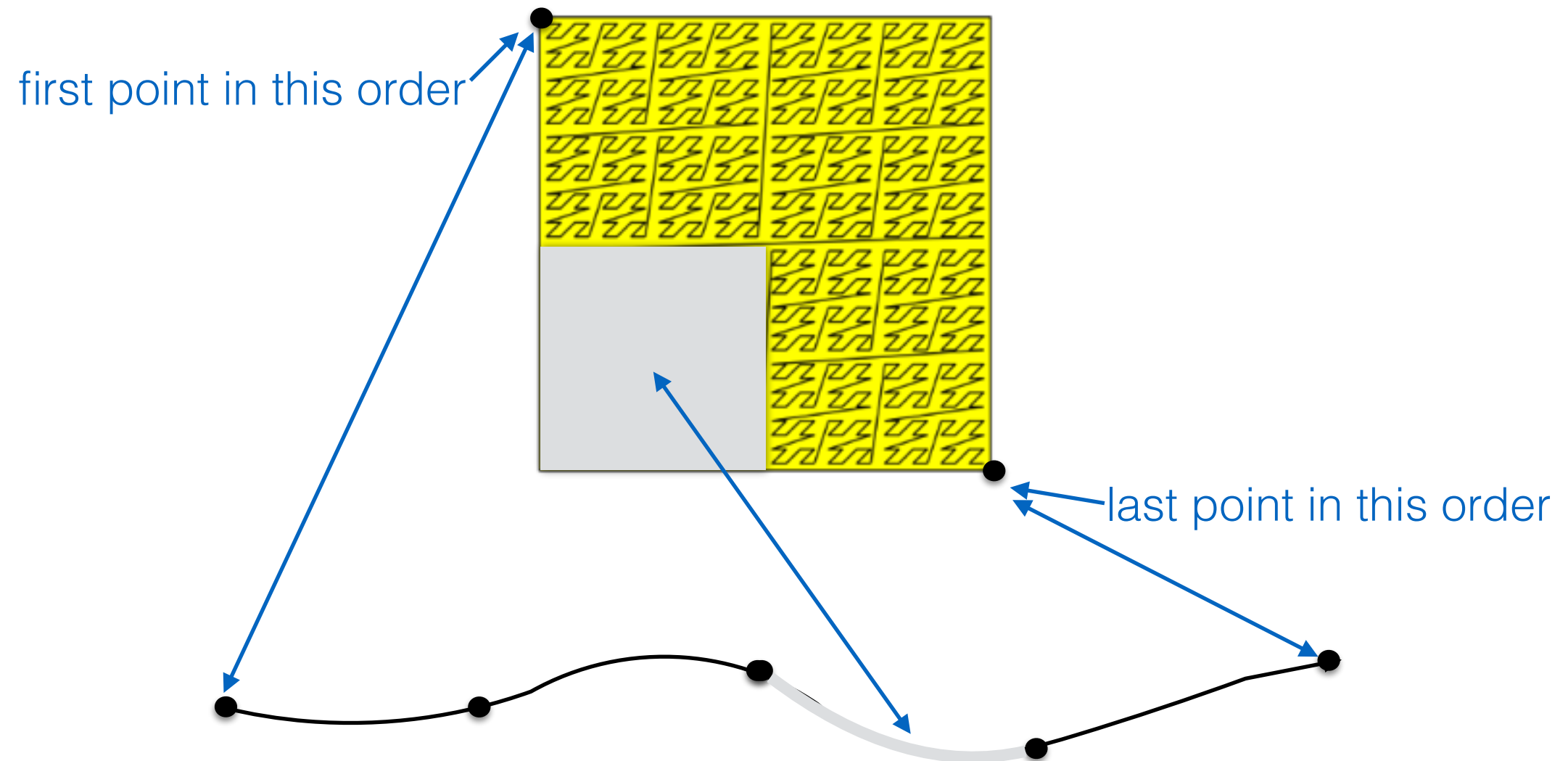
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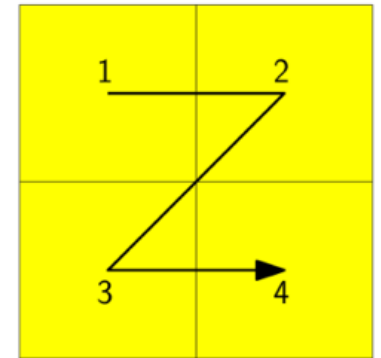
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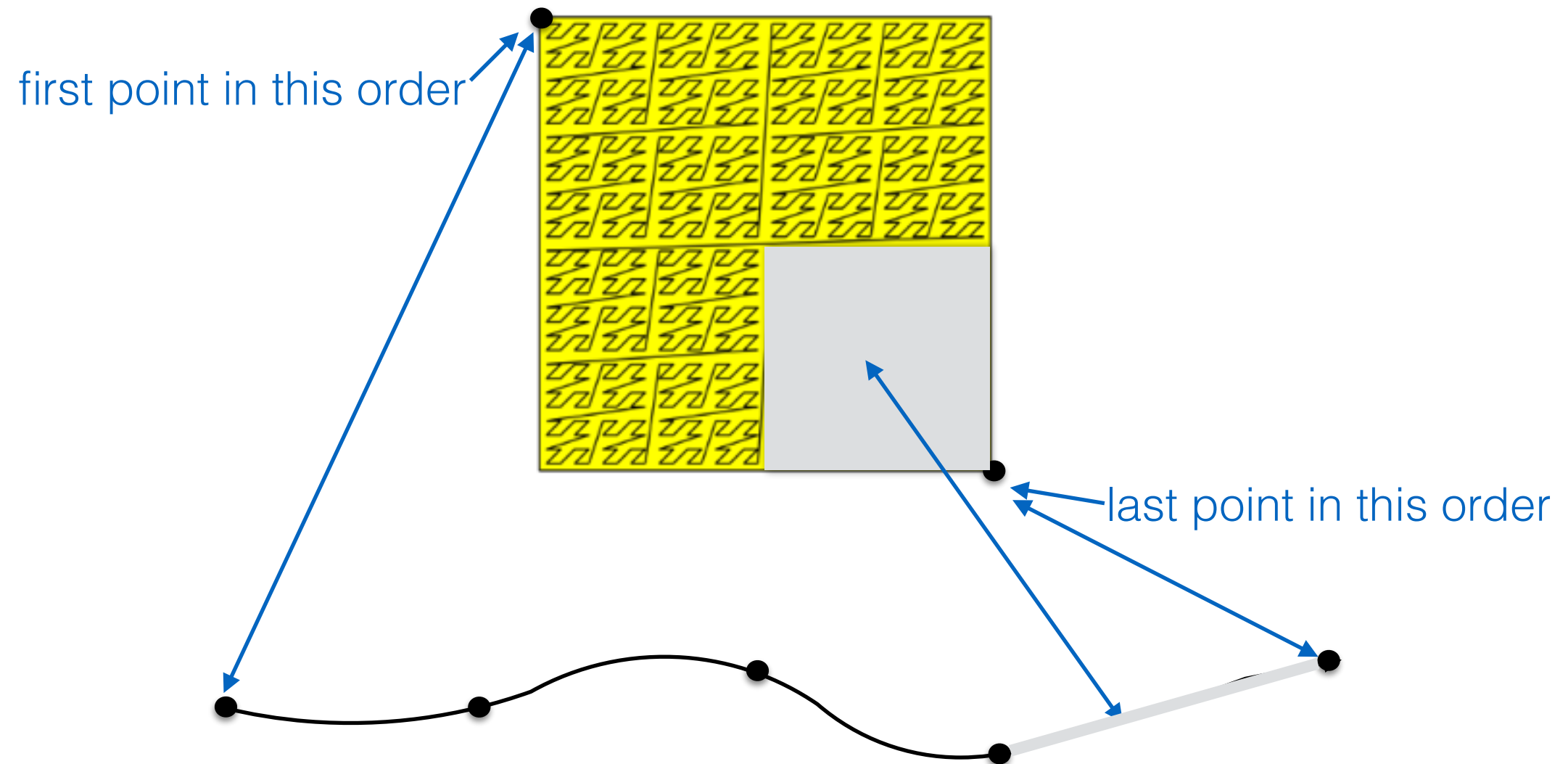
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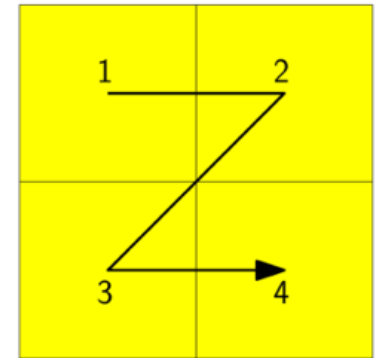
Z-order and quadtrees



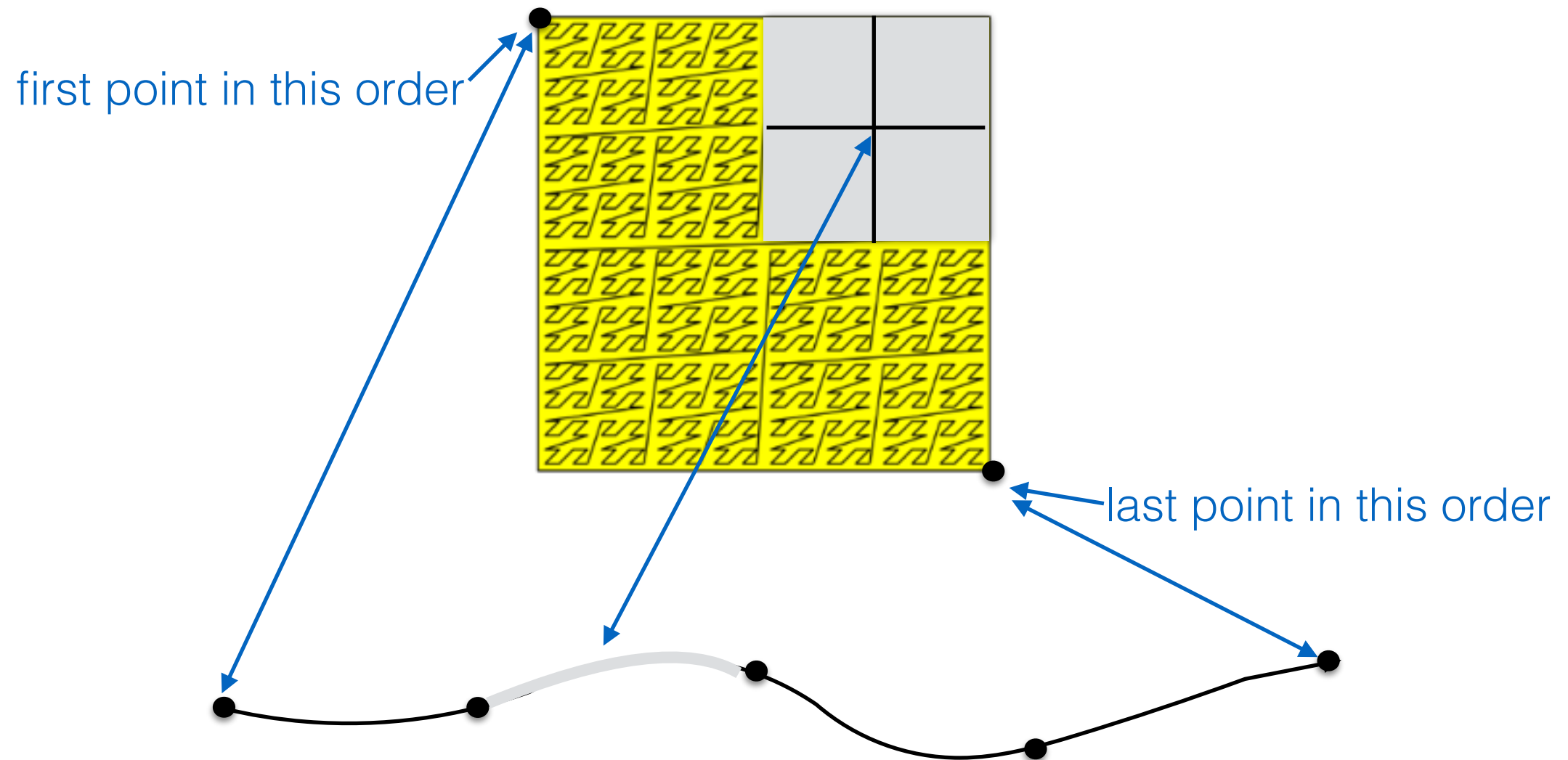
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Z-order and quadtrees

