csci 210: Data Structures

Graph Traversals

1

Depth-first search (DFS)

• G can be directed or undirected

DFS(v)

- mark v visited
- for all adjacent edges (v,w) of v do
 - if w is not visited
 - parent(w) = v
 - (v,w) is a discovery (tree) edge
 - DFS(w)
 - else (v,w) is a non-discovery (non-tree) edge

DFS

- Assume G is undirected (similar properties hold when G is directed).
- DFS(v) visits all vertices in the connected component of v
- The discovery edges form a tree: the DFS-tree of v
 - justification: never visit a vertex again==> no cycles
 - we can keep track of the DFS tree by storing, for each vertex w, its parent
- The non-discovery (non-tree) edges always lead to a parent
- If G is given as an adjacency-list of edges, then DFS(v) takes O(|V|+|E|) time.

DFS

- Putting it all together:
- Proposition: Let G=(V,E) be an undirected graph represented by its adjacency-list. A DFS traversal of G can be performed in O(|V|+|E|) time and can be used to solve the following problems:
 - testing whether G is connected
 - computing the connected components (CC) of G
 - computing a spanning tree of the CC of v
 - computing a path between 2 vertices, if one exists
 - computing a cycle, or reporting that there are no cycles in G

Breadth-first search (BFS)

- BFS(v)
- Main idea:
 - start at v and visit first all vertices at distance =1
 - followed by all vertices at distance=2
 - followed by all vertices at distance=3
 - ...
- BFS corresponds to computing the shortest path (in terms of number of edges) from v to all other vertices
 - we'll justify this later
- To perform BFS we think about coloring each vertex
 - WHITE before we start
 - GRAY after we visit a vertex but before we visited all its adjacent vertices
 - BLACK after we visit a vertex and all its adjacent vertices
- We use a queue to store all GRAY vertices---these are the vertices we have seen but we are not done with
- We remember from which vertex a given vertex w is colored GRAY ---- this is the vertex tat discovered w, or the parent of w

BFS

BFSinitialize:

- for each v in V
 - color(v) = WHITE
 - d[v] = infinity
 - parent(v) = NULL
- BFS(v)
 - color(v) = GRAY
 - d[v] = 0
 - create an empty queue Q
 - Q.enqueue(v)
 - while Q not empty
 - Q.dequeue(u)
 - for all adjacent edges (u,w) of e in E do
 - if color(w) = WHITE
 - >> color(w) = GRAY
 - aggregading d[w] = d[u] + 1
 - » parent(w) = u
 - » Q.enqueue(w)
 - color(u) = BLACK

BFS

- We can classify edges as
 - discovery (tree) edges: edges used to discover new vertices
 - non-discovery (non-tree) edges: lead to already visited vertices
- The distance d(u) corresponds to its "level"
- For each vertex u, d(u) represents the shortest path from v to u
 - justification: by contradiction. If d[u]=k, assume there exists a shorter path from v to u....
- Assume G is undirected (similar properties hold when G is directed).
 - connected components are defined undirected graphs (note: on directed graphs: strong connectivity)
- As for DFS, the discovery edges form a tree, the BFS-tree
- BFS(v) visits all vertices in the connected component of v
- If (u,w) is a non-tree edges, then d(u) and d(w) differ by at most 1.
- If G is given by its adjacency-list, BFS(v) takes O(|V|+|E|) time.

- Putting it all together:
- Proposition: Let G=(V,E) be an undirected graph represented by its adjacency-list. A BFS traversal of G can be performed in O(|V|+|E|) time and can be used to solve the following problems:
 - testing whether G is connected
 - computing the connected components (CC) of G
 - computing a spanning tree of the CC of v
 - computing a path between 2 vertices, if one exists
 - computing a cycle, or reporting that there are no cycles in G
 - computing the shortest paths from v to all vertices in the CC ov v

DFS

Graphs

- Reading: textbook chapter 13 --- only 13.1-13.3
 - 13.1: a good general introduction to graphs
 - 13.2 data structures for graphs
 - 13.3: BFS and DFS
- If you want to know more, take Algorithms or AI
 - offered every fall

Summary

Fundamental data structures

- vectors, lists, queues, stacks, trees, maps, priority queues
- Abstract data structures (ADT)
 - the general interface
 - Queue ADT, Stack ADT, Map ADT, Graph ADT, tree ADT

Implementations of standard ADT

- use arrays, lists, trees, hashing
- Trees
 - binary search trees
- Priority queues
 - heap
- Graphs
 - basic concepts
 - traversals
- Efficiency



- Tomorrow: final project demos
- Final exam: Wednesday May 13th 2-5pm
 - in-class exam
 - meet in the classroom (Seales 126)
 - written part + programming part
- Office hours:
 - tentative: pending scheduling honors presentations. If conflict, I will email new times
 - Monday May 11: 2-4pm
 - Tuesday May 11: 2-4pm