

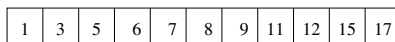
Binary Search Trees: Data Structures for Ordered Sets

(CLRS 12.1-12.3)

- At a high level, we have a set of elements S and we want to represent S with a data structure such that the following operations are supported efficiently:

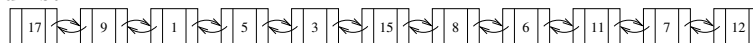
- SEARCH(e): Return (pointer to) element e in S (if $e \in S$)
- INSERT(e): Insert element e in S
- DELETE(e): Delete element e from S
- SUCCESSOR(e): Return (pointer to) minimal element in S larger than e
- PREDECESSOR(e): Return (pointer to) maximal element in S smaller than e

- The first implementation that comes to mind is the ordered array:



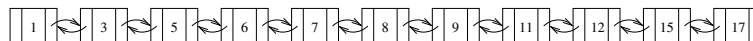
- SEARCH can be performed in $O(n)$ time by scanning through array or in $O(\log n)$ time using binary search
- PREDECESSOR/SUCCESSOR can be performed in $O(\log n)$ time like searching
- INSERT/DELETE takes $O(n)$ time since we need to expand/compress the array after finding the position of e

- Perhaps an unordered list?



- SEARCH takes $O(n)$ time since we have to scan the list
- PREDECESSOR/SUCCESSOR takes $O(n)$ time
- INSERT takes $O(1)$ time since we can just insert e at beginning of list
- DELETE takes $O(n)$ time since we have to perform a search before spending $O(1)$ time on deletion

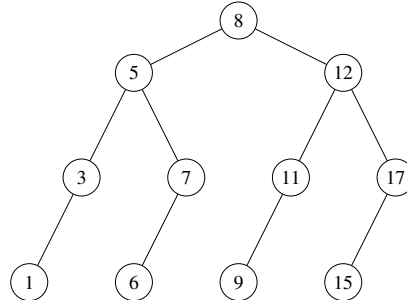
- How about ... an ordered list ?



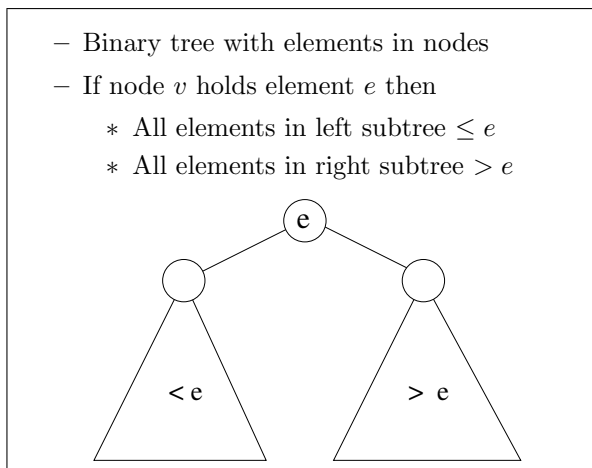
- SEARCH takes $O(n)$ time since we cannot perform binary search
- PREDECESSOR/SUCCESSOR takes $O(n)$ time
- INSERT/DELETE takes $O(n)$ time since we have to perform a search to locate the position of insertion/deletion

Binary search tree implementation

- We want to combine the advantages of sorted arrays (fast search) with the advantages of lists (fast insert and delete)
- Binary search naturally leads to definition of binary search tree

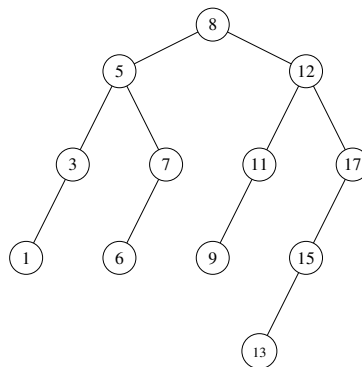


- Formal definition of search tree:



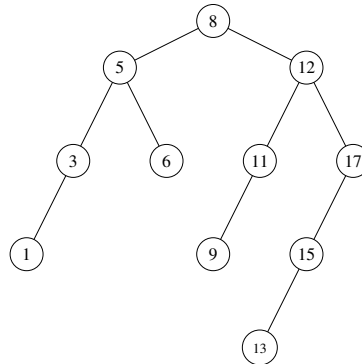
- $Search(e)$ in $O(height)$: Compare with e and recursively search in left or right subtree
- $Insert(e)$ in $O(height)$: Search for e and insert at place where search path terminates (Note: height may increase)

Example: Insertion of 13



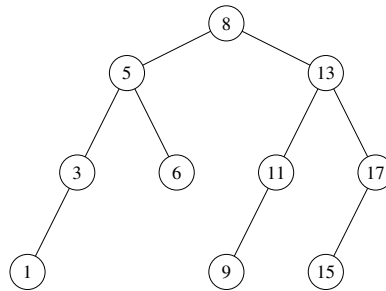
- $Delete(e)$ in $O(height)$: Search for node v containing e ,
 1. v is a leaf: Delete v
 2. v is internal node with one child: Delete v and attach $child(v)$ to $parent(v)$

Example: Delete 7



3. v is internal node with two children:
 - exchange e in v with successor e' in node v' (minimal element in right subtree, found by following left branches as long as possible in right subtree)
 - v' node can be deleted by case 1 or 2

Example: Delete 12



- Class work: How do you find the successor/predecessor of a given node?
- Class work: Assume you have a BST of n elements. How long does it take to sort them?
- Note:
 - Running time of all operations depend on height of tree.
 - Intuitively the tree will be nicely balanced if we do insertion and deletion randomly.
 - In worst case the height can be $O(n)$.