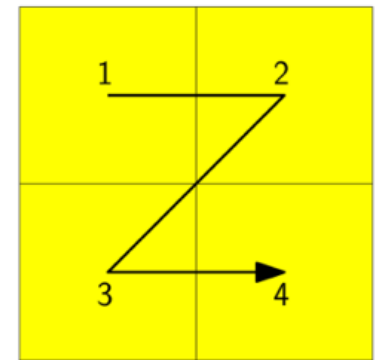


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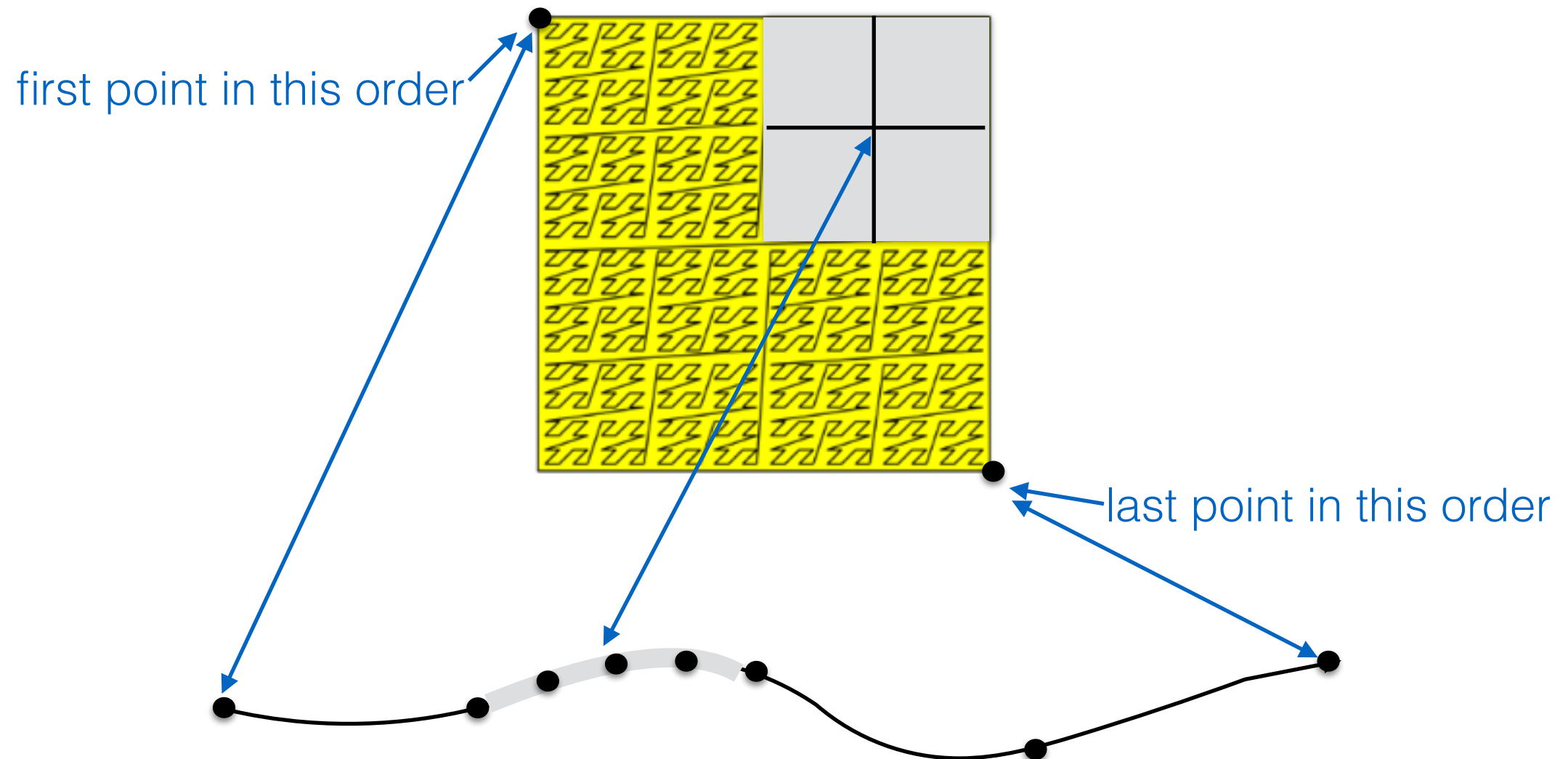


- and so on.....

Z-order and quadtrees

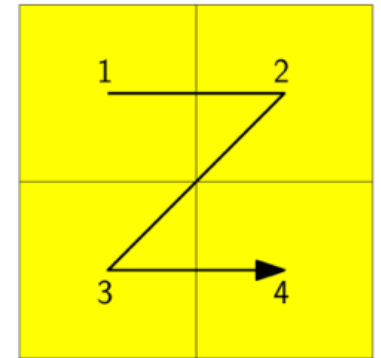


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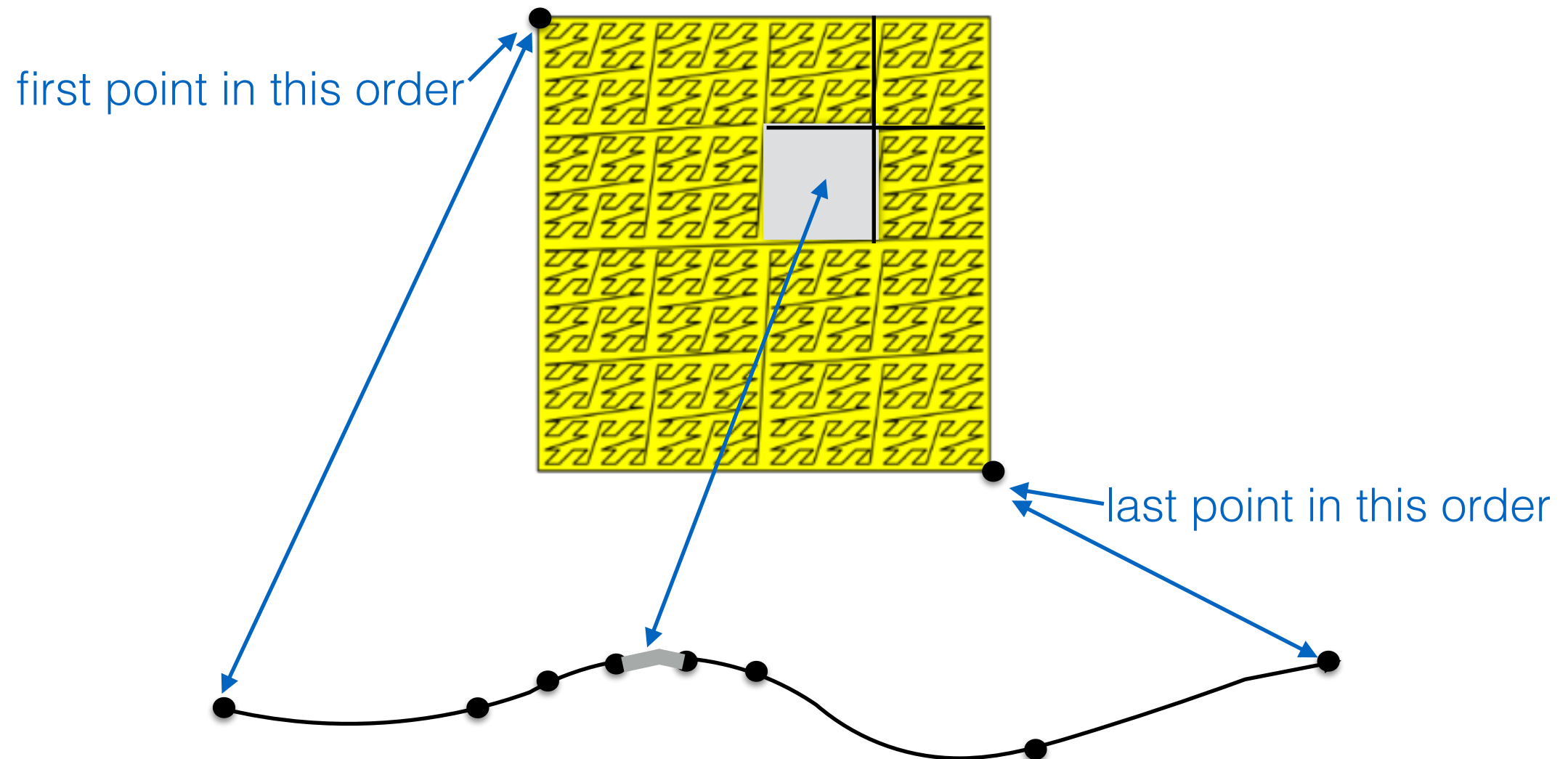


- and so on.....

Z-order and quadtrees

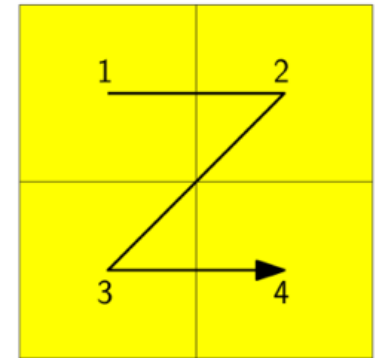


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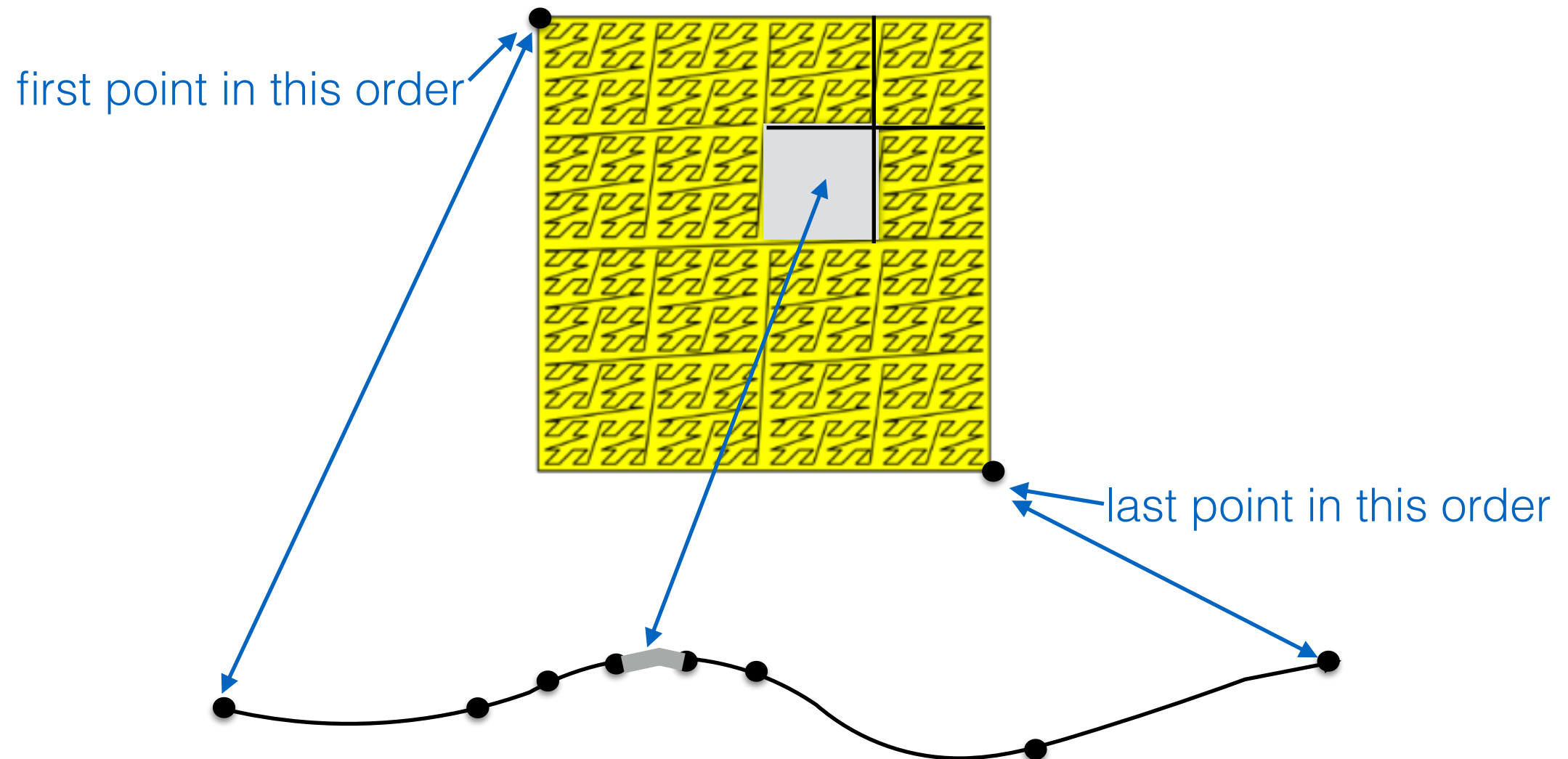


- Every canonical square corresponds to an interval of the z-order curve

Z-order and quadtrees

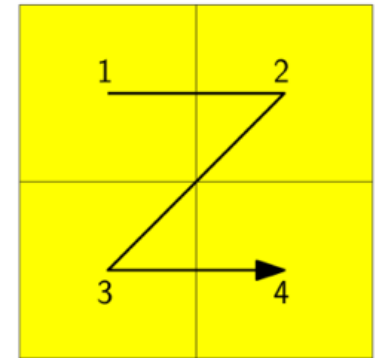


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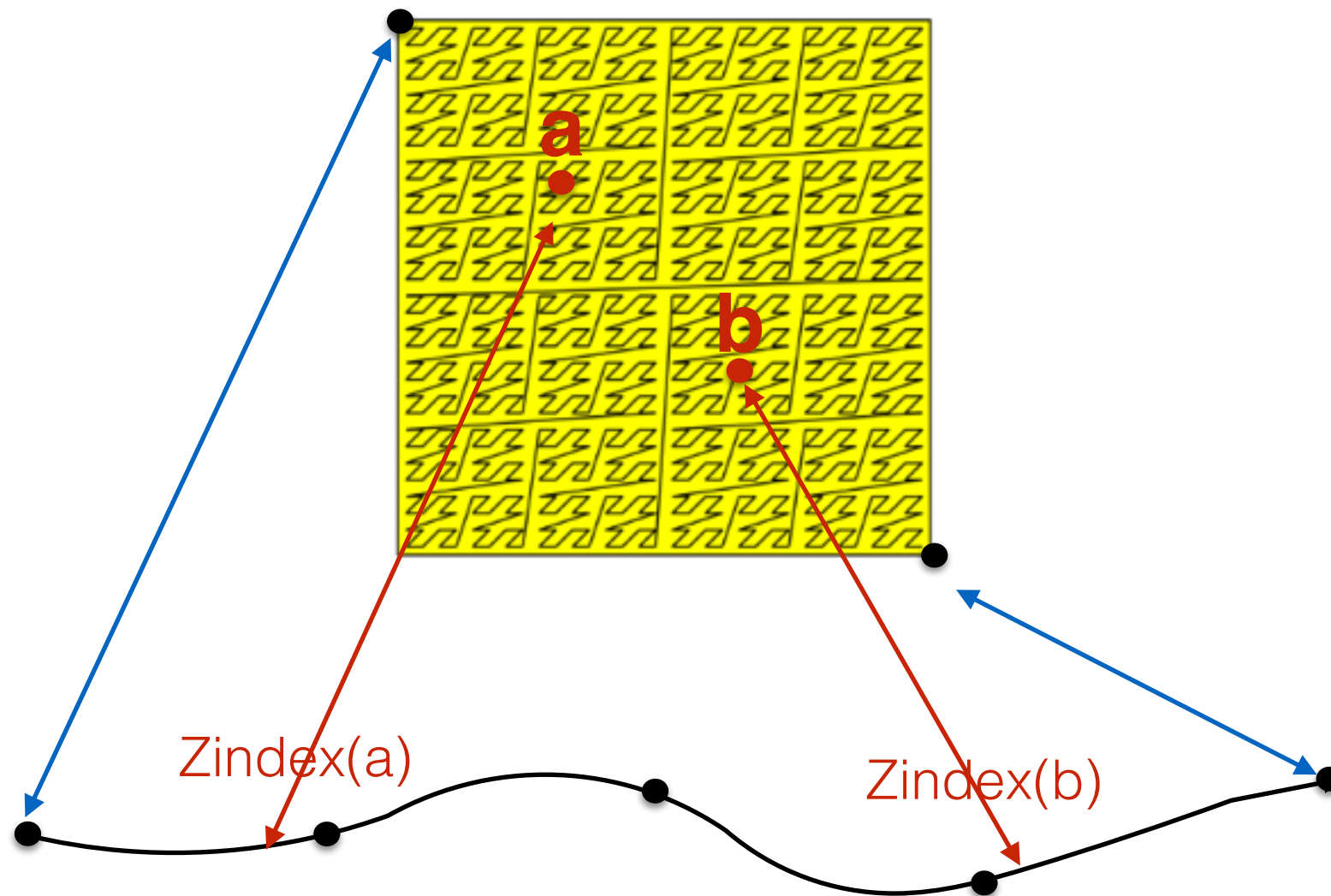


- Two canonical squares are non-intersecting, or one included in the other

Z-order and quadtrees



visit quadrants recursively in this order: NW, NE, SW, SE



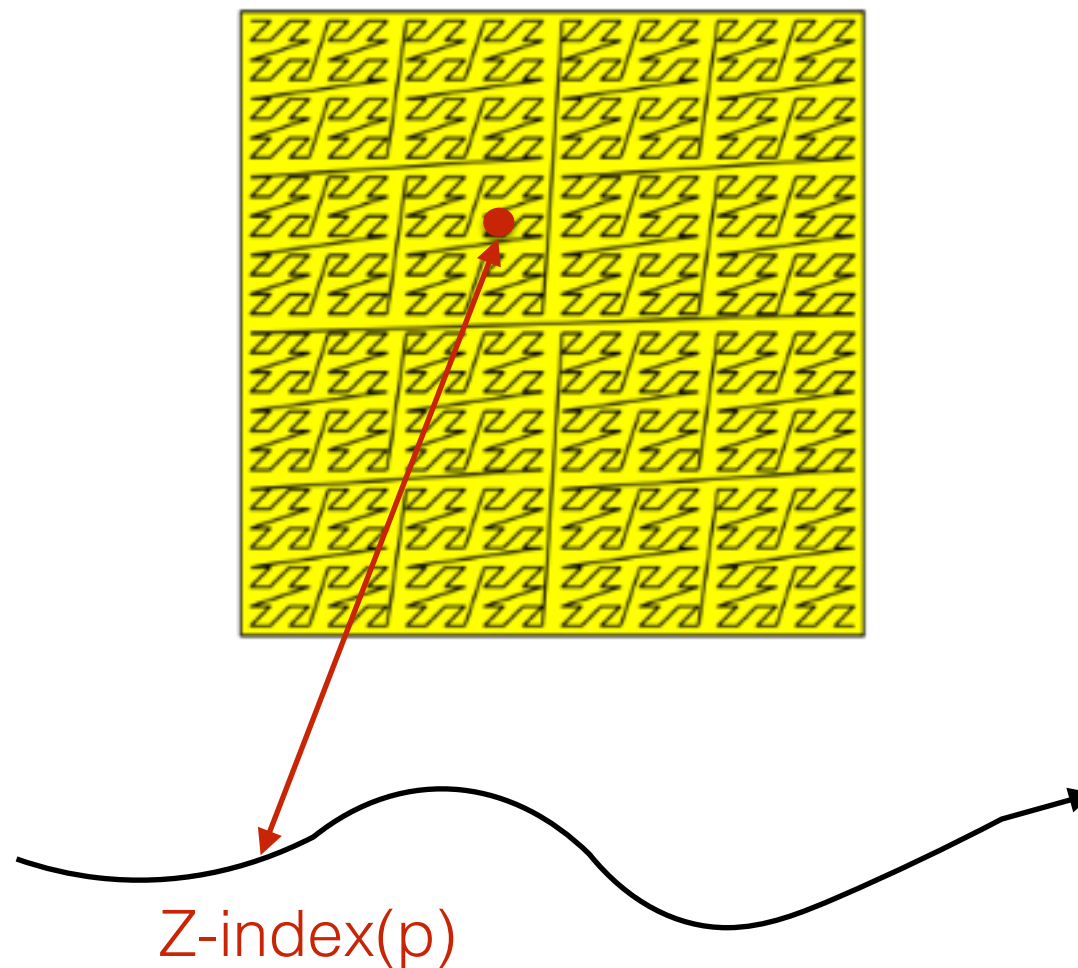
- If $Zindex(a) < Zindex(b)$, we say that $a < b$
- Any two points a, b can be compared

Computing the Z-index

$$Z_index : \mathbb{R}^2 \longrightarrow \mathbb{R}$$

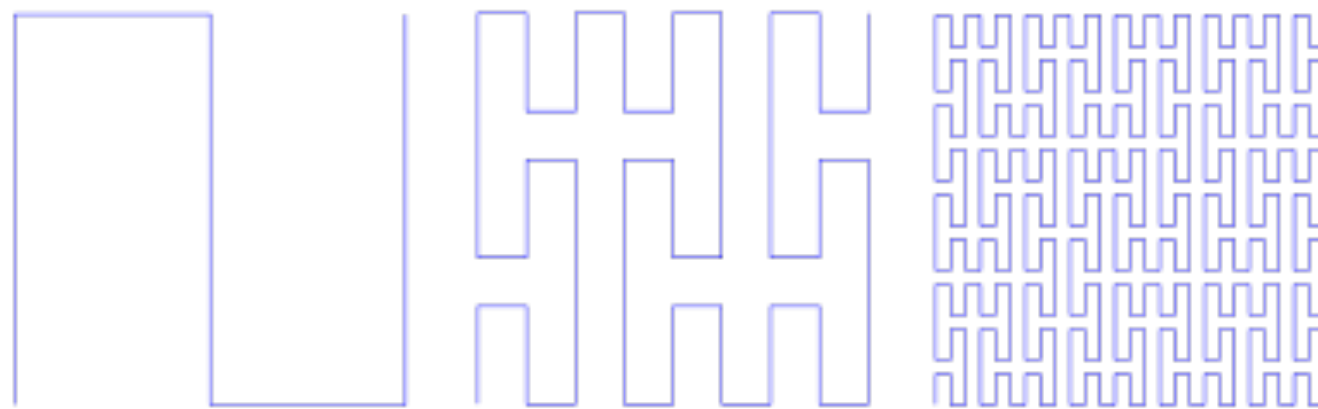
For simplicity assume points with integer coordinates on k bits

- What is the largest integer representable on k bits?



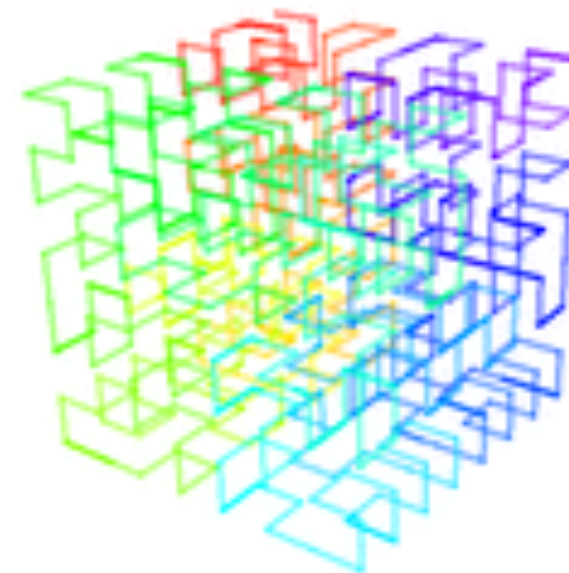
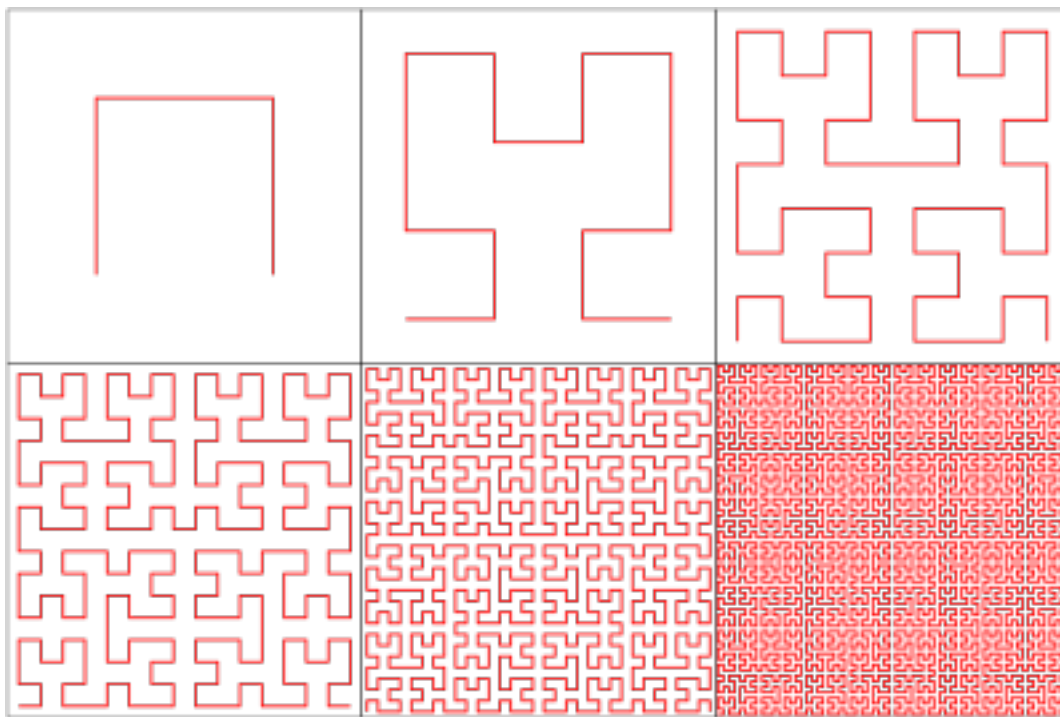
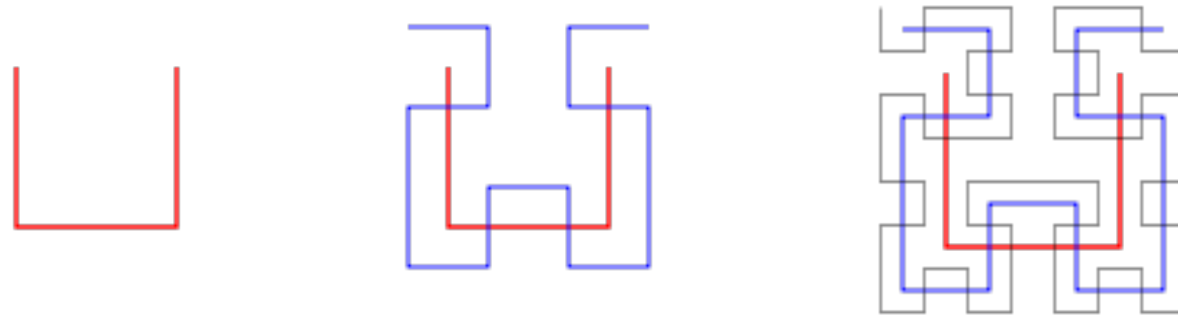
Space-filling curves

- Z-order curves are a special type of space-filling curves
- First SFC were described by Peano and Hilbert



Peano curve

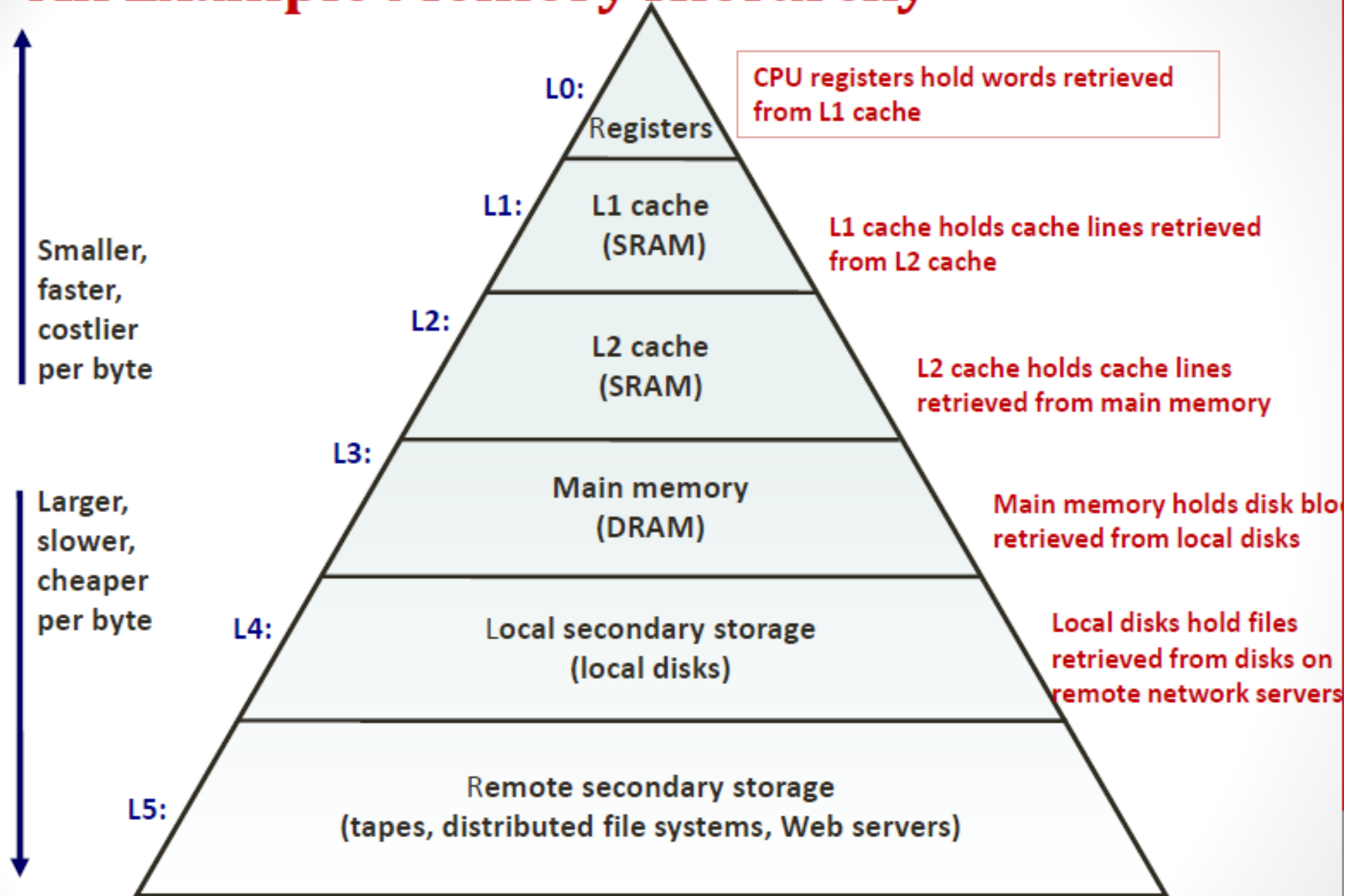
Hilbert curve



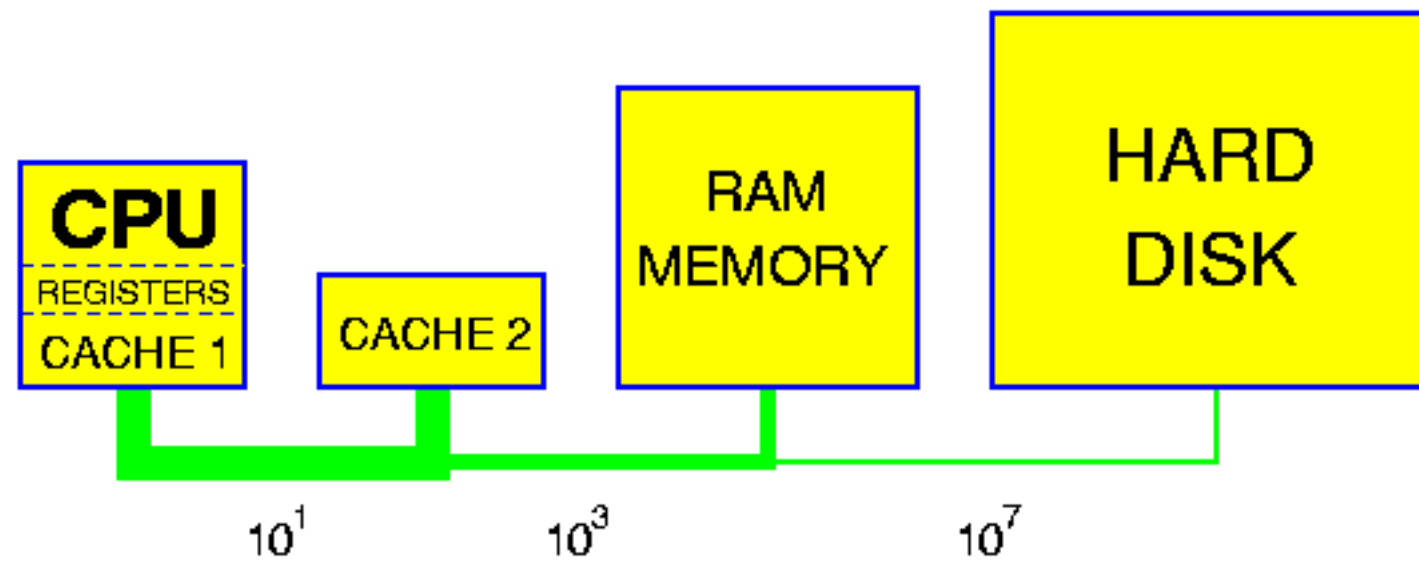
Spatial locality

- Big-Oh analysis does not have the final word
- Two algorithms that have the same big-Oh can differ a lot in performance depending on their cache efficiency
- To analyze and fine tune the algorithm we need to look at the performance across all levels of the memory hierarchy

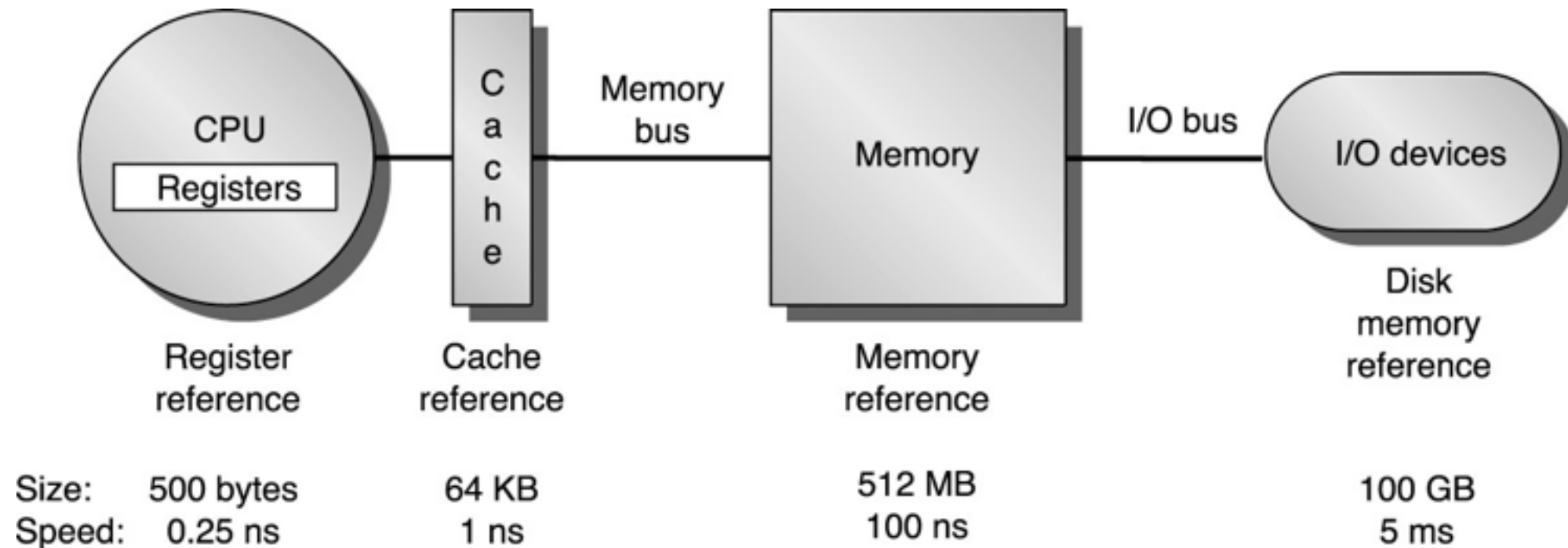
An Example Memory Hierarchy



MEMORY HIERARCHY



Indicated are approximate numbers of clock cycles to access the various elements of the memory hierarchy

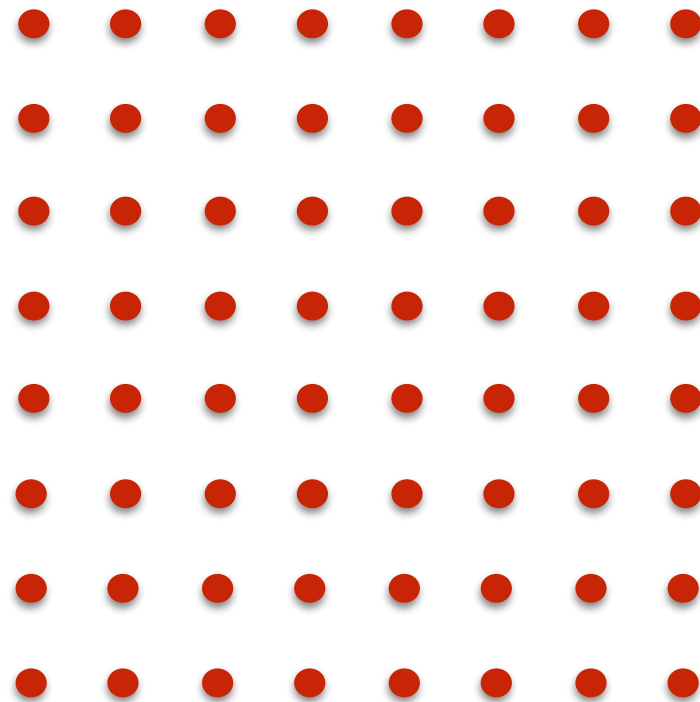


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- At all levels, data is organized and moved in blocks/pages
- Each level acts as a “cache” for the next level: stores most recently used blocks
- Applications that access data that’s stored in a “recent” block will find it in cache
 - 1ns vs 100ns <— SIGNIFICANT!

Spatial locality

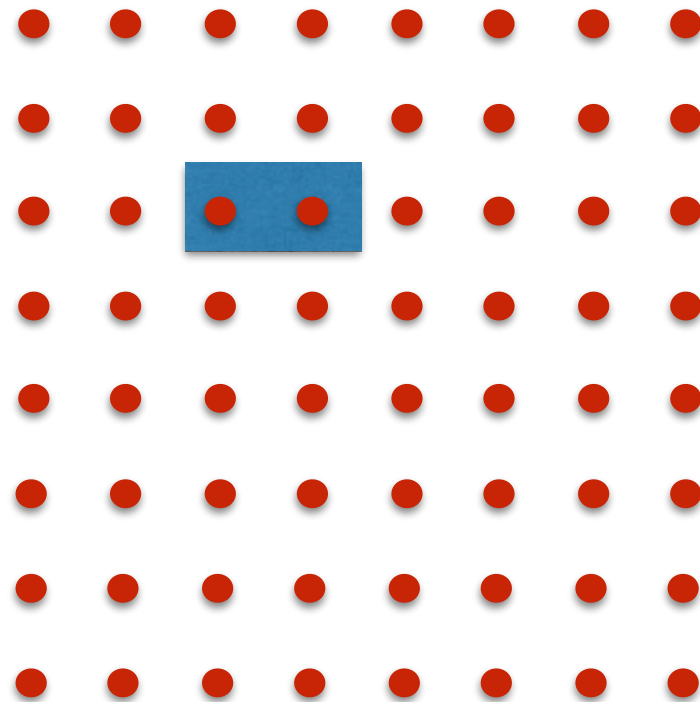
Spatial applications usually have spatial locality in their access to data, i.e. they are likely to access together points that are close to each other in space



We would like points “close” in 2D to be stored “close” to each other in the data structure

Spatial locality

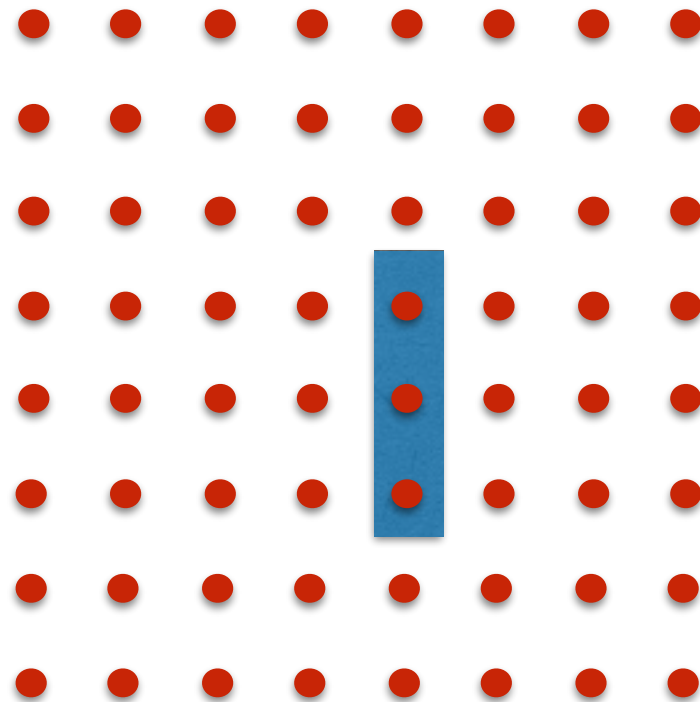
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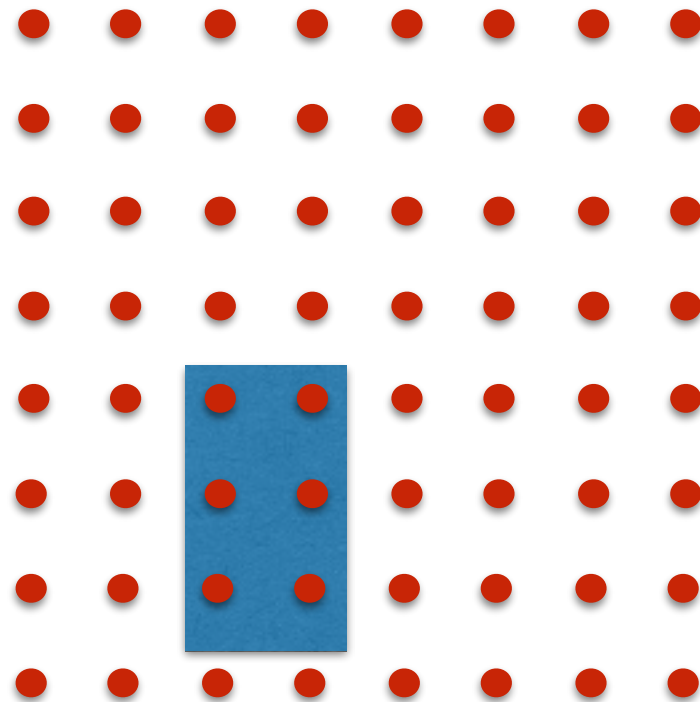
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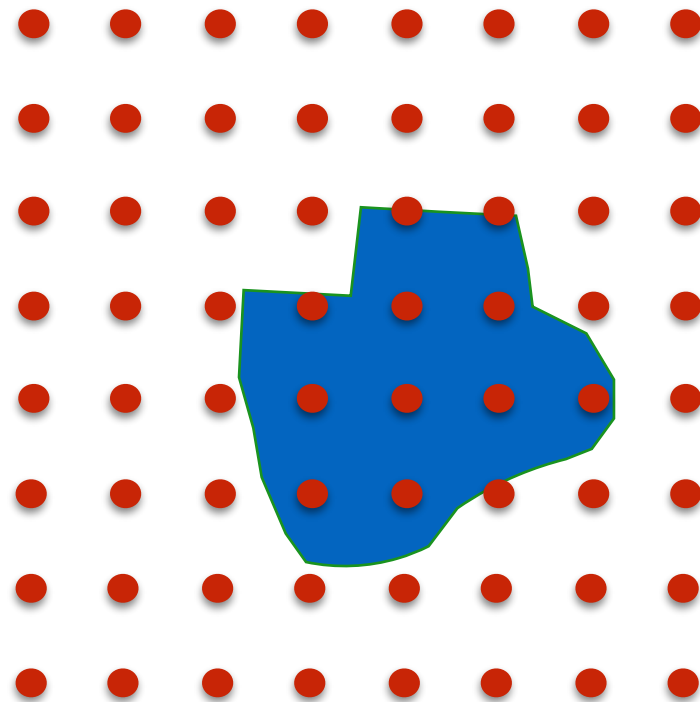
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We would like points “close” in 2D to be stored “close” to each other in the data structure

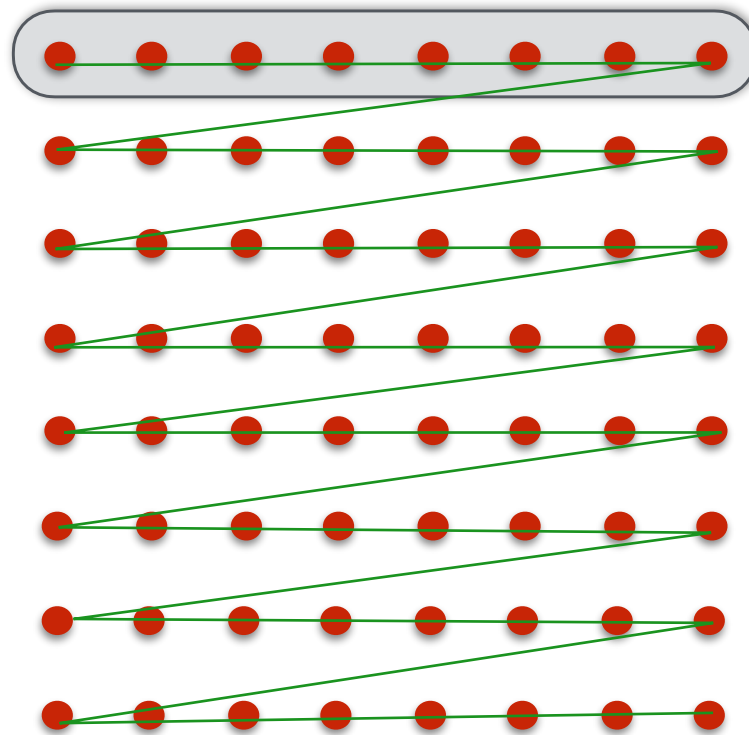
Spatial locality

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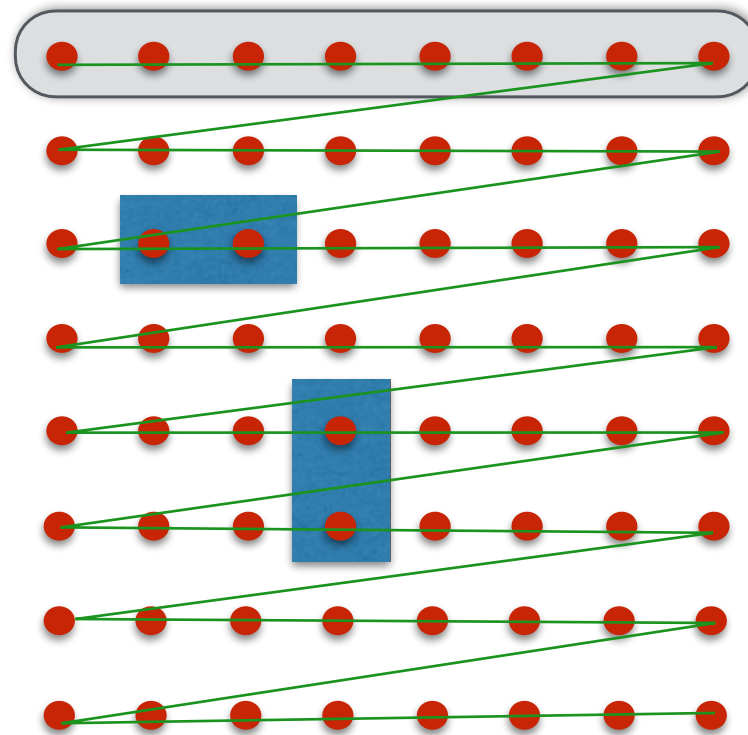


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Grid default layout: row-major order

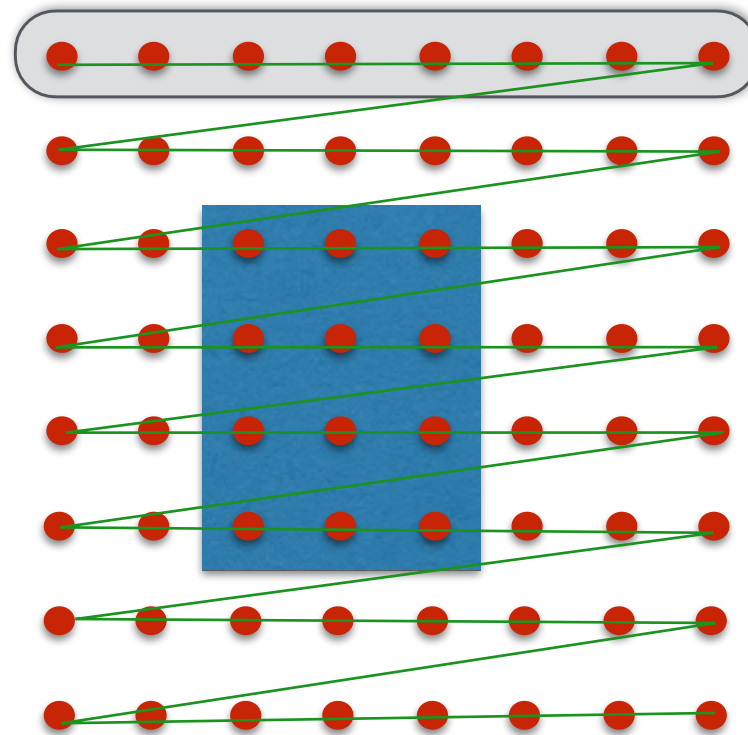


Grid default layout: row-major order



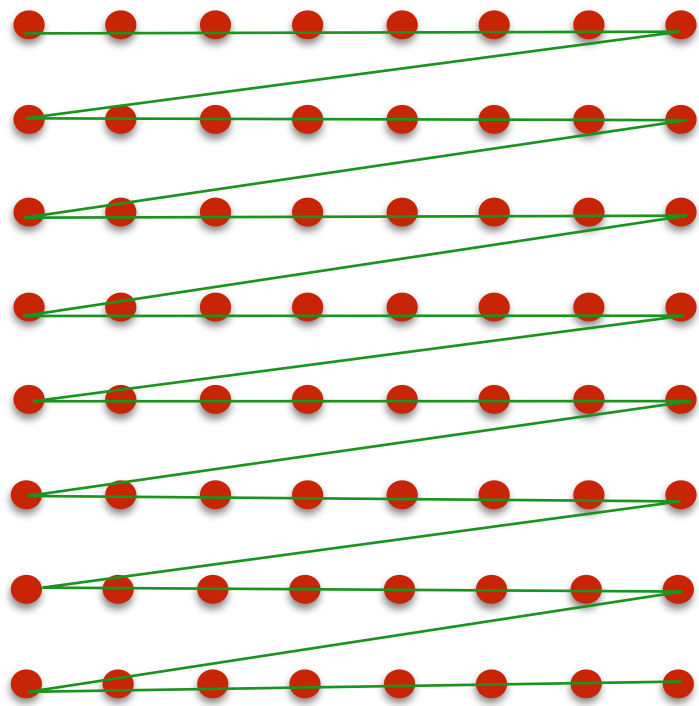
- Does this layout have good spatial locality?
- How far are these points in the array?

Grid default layout: row-major order

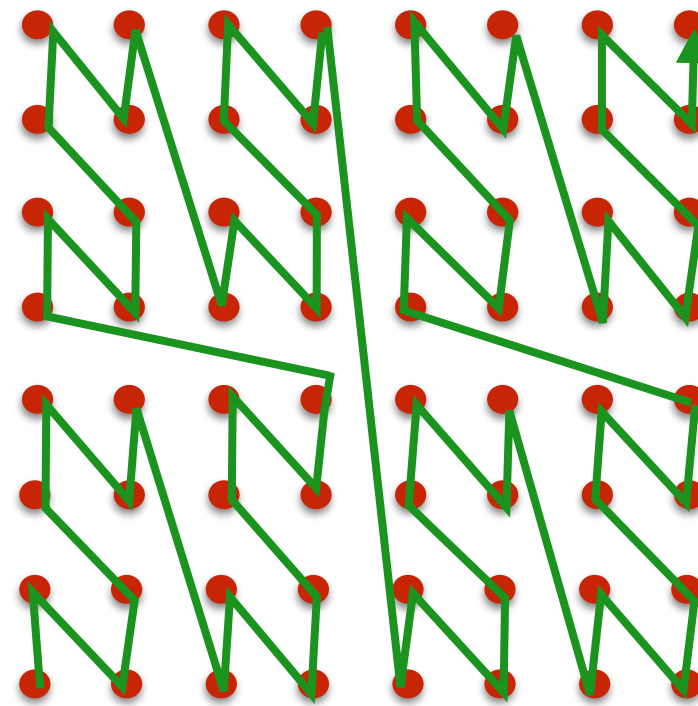


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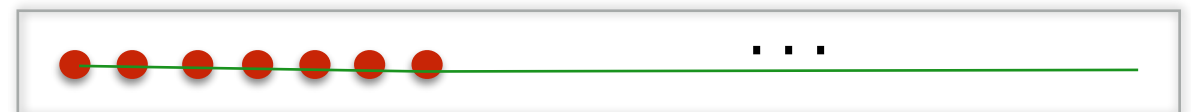
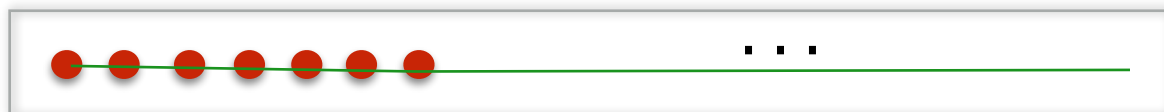
Spatial locality



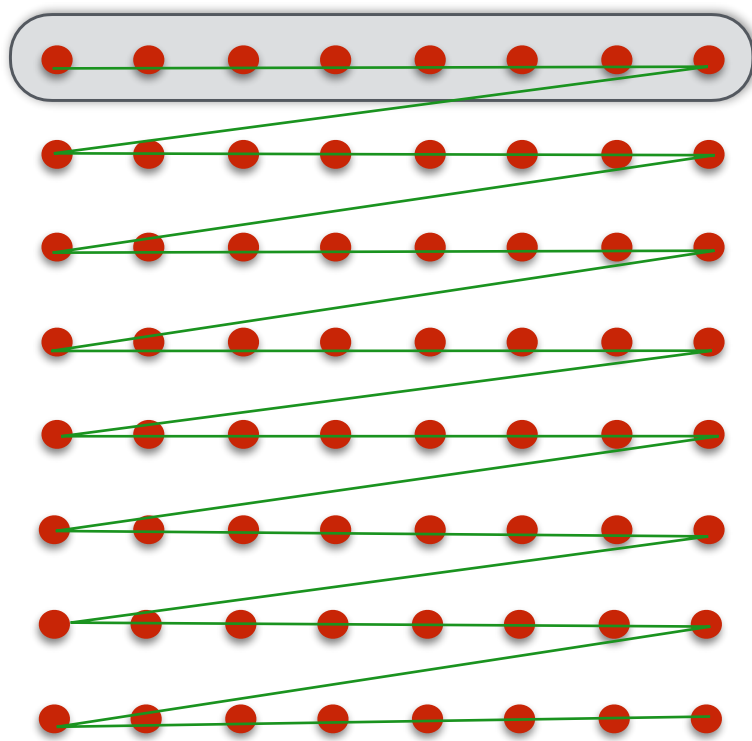
grid in default row-major order



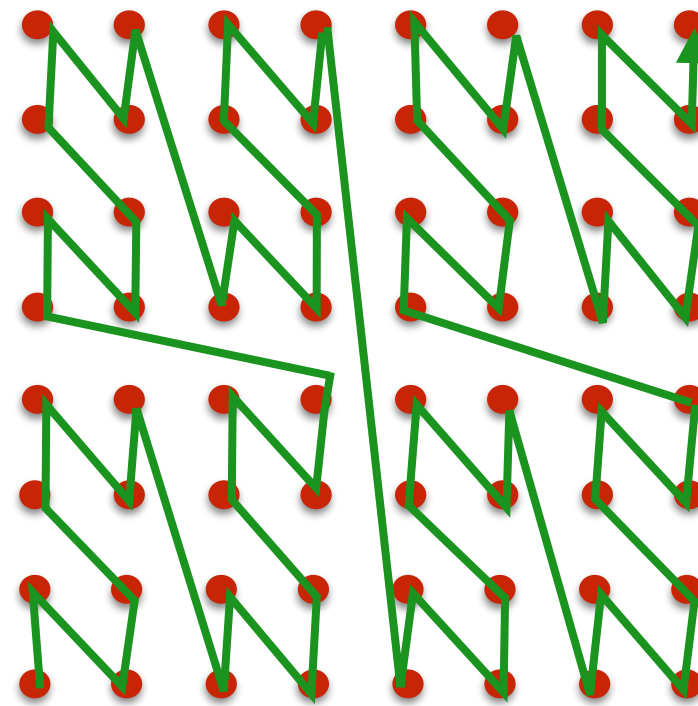
grid stored in Z-order



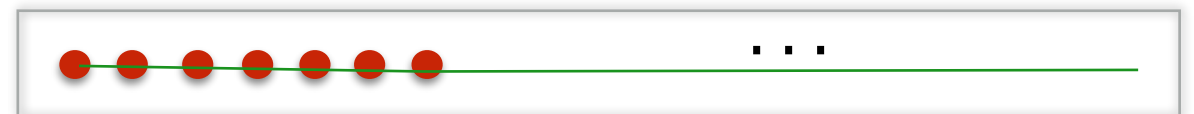
Spatial locality



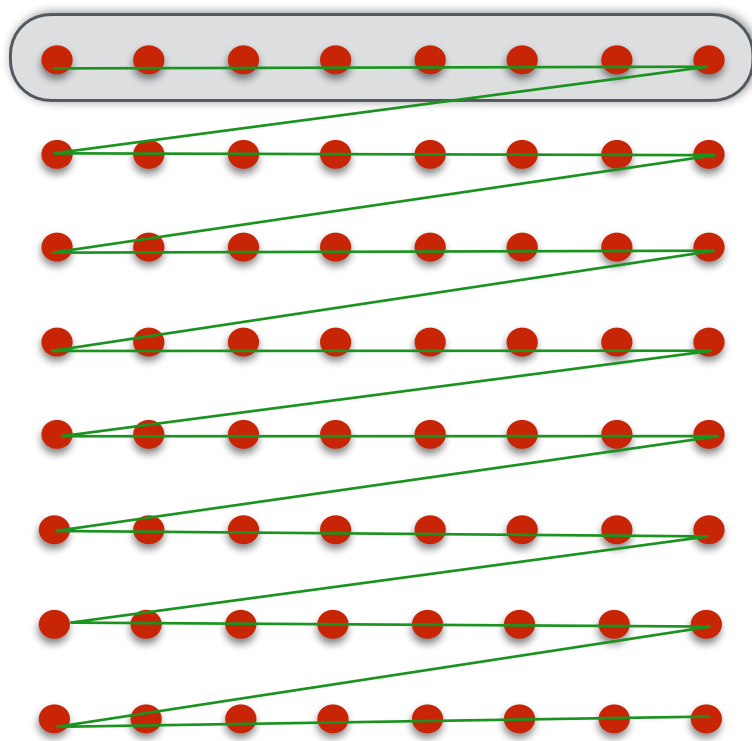
grid in default row-major order



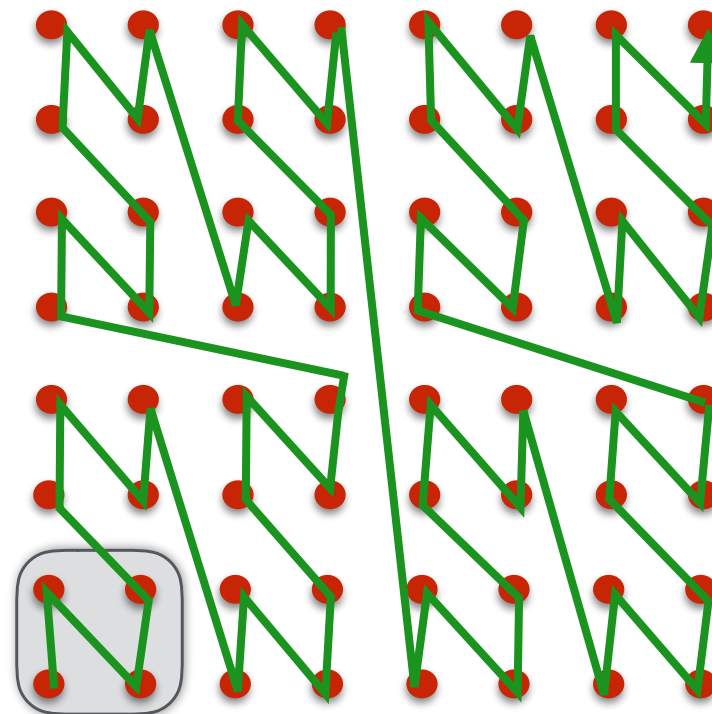
grid stored in Z-order



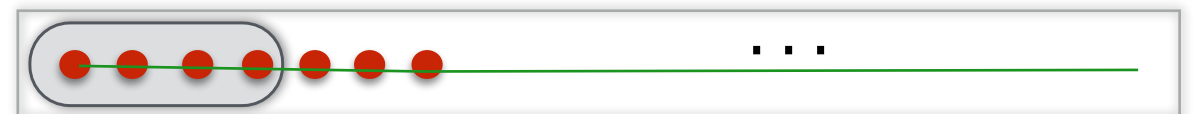
Spatial locality



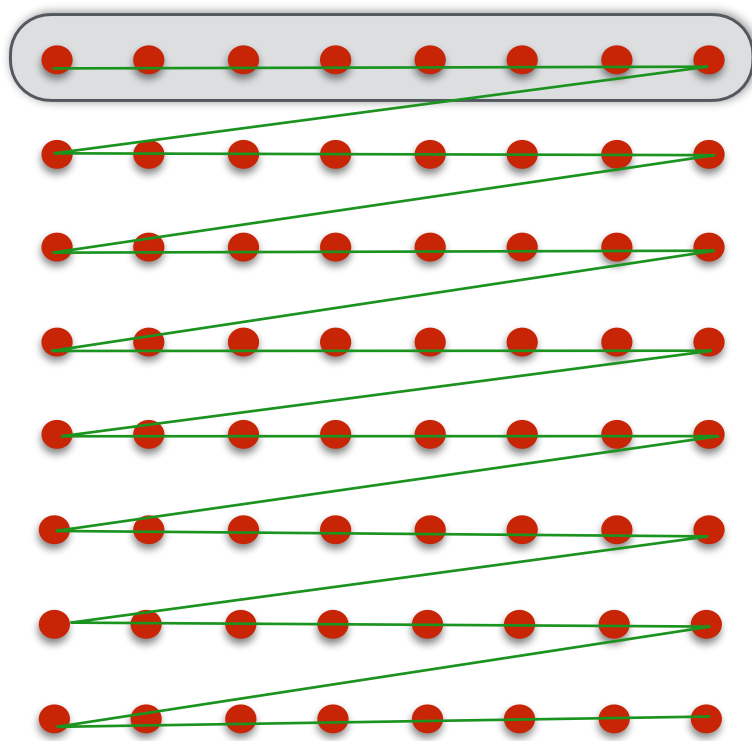
grid in default row-major order



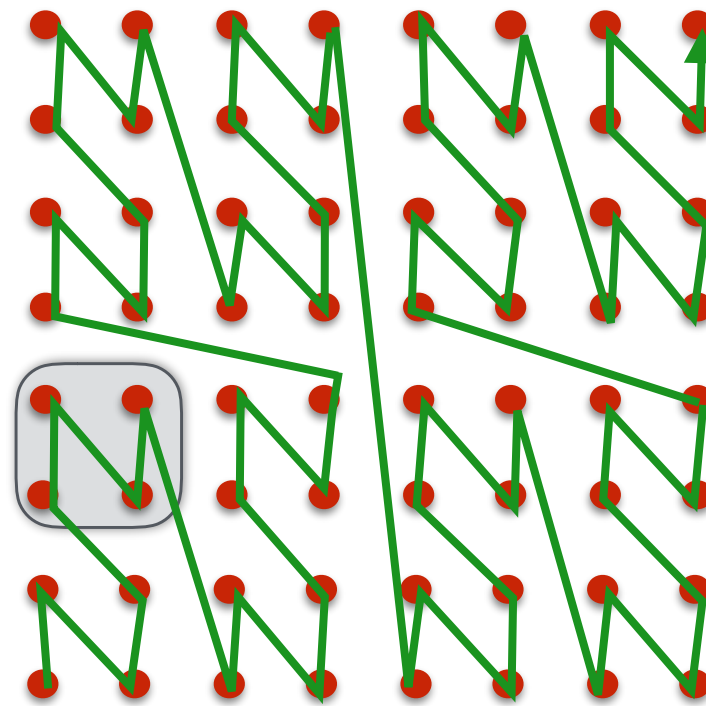
grid stored in Z-order



Spatial locality



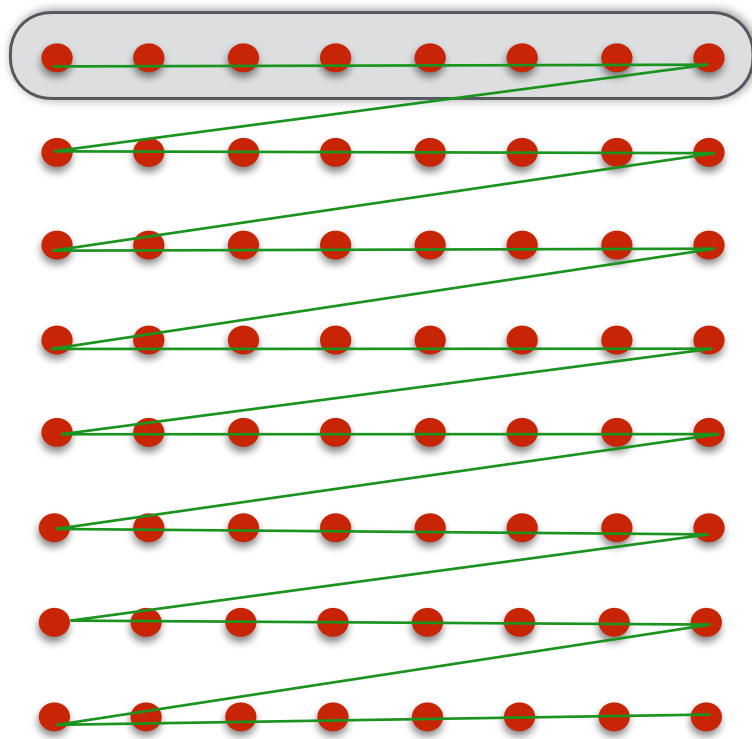
grid in default row-major order



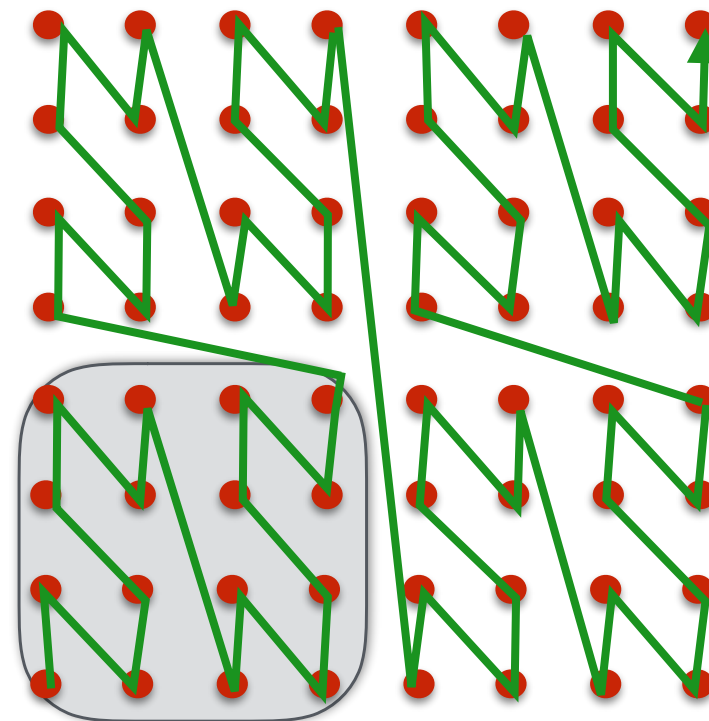
grid stored in Z-order



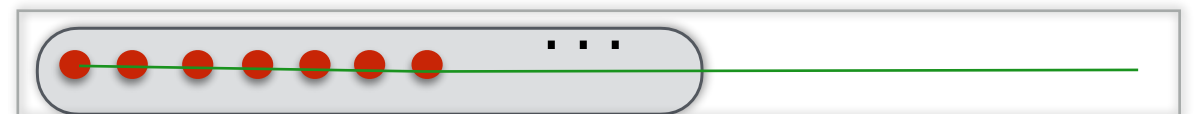
Spatial locality



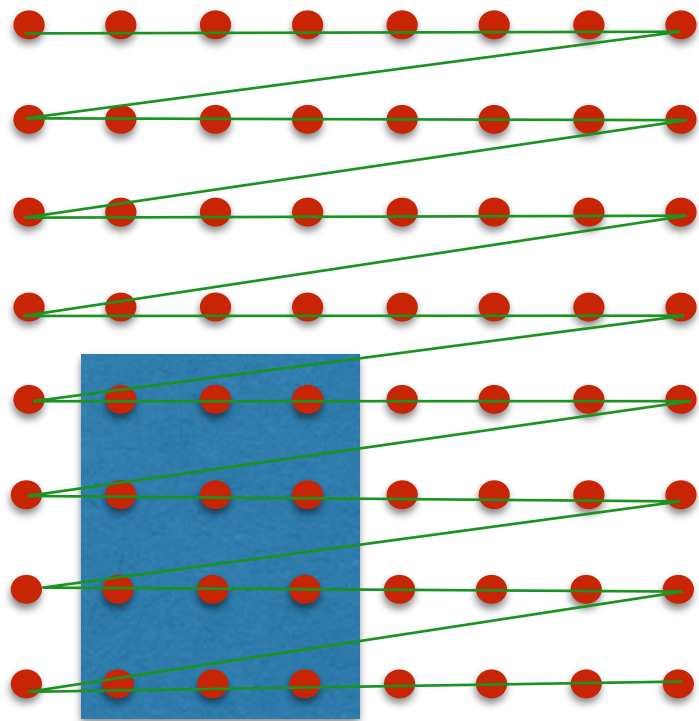
grid in default row-major order



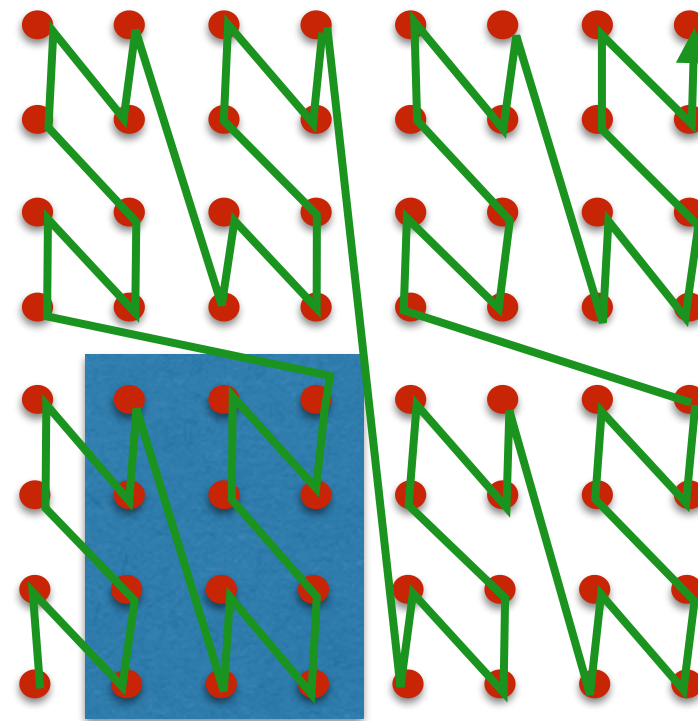
grid stored in Z-order



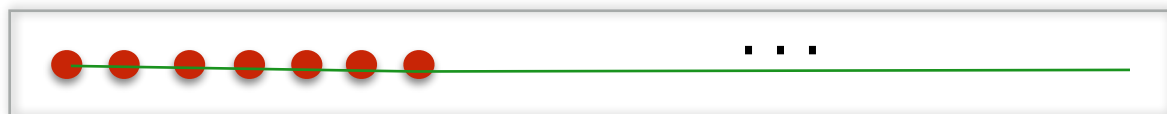
Spatial locality



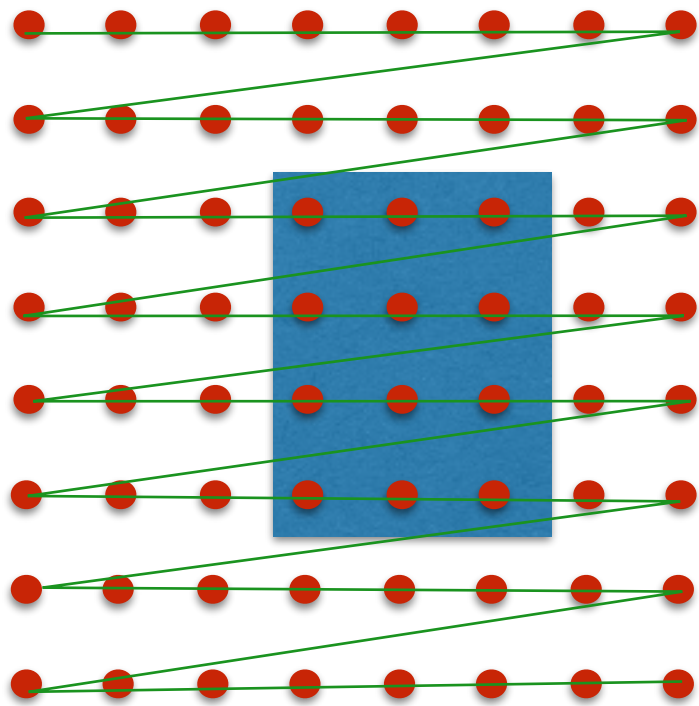
grid in default row-major order



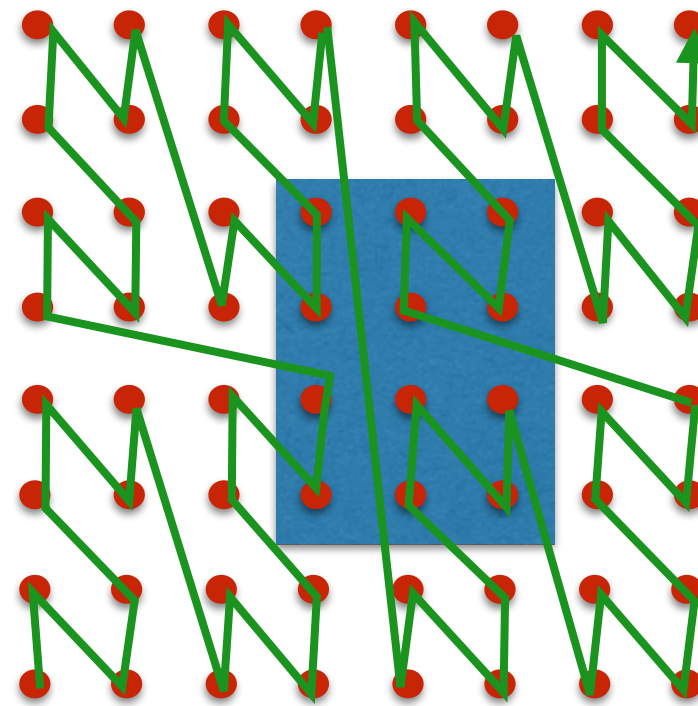
grid stored in Z-order



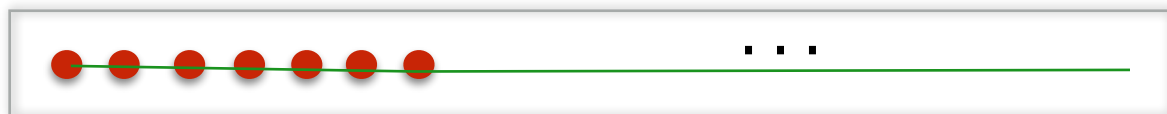
Spatial locality



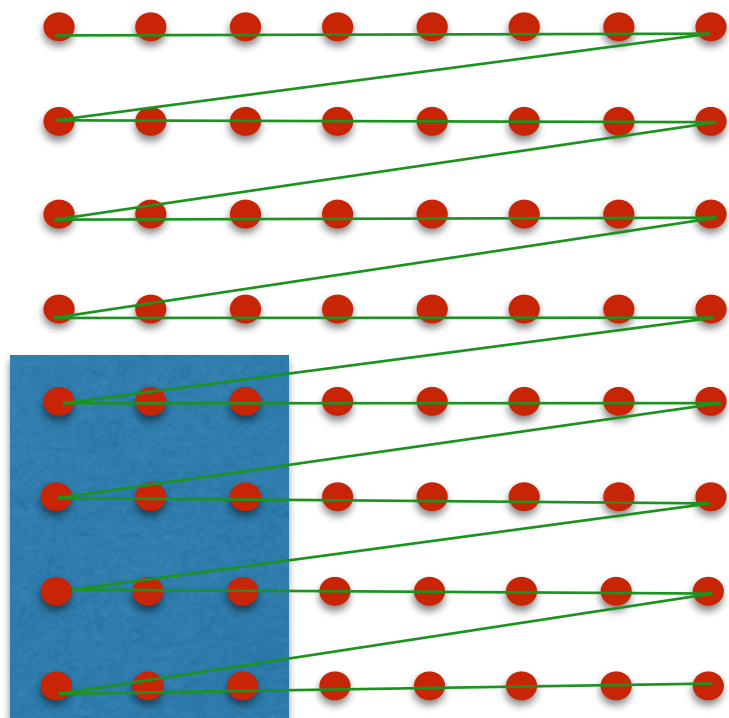
grid in default row-major order



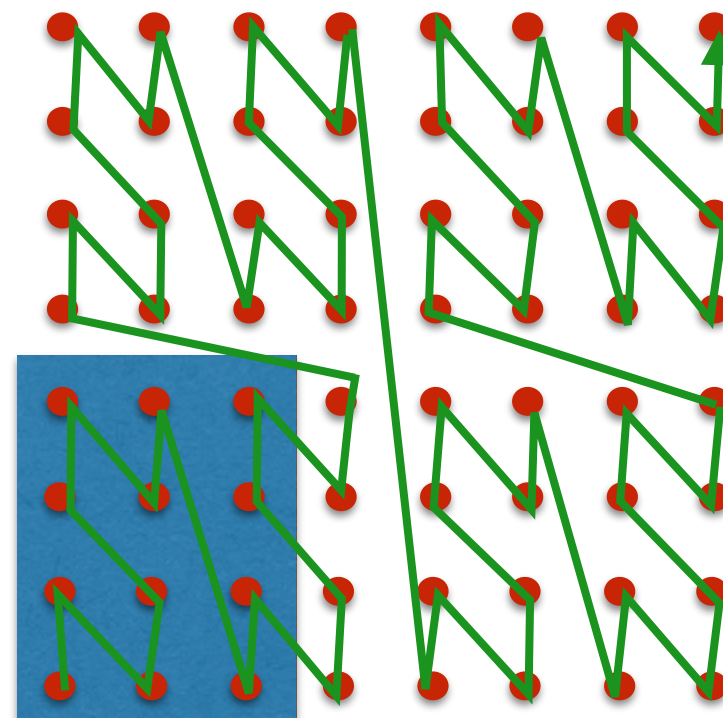
grid stored in Z-order



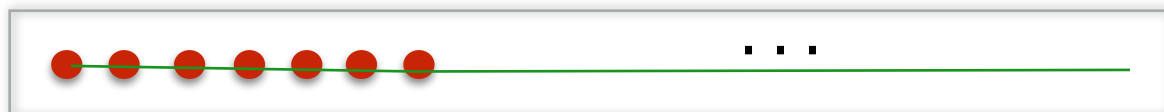
Spatial locality



grid in default row-major order



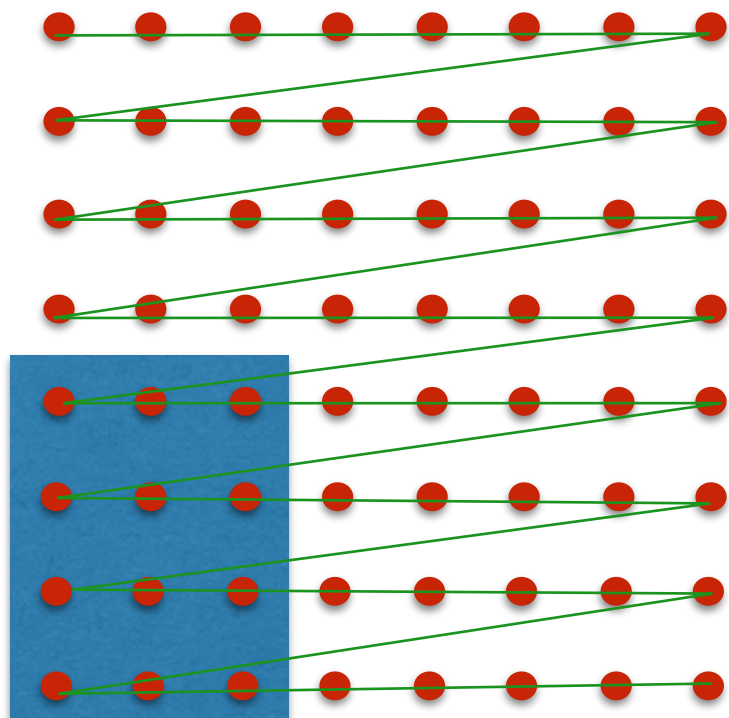
grid stored in Z-order



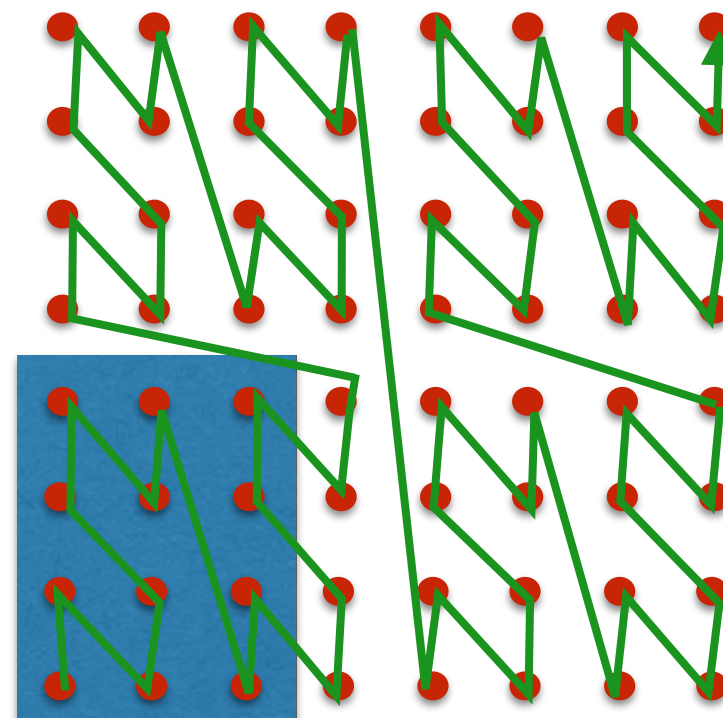
Spatial locality

Arranging data in order of a space-filling curve improves spatial locality

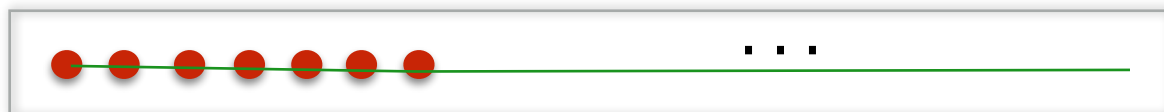
- points that are close together in space, will be stored close to each other



grid in default row-major order

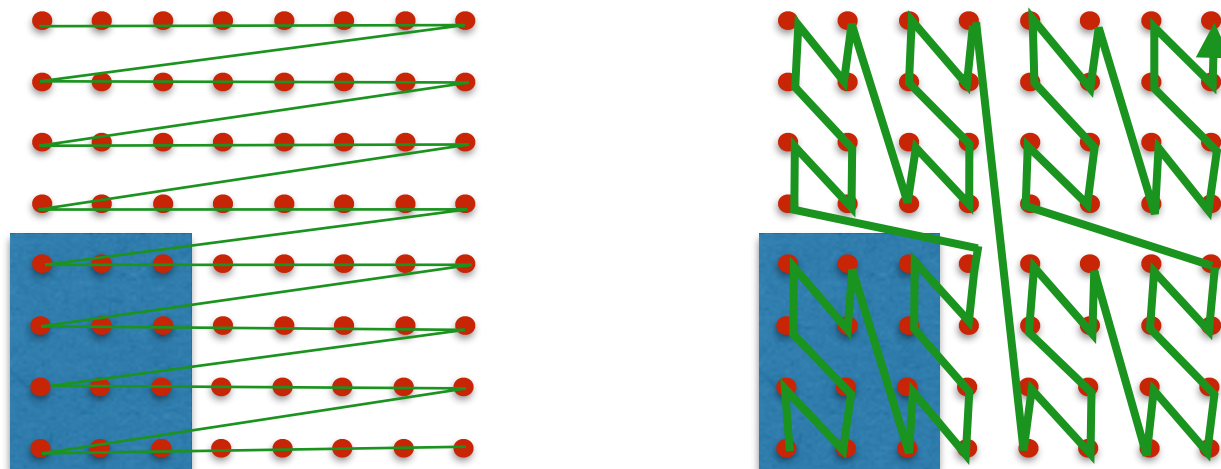


grid stored in Z-order



Spatial locality

- Arranging data in order of a space-filling curve improves spatial locality
 - points that are close together in space, will be stored close to each other
 - data will be in the same blocks as previous data
 - data will be found in cache
 - improvements at all levels of the memory hierarchy



- Hilbert curve has better locality than z-order, but slower to compute
- Z-order used with Strassen's algorithm —> speedups (2002)

SFC in art

Don Relyea, artist futurist and tehnologist

- <http://www.donrelyea.com/site2015/space-filling-curve-art-2004-2014-wide-format/>

